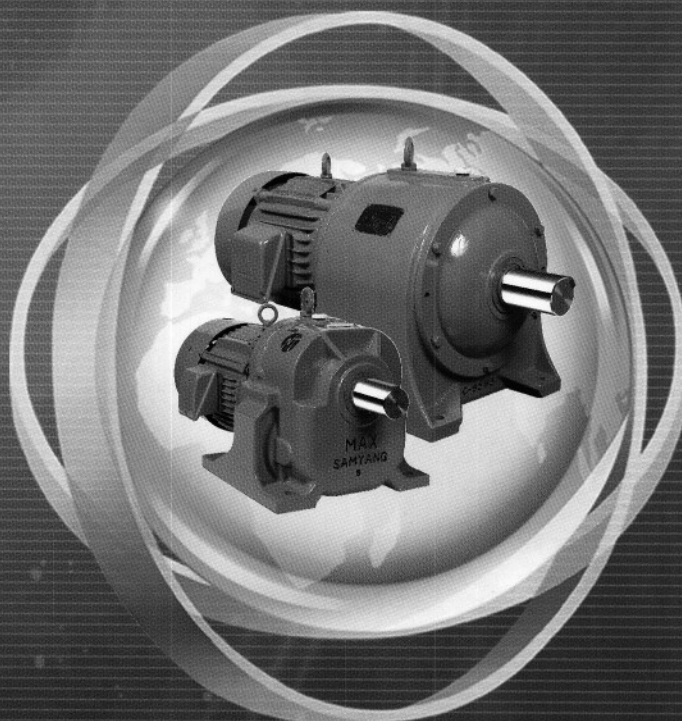
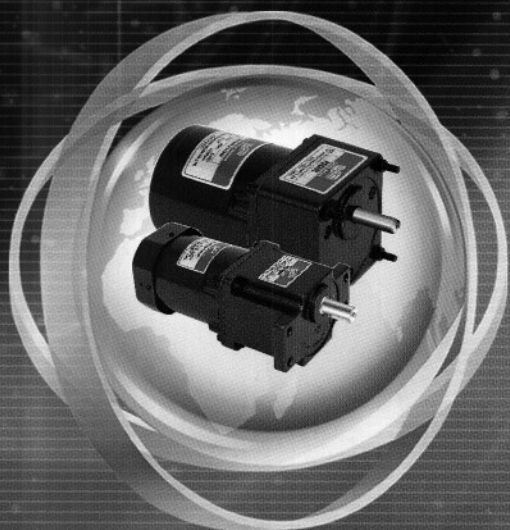


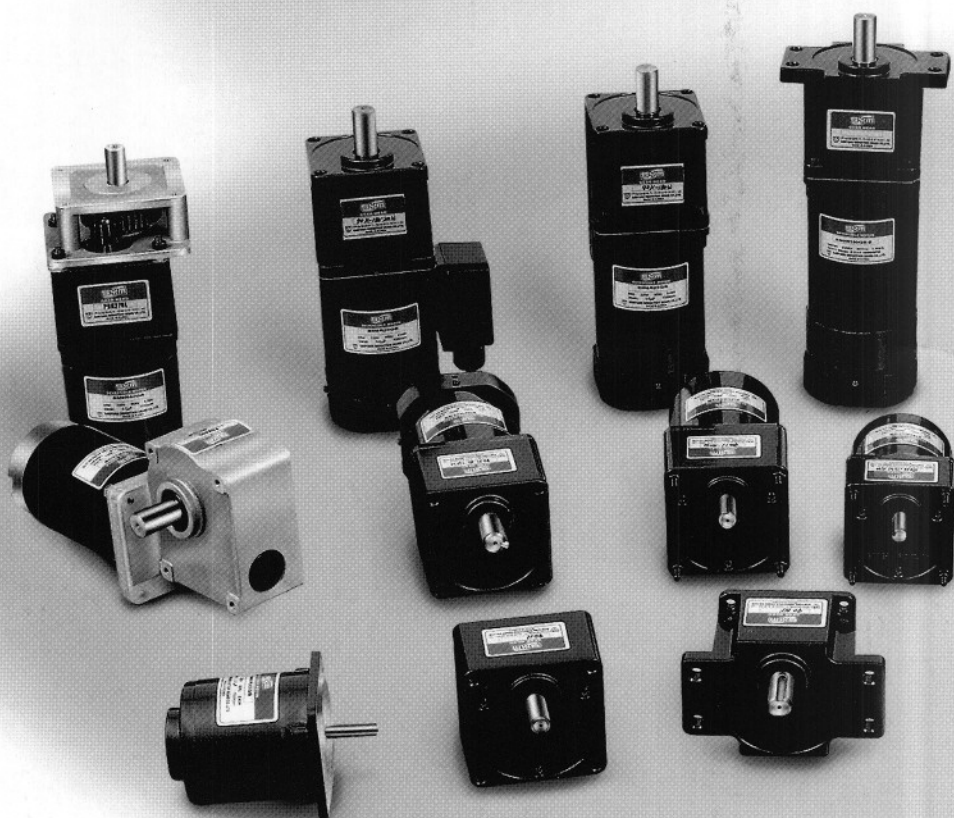
5 GEARED MOTORS

- SYM GEARED MOTOR (6~200W) 5- 1
 - INDUCTION MOTOR 5-10
 - REVERSIBLE MOTOR 5-38
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 - DC GEARED MOTOR 5-92
- MAX GEARED MOTOR (200W 이상) 5-108
 - HORIZONTAL
 - VERTICAL
 - LINE POWER
- SUPER MAX GEARED MOTOR 5-150
 - HORIZONTAL
 - VERTICAL
 - LINE POWER



삼양의 기술력이 만든 최고의 품질!
소형기어드 모터!

SYM

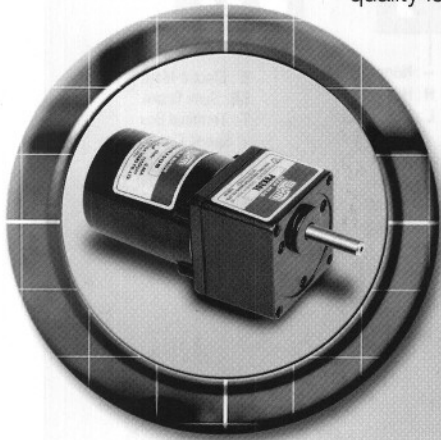


표류분품

Quality, Technique, Cost, Delivery are the competitive of
SAMYANG Reduction Gears.

You will meet SAMYANG SYM geared motor at every
where in the world in near future.

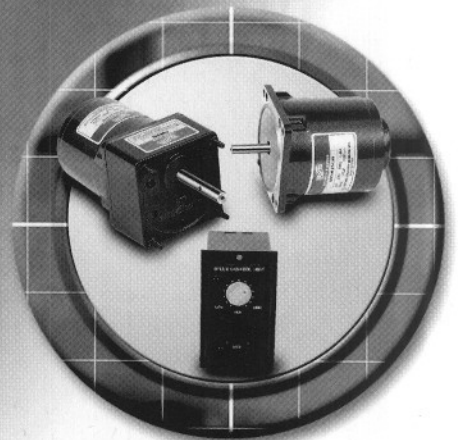
It is the time you can save cost and upgrade your
quality level of geared motored equipments.



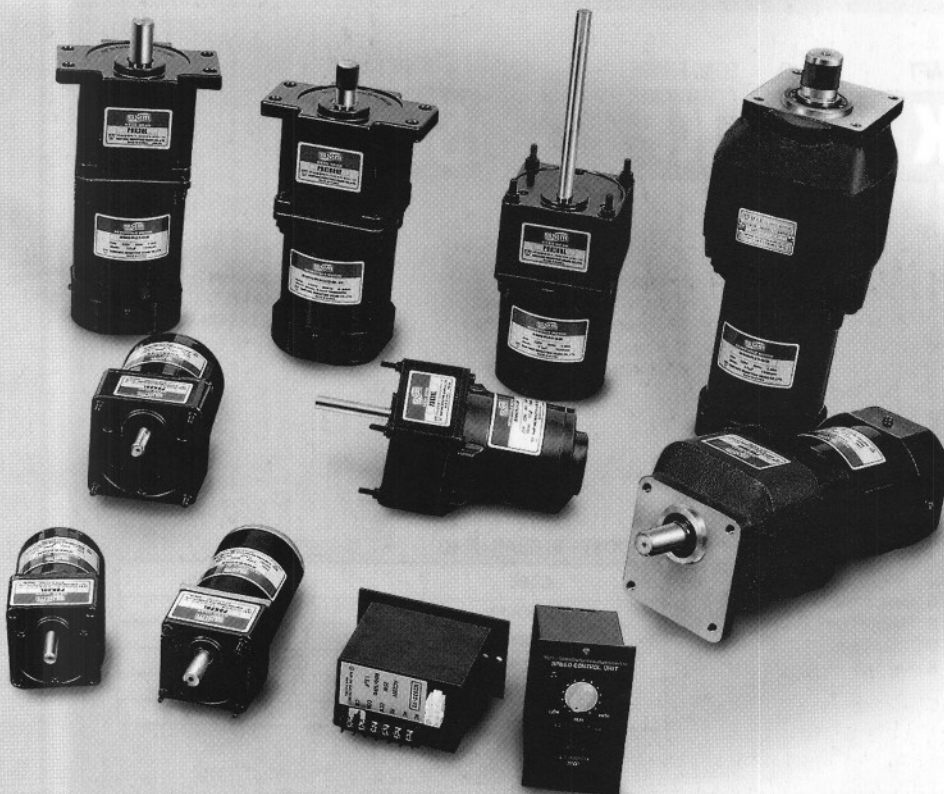
INDUCTION MOTOR



ELECTRO MAGNETIC BRAKE MOTOR



SPEED CONTROL MOTOR



제품분류표

CODE TREE

MOTOR CODE

MAKER	SIZE	MOTOR TYPE	WATT	SHAFT	VOLTAGE	LOAD	OPTION
SM	8	N	40	G	B	()	V12
6 : ☐ 60mm 7 : ☐ 70mm 8 : ☐ 80mm 9 : ☐ 90mm		N : Induction Motor R : Reversible Motor	06 : 6W 15 : 15W 25 : 25W 40 : 40W 60 : 60W 90 : 90W 120 : 120W 150 : 150W 180 : 180W 200 : 200W	G : Gear Screw Type S : Straight Type D : D-Cut Type K : Key Type	A : AC 110V-1 ϕ -60Hz-4P B : AC 220V-1 ϕ -60Hz-4P C : AC 100V-1 ϕ -50/60Hz-4P D : AC 200V-1 ϕ -50/60Hz-4P E : AC 115V-1 ϕ -60Hz-4P X : AC 220/240V-1 ϕ -50Hz-4P U : AC 200V-3 ϕ -50/60Hz-4P T : AC 220V-3 ϕ -50/60Hz-4P S : AC 380-440V-3 ϕ -50/60Hz-4P	- : Normal H : Heavy Load L : Light Load	E : Electro-Mag. Brake SB : Semi Brake T : Terminal Box V : Speed Control V12 : 12 Volt TG V24 : 24 Volt TG EV : Electro Mag. Brake Plus Speed Control

SAMYANG MOTOR

GEAR HEAD CODE

TYPE	SIZE	SHAFT	RATIO	LOAD FRAME	OPTION
P	9	K	180	KF	SL150
P : Parallel Shaft C : Concentric Shaft R : Right angle Shaft	6 : ☐ 60mm 7 : ☐ 70mm 8 : ☐ 80mm 9 : ☐ 90mm	G : Gear Screw Type S : Straight Type D : D-Cut Type K : Key Type	Reduction Ratio 03 : 1/3 05 : 1/5 075 : 7.5/1 ... 10 : 1/10 100 : 1/100 ... 1750 : 1/1750	L : Light H : Heavy HF : Heavy + Flange K : King KF : King + Flange	SL# : Shaft Length #mm 1GHT : 1ST GEAR H/T 1GPOM : 1ST GEAR POM (ACETAL)

► BOOST - IN GEAR HEAD

CODE	SIZE
BST 60N10	☐ 60mm Light
BST 80N10	☐ 80mm Light
BST 90N10	☐ 90mm Light
BST 90H10	☐ 90mm Heavy
BST 90K10	☐ 90mm King

소형모터·기어헤드

MOTOR · GEAR HEAD

● 소형모터 (MOTOR)

동 력 (POWER)	모터형식 (TYPE OF MOTOR)	INDUCTION	REVERSIBLE	EB-BRAKE	SPEED CONTROL	EB + SPEED CTRL
6W	민 축 D-SHAFT	SM6N06DB	SM6R06DB	SM6R06DB-E	SM6R06DB-V12	SM6R06DB-EV12
	기어축 G-SHAFT	SM6N06GB	SM6R06GB	SM6R06GB-E	SM6R06GB-V12	SM6R06GB-EV12
15W	민 축 D-SHAFT	SM7N15DB	SM7R15DB	SM7R15DB-E	SM7R15DB-V12	SM7R15DB-EV12
	기어축 G-SHAFT	SM7N15GB	SM7R15GB	SM7R15GB-E	SM7R15GB-V12	SM7R15GB-EV12
15W	민 축 D-SHAFT	SM8N15DB	SM8R15DB	SM8R15DB-E	SM8R15DB-V12	SM8R15DB-EV12
	기어축 G-SHAFT	SM8N15GB	SM8R15GB	SM8R15GB-E	SM8R15GB-V12	SM8R15GB-EV12
20W	민 축 D-SHAFT	SM8N20DB	SM8R20DB	SM8R20DB-E	SM8R20DB-V12	SM8R20DB-EV12
	기어축 G-SHAFT	SM8N20GB	SM8R20GB	SM8R20GB-E	SM8R20GB-V12	SM8R20GB-EV12
25W	민 축 D-SHAFT	SM8N25DB	SM8R25DB	SM8R25DB-E	SM8R25DB-V12	SM8R25DB-EV12
	기어축 G-SHAFT	SM8N25GB	SM8R25GB	SM8R25GB-E	SM8R25GB-V12	SM8R25GB-EV12
40W	민 축 D-SHAFT	SM9N40DB	SM9R40DB	SM9R40DB-E	SM9R40DB-V12	SM9R40DB-EV12
	기어축 G-SHAFT	SM9N40GB	SM9R40GB	SM9R40GB-E	SM9R40GB-V12	SM9R40GB-EV12
	H 기 어 HG-SHAFT	SM9N40GBH	SM9R40GBH	SM9R40GBH-E	SM9R40GBH-V12	SM9R40GBH-EV12
60W	민 축 D-SHAFT	SM9N60DB	SM9R60DB	SM9R60DB-E	SM9R60DB-V12	SM9R60DB-EV12
	기어축 G-SHAFT	SM9N60GB	SM9R60GB	SM9R60GB-E	SM9R60GB-V12	SM9R60GB-EV12
90W	민 축 D-SHAFT	SM9N90DB	SM9R90DB	SM9R90DB-E	SM9R90DB-V12	SM9R90DB-EV12
	기어축 G-SHAFT	SM9N90GB	SM9R90GB	SM9R90GB-E	SM9R90GB-V12	SM9R90GB-EV12
120W	민 축 D-SHAFT	SM9N120DB		SM9N120DB-E		
	기어축 G-SHAFT	SM9N120GB		SM9N120GB-E		
	킹기어 KG-SHAFT	SM9N120GBK		SM9N120GBK-E		
150W	민 축 D-SHAFT	SM9N150DB		SM9N150DB-E		
	기어축 G-SHAFT	SM9N150GB		SM9N150GB-E		
	킹기어 KG-SHAFT	SM9N150GBK		SM9N150GBK-E		
180W	민 축 D-SHAFT	SM9N180DB		SM9N180DB-E		
	기어축 G-SHAFT	SM9N180GB		SM9N180GB-E		
200W	민 축 D-SHAFT	SM9N200DB		SM9N200DB-E		
	기어축 G-SHAFT	SM9N200GB		SM9N200GB-E		

- 기어축인 경우 정격 기어 헤드와 조정됨. 기어 헤드에 따라 기어가 달라짐. 민축은 D자 형임.
- 전압은 220Vac기준이므로 [미로 표기되어 있음. 전원이 다를 경우에는 기호가 달라짐.
- 150Watt, 200Watt는 기본형의 크기에서는 삼상 전원만 사용함.
- D-SHAFT : Motor shaft to be round bar with D-cut seat.
- G-SHAFT : Motor shaft to be helical gear for SYM gear head, (normal)
- HG-SHAFT : Motor shaft to be helical gear for heavy gear head.
- KG-SHAFT : Motor shaft to be helical gear for king gear head.
- Geared shaft to be matched with specified gear head or optional (HG, KG)

- SPEED CONTROL 전압은 12V AC기준임.
- EB형 REVERSIBLE은 90W까지만 있고, 그 이상은 INDUCTION MOTOR 적용.
- 220VAG-60 HZ is type on the table for example only. Please specify input requirements exactly
- 150WATT, 220WATT : No single Phase of input available.
- 12 VAC is standard for speed controller generation.
- Reversible motors are available up to 90 watt.

● 소형기어헤드 (GEAR HEAD)

크 기 SIZE	출력축 SHAFT	일반형 N L: LIGHT		강력형 H H: HEAVY		강력플랜지 HF HF: HEAVY+FLANGE		킹형 K K: KING		킹플랜지 KF KF: KING+FLANGE	
		Model	동력(W)	Model	동력(W)	Model	동력(W)	Model	동력(W)	Model	동력(W)
60mm	평행형 PARALLEL	P6D # #L	6W								
	동심형 CONCENTRIC	C6D # #L									
	직교형 RIGHT	R6D # #L									
70mm	평행형 PARALLEL	P7K # #L	15W								
	동심형 CONCENTRIC	C7K # #L									
	직교형 RIGHT	R7K # #L									
80mm	평행형 PARALLEL	P8K # #L	15W 25W								
	동심형 CONCENTRIC	C8K # #L									
	직교형 RIGHT	R8K # #L									
90mm	평행형 PARALLEL	P9K # #H	40W	P9K # #H	60W, 90W	P9K # #HF	60W, 90W	P9K # #K	180W	P9K # #KF	180W
	동심형 CONCENTRIC	C9K # #H		C9K # #H	120W	C9K # #HF	120W	C9K # #K	200W	C9K # #KF	200W
	직교형 RIGHT	R9K # #H		R9K # #H	150W	R9K # #HF	150W	R9K # #K		R9K # #KF	

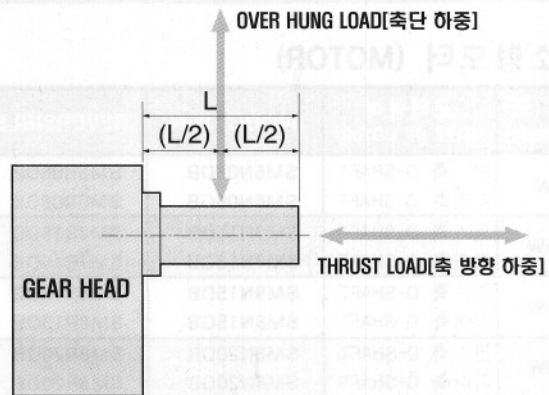
- ##에는 기어 비율을 기입함.
- 출력축의 형상에 따라 추가 사항을 기입하면 됨.
- Gear ratio to be filled at '##'.
- Options to be added to the code, (Shaft configurations . . .)

- 동심형은 유성 기어를 사용함.
- 직교형은 원 기어 형식이 표준임.
- Planetary gears may be used in concentric type.
- Worm gearing may be used in right angle type.

● OVER HUNG과 THRUST하중 (OVERHUNG LOAD AND THRUST LOAD)

▶ 축단하중은 축에 직각으로 걸리는 하중으로 감속기가 출력축과 사용기계와의 연결시 체인, 기어, 벨트등을 사용하는 경우에 축단 하중이 걸리게 됩니다. 축단하중이 크게 작용하면 축이 휘며, 진동, 베어링의 파손 또는 CASE에 CRACK이 발생되는 원인이 되므로 반드시 축단하중을 검토하여 주십시오.

▶ Overhung Load(OHL) is a load which directs orthogonal to a shaft as radial load, generated by chain, gear, pulley, belt transmission. OHL causes bending, misalignment, vibration, bearing failure, foot failure or crack of structures when exceeds the capability. When you select a reducer, OHL should be considered into the system design.



● 각 GEAR HEAD별 OVER HUNG LOAD표(La) (Allowable Over-Hung Load (La))

MODEL	GEAR RATIO	MAX.허용 토크(Kg·cm) ALLOWABLE LOAD TORQUE(Kg·cm)	허용 축단하중(La) (L/2위치) (Kg) ALLOWABLE OHL(Center OS)Kg	허용 스러스트 하중(Kg) ALLOWABLE THRUST LOAD(Kgf)	비 고 REMARKS
P60N	20 ~ 200	30	12	3	P80N20Watt MEDIUM SPECIAL은 50%적용 50% CAPABILITY FOR 20WATT SPECIAL TYPE
P80N	20 ~ 200	80	25	5	
P90N	20 ~ 200	100	35	10	
P90H,HF	3 ~ 200	200	60	15	
P90K,KF	3 ~ 200	300	70		

- 허용 토크는 감속비별로 틀립니다.(각 GEAR HEAD 토크표 참조)
- GEAR RATIO 1/18 이하의 허용 축단 하중은 50~30%낮아짐.
- O.H.L.의 작용 위치가 멀어질수록 허용 O.H.L.도 작아짐.
- Allowable Load Torque will be dependent on gear ratio. Refer to the torque table of detail data sheet.
- Allowable OHL shall be 50~70 % of listed for the gear ratio 1/2 ~ 1/18
- Allowable OHL shall be reduced at the point of load locates further than middle of shaft length

● OVER HUNG LOAD계산 (Calculating OHL Capacity)

$$L_r = \frac{K \times T \times S_f}{R}$$

L_r : Over Hung Load(Kg)
 K : 구동방법에 의한 계수 (Pulley Factor)
 T : GEAR HEAD 출력축에 있어서 전달 토크(Kg·cm) (Load Torque (kg-cm))
 S_f : 설계자 안전계수 (Safety Factor by Designer)
 R : 치차, PULLEY 등의 유효 반경(cm) (Radius of Loading Pulley or Gear)

$L_r \geq L_a$ 이면 기어헤드를 더 큰 것으로 선정하십시오.
 $L_r < L_a$ should be required. If not, replace by bigger gear box.

구동방법에 따른 계수표(K) (Table : Pulley Factors (K))

구동방법 (DRIVING METHOD)	K
CHAIN TRANSMISSION	1.0
GEAR TRANSMISSION	1.25
V-BELT TRANSMISSION	1.5
FLAT BELT TRANSMISSION	2.5

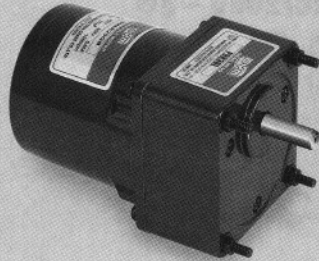
제품의 소개

INTRODUCTIONS

INDUCTION MOTOR

연속 운전 정격용 모터의 대표적인 기종으로서, Condenser 운전형 단상 모터와 콘덴서가 필요없는 삼상 모터 2종류가 있습니다.

Typical AC motors for continuous run under the loads. Single phase input type with condenser or three phases input type without condenser will provide you to select wide range of applications.

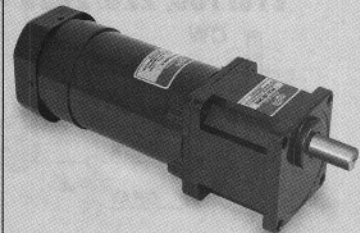


브레이크 모터

ELECTRO-MAGNETIC BRAKE MOTOR

전자 브레이크를 장착한 모터입니다. 무여자 작동형(NormClosed) B-Type 전자 브레이크를 채택하였습니다. 정지시 확실한 유지력을 갖추며, 안전성을 확보할 수 있습니다.

Electric motors with electro-magnetic brake inclosed, B-Type of brake (Normally closed) is the default type unless specified in order for EB-Motor. B-typed motor will be held during electric power off.



REVERSIBLE MOTOR

단속 운전 정격용 모터 기종으로서, 콘덴서 운전형 단상 모터입니다. 외관은 INDUCTION MOTOR와 거의 같지만 모터를 순간적으로 정지,기동 또는 역방향 기동이 가능하므로 정역운전을 자주 반복할 때 적합합니다.

Electric motor having semi-disk brake inclosed so that it can stop and run reverse direction within a second. It looks similar to Induction motor but is applied to the equipment that run and stop and rerun or reverse run frequently and continuous running within 30 minutes.



속도제어 MOTOR SPEED CONTROL MOTOR

속도 측정 Unit 및 컨트롤 Unit를 조합하여 회전속도를 자유자재로 조절할 수 있습니다. 속도제어 콘트롤 Unit를 필요로 합니다.

Electric motor having Tacho-Generator inclosed and external control unit combined. It requires speed control unit separately.



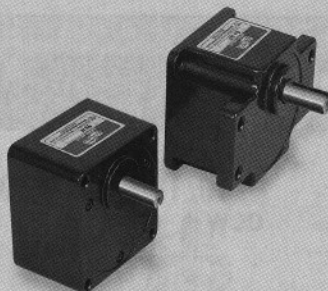
기어헤드 GEAR HEAD

SY모터중 기어형 출력축에 직결하여 사용할 수 있도록 제조된 감속기 Unit입니다. □60mm, □80mm, □90mm의 크기로 모터 부착부와 크기를 맞출 수 있습니다.

경하중에서 사용되는 일반형과 비교적 큰 부하용인 강력형, 대용량인 킹 사이즈로 대별되며 강력형과 킹사이즈는 플랜지형이 있어 설치 사용에 편리합니다.

Gear Box Reducer which was designed to be installed with SYM motor.

Size of boxes are □60 mm, □80 mm, □90 mm to fit with motors. Light type, Heavy Type, King type and Flanged Types will provide you wide variety of choice.



속도 컨트롤러 SPEED CONTROL UNIT

속도 컨트롤러는 Unit형과 PACK형이 있습니다. 당사는 일반 사용자에게 가장 널리 이용되는 Unit형을 기본으로 채택하고 있습니다. 디지털모델에는 피이드백 제어기능이 있는 고급형과 단순표시 기능만 있는 보급형이 있습니다. 아날로그와 보급형은 회전속도 가감 기능만 있습니다.

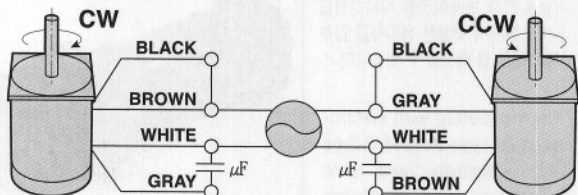
Separate unit to control speed control motor by Volume Handle. Unit type is the standard for default order.



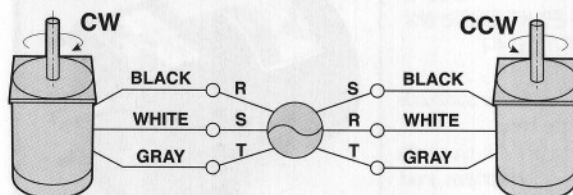
● 전원 결선도 종합표(WIRINGS TO MOTOR)

INDUCTION MOTOR

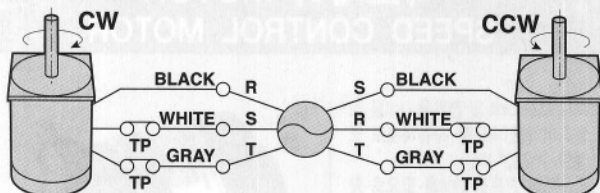
110/100, 220/200V - 1Ø



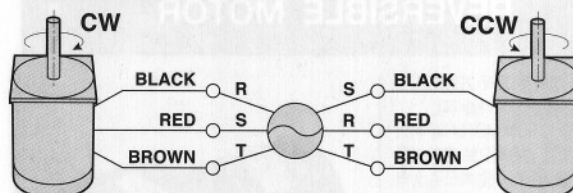
220/200V - 3Ø



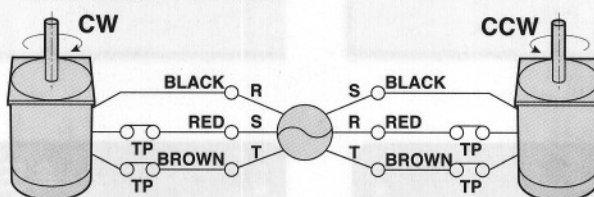
220/200V - 3Ø (TP)



380/440V - 3Ø

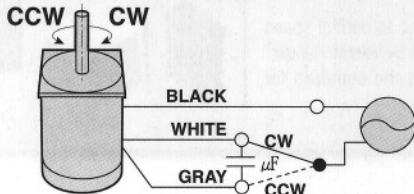


380/440V - 3Ø (TP)

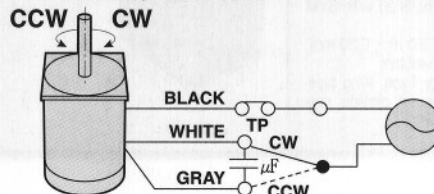


REVERSIBLE MOTOR

110/100, 220/200V - 1Ø

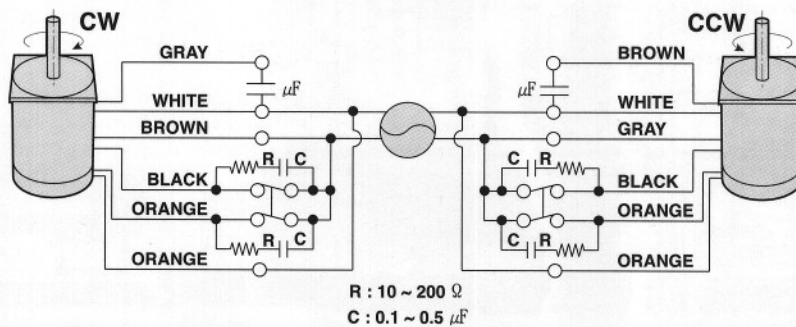


110/100, 220/200V - 1Ø (TP)

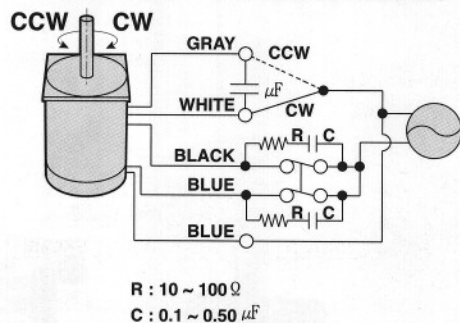


ELECTRO MAGNETIC BRAKE MOTOR

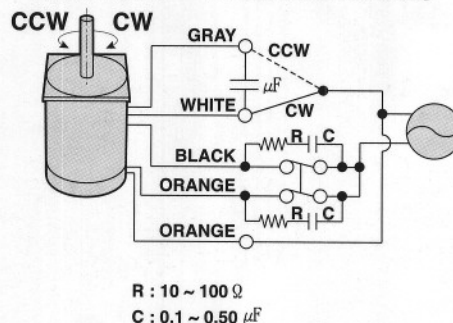
220/200V - 1 ϕ (INDUCTION)



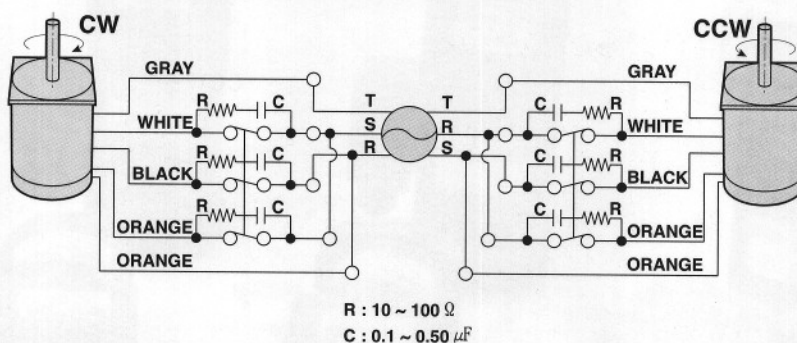
100/110V - 1 ϕ (REVERSIBLE)



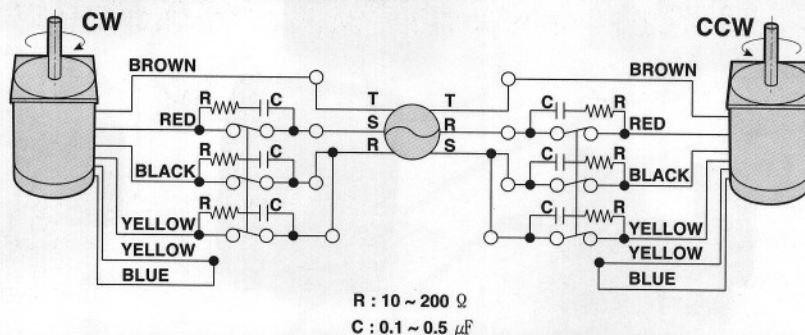
220/200V - 1 ϕ (REVERSIBLE)

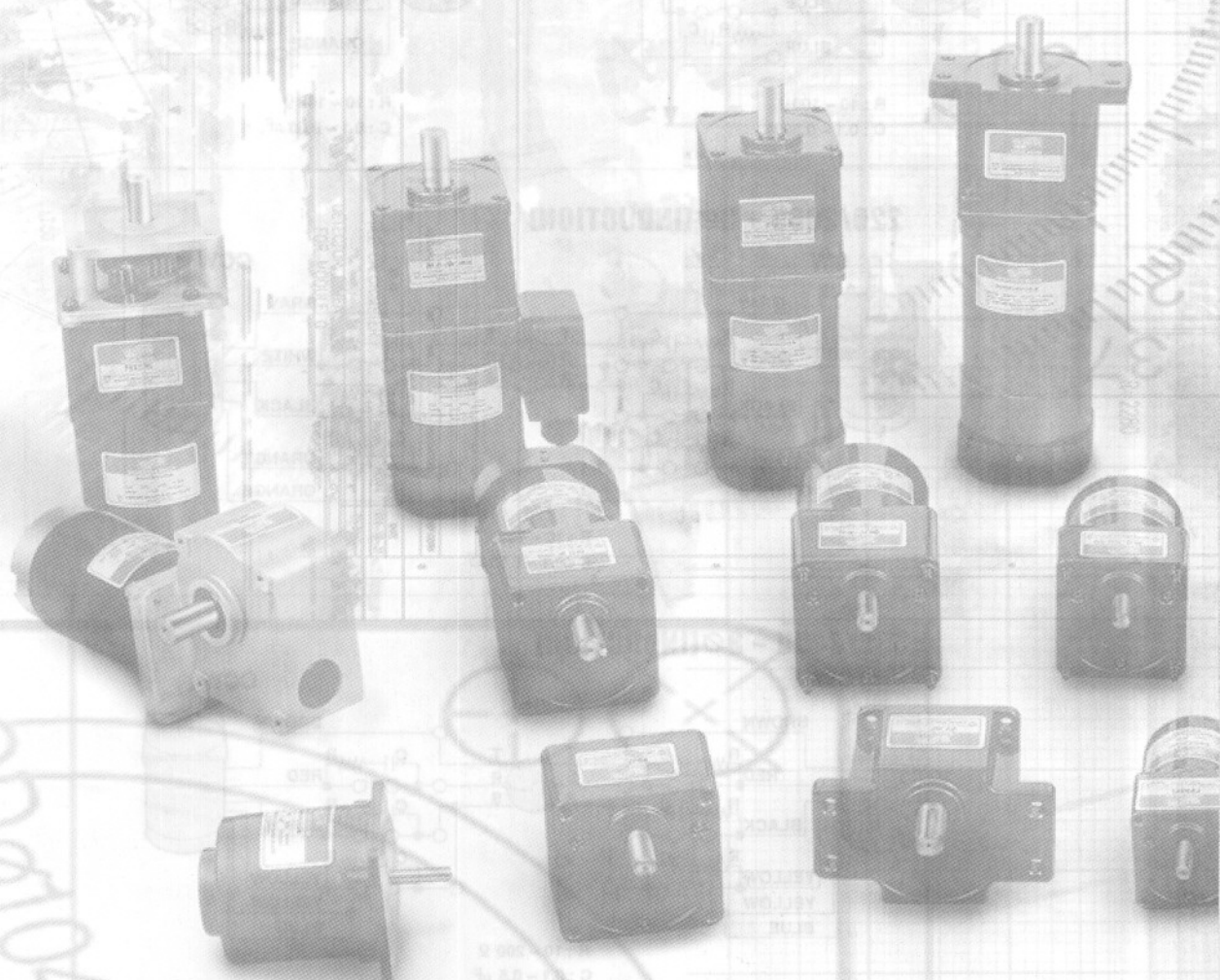


220/200V - 3 ϕ (INDUCTION)

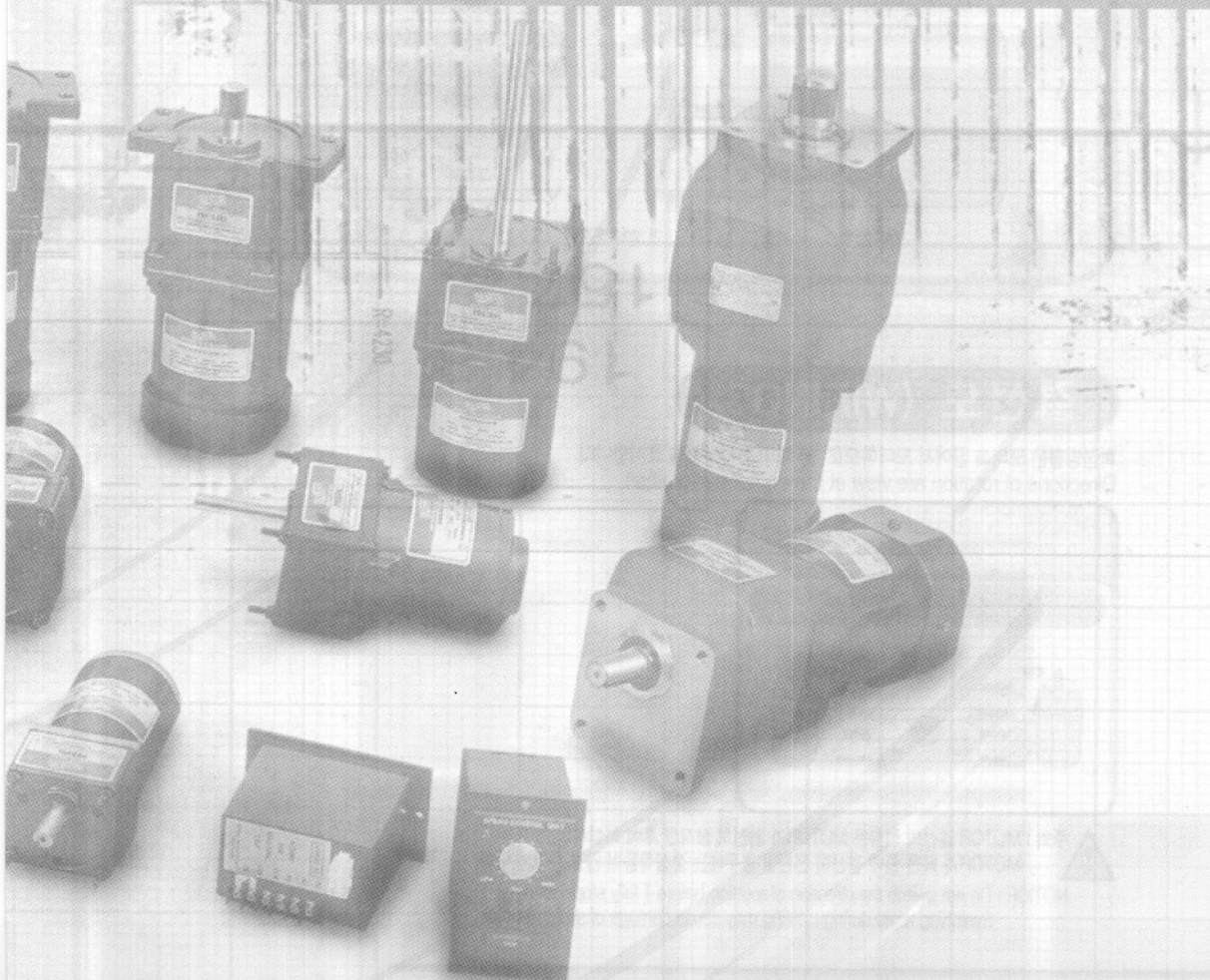
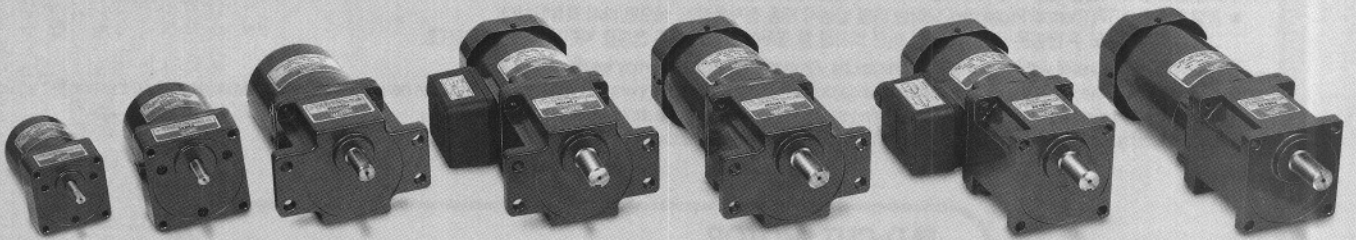


380/440V - 3 ϕ (INDUCTION)





INDUCTION MOTOR



6W

INDUCTION MOTOR

□60mm

LEAD WIRE TYPE

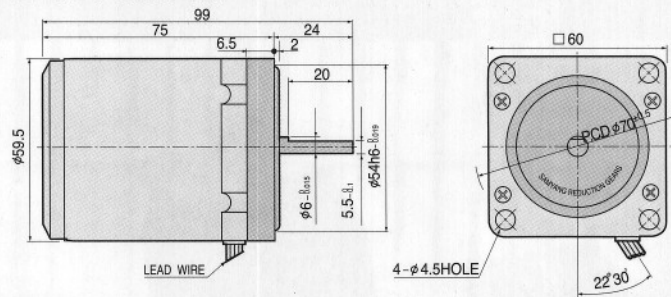


MOTOR SPECIFICATIONS

Model	Output Watt	Input Volt V	Phase	Freq. Hz	Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
							Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM6N06GB	6	220	1 ϕ	60	4	Cont.	0.11	1550	0.45	0.044	0.65	0.064	0.7

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

D-CUT MOTOR

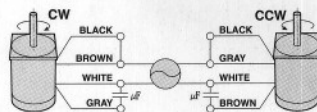


결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 200/220V-1 ϕ

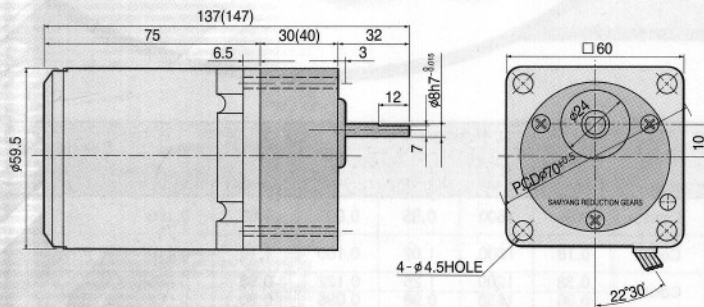
CW/CCW



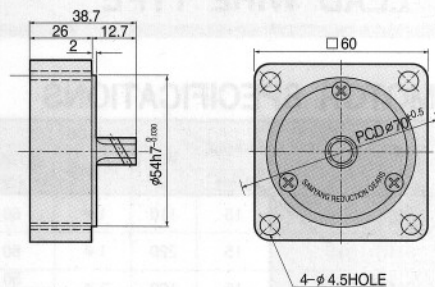
주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

● GEARED MOTOR



● BOOST-IN GEAR HEAD (BST 60N 10)



● WEIGHT

PART		WEIGHT(kg)
MOTOR		0.72
BOOST-IN GEAR HEAD		0.18
GEAR HEAD	1/3~1/18	0.25
	1/20~1/40	0.30
	1/50~1/200	0.33

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm) ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	0.9	1.0	1.4	1.7	2.1	2.6	2.9	3.6	4.3	5.1	5.1	6.3	7.6	9.1	10.1	11.4	13.6	17.0	20.5	22.7	27.3	30.0	30.0	30.0
	N-m	0.08	0.10	0.14	0.17	0.21	0.25	0.28	0.35	0.42	0.50	0.50	0.62	0.74	0.89	0.99	1.11	1.34	1.67	2.00	2.23	2.67	2.94	2.94	2.94

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	1.0	1.2	1.7	2.1	2.6	3.1	3.4	4.3	5.1	6.2	6.1	7.6	9.1	10.9	12.2	13.6	16.4	20.5	24.5	27.3	30.0	30.0	30.0	30.0
	N-m	0.10	0.12	0.17	0.20	0.25	0.30	0.34	0.42	0.50	0.60	0.60	0.74	0.89	1.07	1.19	1.34	1.60	2.00	2.41	2.67	2.94	2.94	2.94	2.94

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM, it may be reduced 1 ~ 20% dependent on the load applied actually.

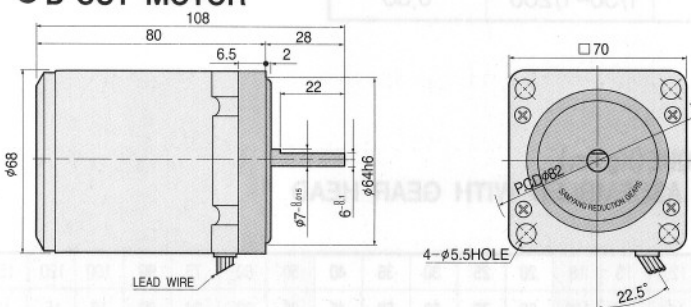
15W**INDUCTION MOTOR****70mm****LEAD WIRE TYPE**

● MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM7N15QA	15	110	1 ϕ	60	4	Cont.	0.36	1600	0.95	0.095	1.00	0.100	0.5
SM7N15GB	15	220	1 ϕ	60	4	Cont.	0.18	1600	1.02	0.100	1.10	0.110	1.3
SM7N15GC	15	100	1 ϕ	50	4	Cont.	0.38	1200	1.25	0.122	0.98	0.096	5.0
				60			0.36	1550	0.98	0.096	0.90	0.088	
SM7N15GD	15	200	1 ϕ	50	4	Cont.	0.18	1250	1.20	0.120	0.85	0.085	1.3
				60			0.17	1550	1.00	0.100			
SM7N15QE	15	115	1 ϕ	60	4	Cont.	0.32	1600	1.00	0.100	1.10	0.110	4.5
SM7N15GX	15	220	1 ϕ	50	4	Cont.	0.17	1200	1.17	0.114	0.90	0.088	1.0
		240					0.16	1300	1.10	0.108	1.06	0.104	

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

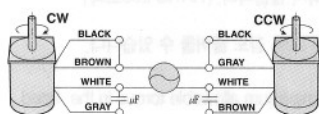
● D-CUT MOTOR



결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 200/220V-1 ϕ

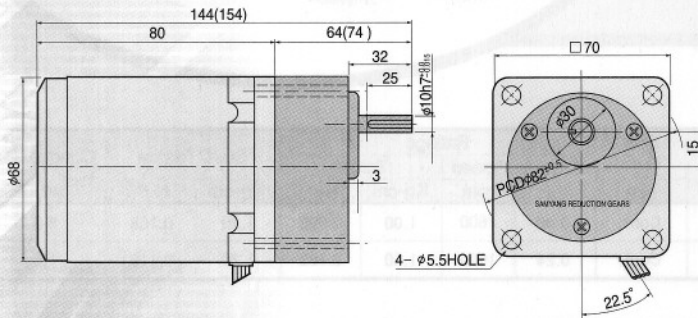
CW/CCW

주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

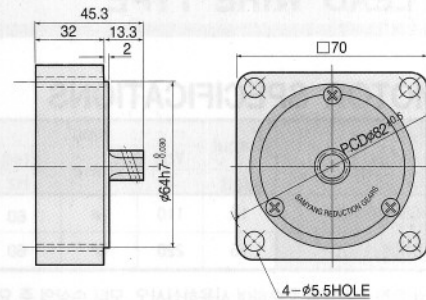
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

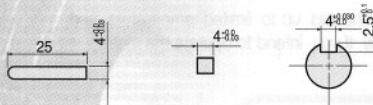
● GEARED MOTOR



● BOOST-IN GEAR HEAD (BST 70N 10)



● KEY SPEC



● WEIGHT

PART		WEIGHT(kg)
MOTOR		1.06
BOOST-IN GEAR HEAD		0.35
GEAR HEAD	1/3~1/18	0.36
	1/20~1/40	0.45
	1/50~1/200	0.5

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm) ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

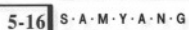
Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P7K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	2.1	2.6	3.6	4.3	5.4	6.4	7.1	8.9	10.7	12.9	12.7	15.8	19.0	22.8	25.3	28.4	34.1	42.6	51.1	56.8	60.0	60.0	60.0	60.0
	N-m	0.21	0.25	0.35	0.42	0.52	0.63	0.70	0.87	1.05	1.26	1.24	1.55	1.86	2.23	2.48	2.78	3.34	4.18	5.01	5.57	5.88	5.88	5.88	5.88

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P7K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	2.6	3.1	4.3	5.1	6.4	7.7	8.6	10.7	12.9	15.4	15.2	19.0	22.8	27.3	30.4	34.1	40.9	51.1	60.0	60.0	60.0	60.0	60.0	60.0
	N-m	0.25	0.30	0.42	0.50	0.63	0.76	0.84	1.05	1.26	1.51	1.49	1.86	2.23	2.68	2.98	3.34	4.01	5.01	5.88	5.88	5.88	5.88	5.88	5.88

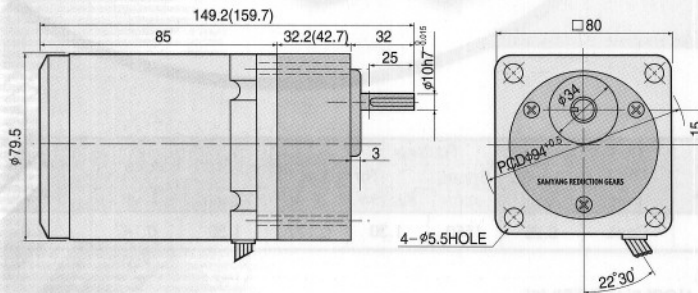
- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

LEAD WIRE TYPE

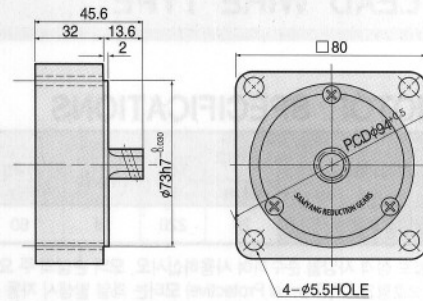


DIMENSIONS

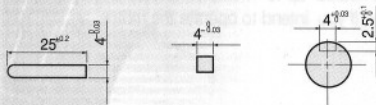
● GEARED MOTOR



● BOOST-IN GEAR HEAD (BST 80N 10)



● KEY SPEC



● WEIGHT

PART		WEIGHT(kg)
MOTOR		1.16
BOOST-IN GEAR HEAD		0.43
GEAR HEAD	1/3~1/18	0.43
	1/20~1/40	0.57
	1/50~1/200	0.60

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	2.1	2.6	3.6	4.3	5.4	6.4	7.1	8.9	10.7	12.9	12.7	15.8	19.0	22.8	25.3	28.4	34.1	42.6	51.1	56.8	68.2	80.0	80.0	80.0
	N-m	0.21	0.25	0.35	0.42	0.52	0.63	0.70	0.87	1.05	1.26	1.24	1.55	1.86	2.23	2.48	2.78	3.34	4.18	5.01	5.57	6.68	7.84	7.84	7.84

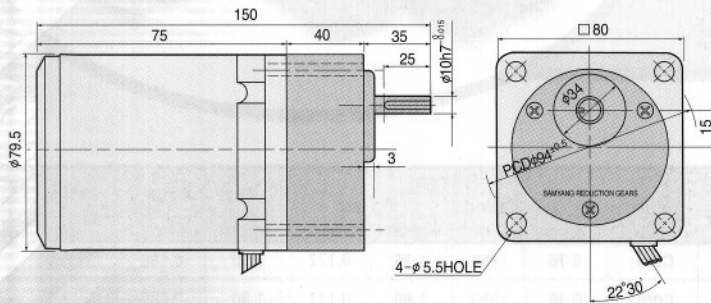
50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	2.6	3.1	4.3	5.1	6.4	7.7	8.6	10.7	12.9	15.4	15.2	19.0	22.8	27.3	30.4	34.1	40.9	51.1	61.4	68.2	80.0	80.0	80.0	80.0
	N-m	0.25	0.30	0.42	0.50	0.63	0.76	0.84	1.05	1.26	1.51	1.49	1.86	2.23	2.68	2.98	3.34	4.01	5.01	6.01	6.68	7.84	7.84	7.84	7.84

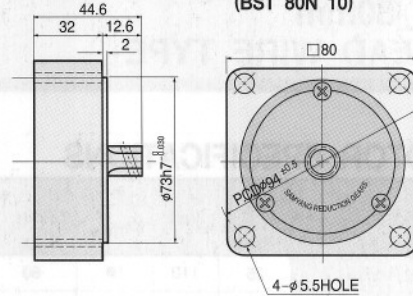
- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM, It may be reduced 1 ~ 20% dependent on the load applied actually.

DIMENSIONS

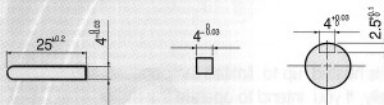
● GEARED MOTOR



● BOOST-IN GEAR HEAD (BST 80N 10)



● KEY SPEC



● WEIGHT

PART		WEIGHT(kg)
MOTOR		1.30
BOOST-IN GEAR HEAD		0.43
GEAR HEAD	1/3~1/18	0.38
	1/20~1/40	0.52
	1/50~1/200	0.55

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L-MD	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	2.9	3.4	4.8	5.7	7.1	8.6	9.5	11.9	14.3	17.1	16.9	21.1	25.3	30.4	33.8	37.9	45.5	56.8	68.2	75.8	80.0	80.0	80.0	80.0
	N-m	0.28	0.34	0.47	0.56	0.70	0.84	0.93	1.17	1.40	1.68	1.65	2.07	2.48	2.98	3.31	3.71	4.45	5.57	6.68	7.42	7.84	7.84	7.84	7.84

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L-MD	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	3.4	4.1	5.7	6.9	8.6	10.3	11.4	14.3	17.1	20.6	20.3	25.3	30.4	36.5	40.5	45.5	54.5	68.2	80.0	80.0	80.0	80.0	80.0	80.0
	N-m	0.34	0.40	0.56	0.67	0.84	1.01	1.12	1.40	1.68	2.02	1.99	2.48	2.98	3.57	3.97	4.45	5.35	6.68	7.84	7.84	7.84	7.84	7.84	7.84

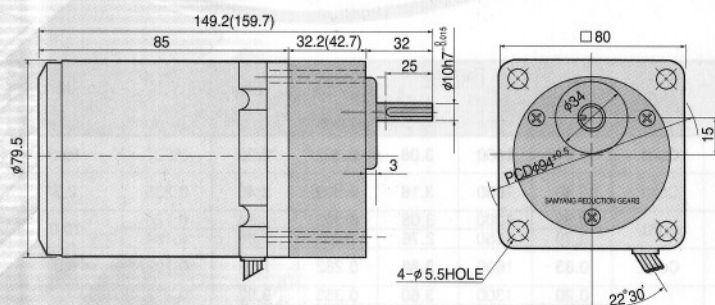
- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어든 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

LEAD WIRE TYPE

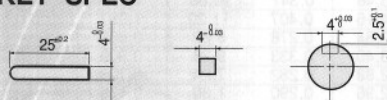


DIMENSIONS

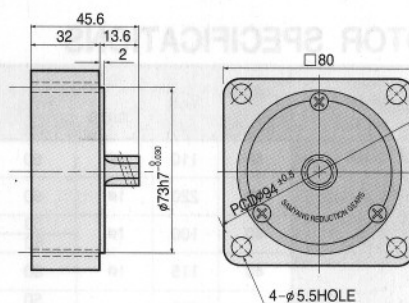
GEARED MOTOR



KEY SPEC



BOOST-IN GEAR HEAD (BST 80N 10)



WEIGHT

PART		WEIGHT(kg)
MOTOR		1.48
BOOST-IN GEAR HEAD		0.43
GEAR HEAD	1/3~1/18	0.43
	1/20~1/40	0.57
	1/50~1/200	0.60

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	3.6	4.3	6.0	7.1	8.9	10.7	11.9	14.9	17.9	21.4	21.1	26.4	31.7	38.0	42.2	47.3	56.8	71.0	80.0	80.0	80.0	80.0	80.0	80.0
	N-m	0.35	0.42	0.58	0.70	0.87	1.05	1.17	1.46	1.75	2.10	2.07	2.59	3.10	3.72	4.14	4.64	5.57	6.96	7.84	7.84	7.84	7.84	7.84	7.84

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.7	15	12.5	10	8.333	7.5
	kg-cm	4.3	5.1	7.1	8.6	10.7	12.9	14.3	17.9	21.4	25.7	25.3	31.7	38.0	45.6	50.6	56.8	68.2	80.0	80.0	80.0	80.0	80.0	80.0	80.0
	N-m	0.42	0.50	0.70	0.84	1.05	1.26	1.40	1.75	2.10	2.52	2.48	3.10	3.72	4.47	4.96	5.57	6.68	7.84	7.84	7.84	7.84	7.84	7.84	7.84

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

40W

INDUCTION MOTOR

□90mm

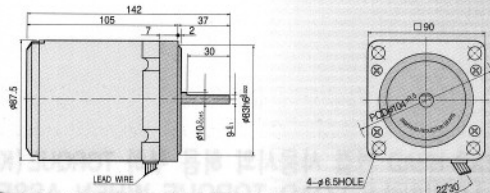
LEAD WIRE TYPE

● MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9N40GA	40	110	1 ϕ	60	4	Cont.	0.81	1600	3.08	0.302	2.32	0.227	10.0
SM9N40GB	40	220	1 ϕ	60	4	Cont.	0.40	1600	3.16	0.309	2.40	0.235	2.5
SM9N40GC	40	100	1 ϕ	50	4	Cont.	0.89	1300	3.08	0.302	1.84	0.180	10.0
SM9N40GE	40	115	1 ϕ	60	4	Cont.	0.79	1550	2.76	0.27	1.88	0.184	8.0
SM9N40GS	40	380	3 ϕ	50	4	Cont.	0.20	1300	3.60	0.353	9.92	0.972	2.0
				60			0.17	1600	2.48	0.243	7.80	0.764	
				50			0.25	1300	4.92	0.482	13.32	1.305	
				60			0.20	1600	3.48	0.341	10.60	1.039	
SM9N40GT	40	220	3 ϕ	50	4	Cont.	0.41	1300	4.16	0.407	11.20	1.097	2.0
				60			0.34	1600	2.84	0.278	8.80	0.862	
SM9N40GU	40	200	3 ϕ	50	4	Cont.	0.37	1300	3.40	0.333	9.28	0.909	2.0
				60			0.34	1550	2.88	0.282	7.24	0.709	
SM9N40GX	40	220	1 ϕ	50	4	Cont.	0.41	1300	2.96	0.290	1.80	0.176	2.0
		240					0.44	1300	3.60	0.353	2.12	0.207	

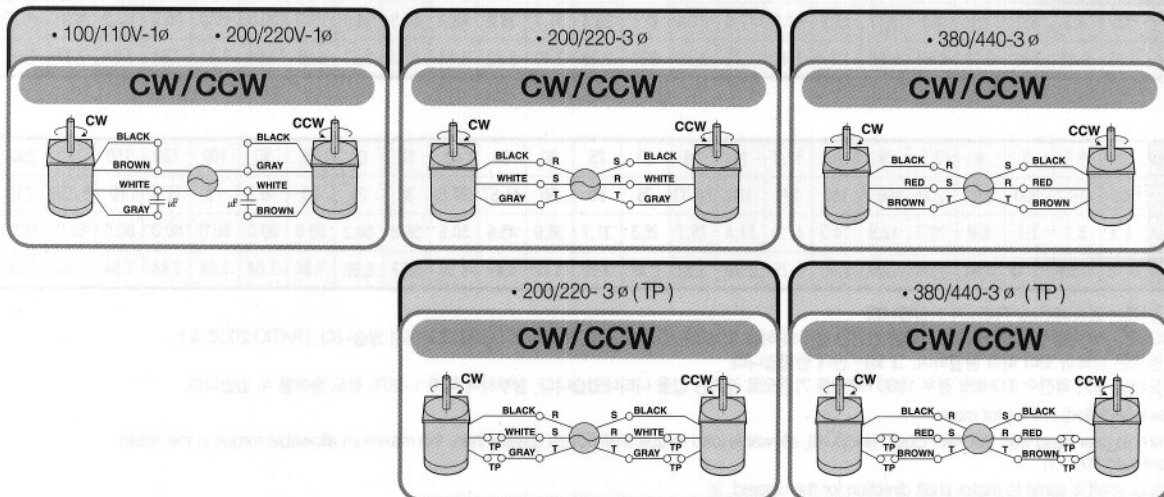
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications, Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR



결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다. Directions of rotation are view at the end of motor shaft.

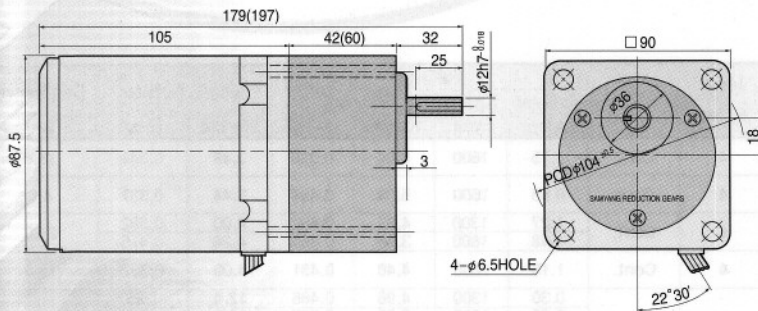


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

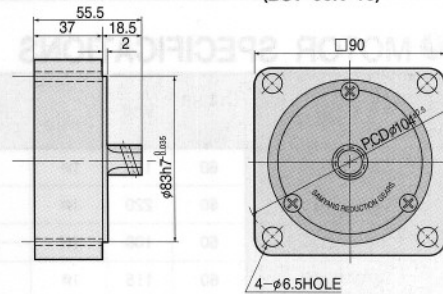
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

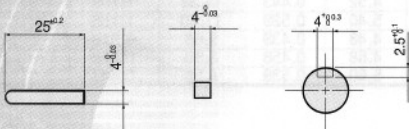
● GEARED MOTOR



● BOOST-IN GEAR HEAD (BST 90N 10)



● KEY SPEC



● WEIGHT

PART		WEIGHT(kg)
MOTOR		2,35
BOOST-IN GEAR HEAD		0,60
GEAR HEAD	1/3~1/18	0,75
	1/20~1/40	1,05
	1/50~1/200	1,15

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	5.7	6.9	9.5	11.4	14.3	17.1	19.0	23.8	28.6	34.3	33.8	42.2	50.6	60.8	67.5	75.8	90.9	100	100	100	100	100	100	100
	N-m	0.56	0.67	0.93	1.12	1.40	1.68	1.87	2.33	2.80	3.36	3.31	4.14	4.96	5.96	6.62	7.42	8.91	9.80	9.80	9.80	9.80	9.80	9.80	9.80

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	6.9	8.2	11.4	13.7	17.1	20.6	22.9	28.6	34.3	41.1	40.5	50.6	60.8	72.9	81.0	90.9	100	100	100	100	100	100	100	100
	N-m	0.67	0.81	1.12	1.34	1.68	2.02	2.24	2.80	3.36	4.03	3.97	4.96	5.96	7.15	7.94	8.91	9.80	9.80	9.80	9.80	9.80	9.80	9.80	9.80

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

60W

INDUCTION MOTOR

□90mm

LEAD WIRE TYPE

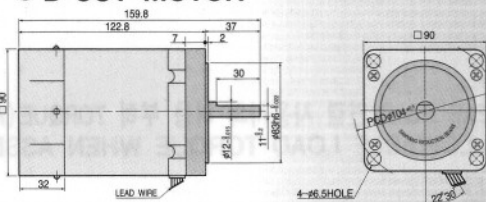


● MOTOR SPECIFICATIONS

Model	Output Watt	Input Volt V	Input Phase	Freq. Hz	Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
							Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9N60GA	60	110	1 ϕ	60	4	Cont.	1.15	1600	4.04	0.396	3.48	0.341	15.0
SM9N60GB	60	220	1 ϕ	60	4	Cont.	0.68	1600	5.04	0.494	3.44	0.337	4.0
SM9N60GC	60	100	1 ϕ	50	4	Cont.	1.27	1300	4.92	0.482	4.00	0.392	21.0
				60			1.48	1600	3.68	0.360	4.24	0.415	
SM9N60GE	60	115	1 ϕ	60	4	Cont.	1.18	1600	4.40	0.431	4.00	0.392	15.0
SM9N60GS	60	380	3 ϕ	50	4	Cont.	0.30	1300	4.96	0.486	12.4	1.26	
				60			0.25	1600	3.68	0.360	13.6	1.39	
				50			0.38	1300	6.60	0.647	16.2	1.65	
				60			0.30	1600	4.84	0.474	13.4	1.37	
SM9N60GT	60	220	3 ϕ	50	4	Cont.	0.70	1300	6.16	0.603	13.20	1.293	
				60			0.56	1600	4.52	0.443	11.32	1.109	
SM9N60GU	60	200	3 ϕ	50	4	Cont.	0.62	1300	5.40	0.529	11.80	1.156	
				60			0.57	1550	4.48	0.439	9.68	0.948	
SM9N60GX	60	220	1 ϕ	50	4	Cont.	0.58	1300	4.68	0.458	3.80	0.372	4.0
		240					0.64	1300	5.60	0.539	4.56	0.447	

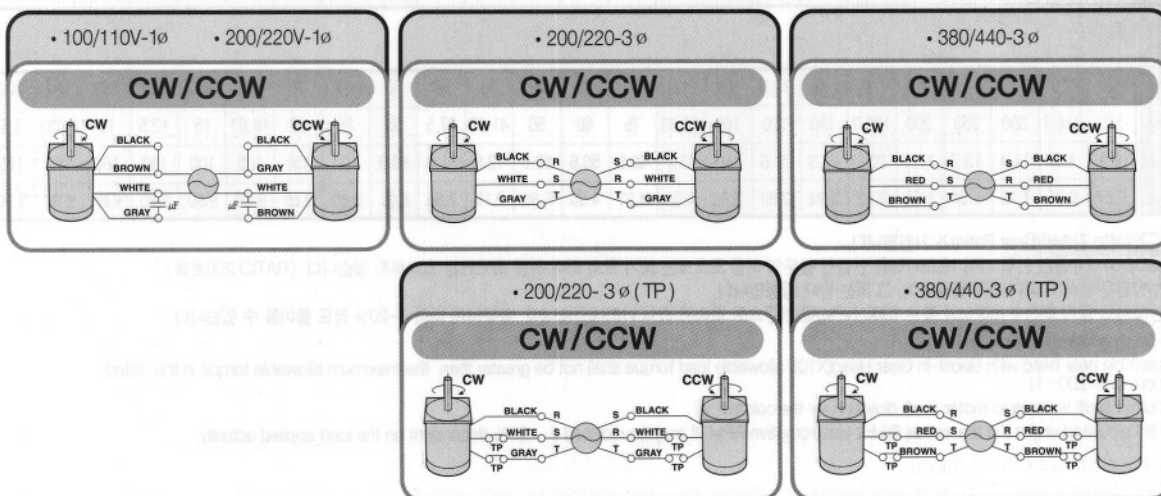
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- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR



결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다. Directions of rotation are view at the end of motor shaft.

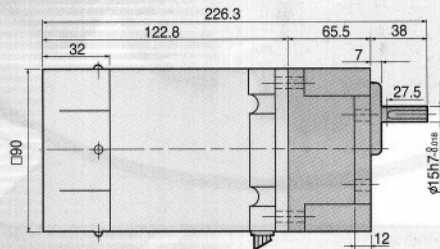


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MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

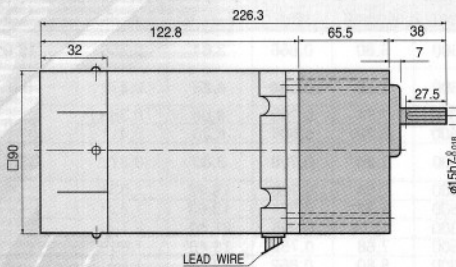
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DIMENSIONS

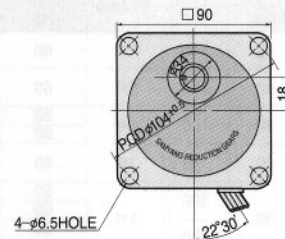
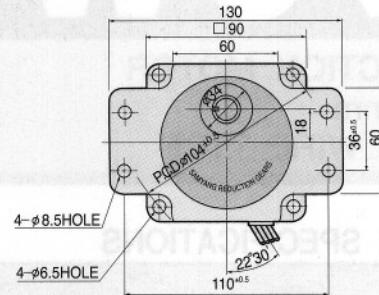
GEARED MOTOR



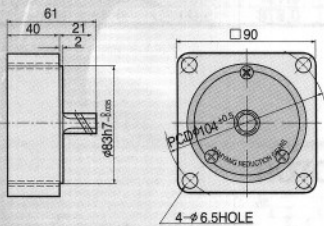
◀ HF TYPE ▶



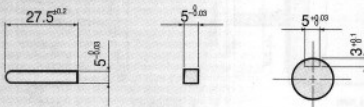
◀ H TYPE ▶



BOOST-IN GEAR HEAD (BST 90H 10)



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		2.50
BOOST- IN GEAR HEAD		0.65
GEAR HEAD	1/3~1/10	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□H	kg-cm	8.6	10.3	14.3	17.1	21.4	25.7	28.6	31.7	38.0	45.6	50.6	56.8	68.2	81.8	90.9	114	136	156	187	200	200	200	200	200
	N-m	0.84	1.01	1.40	1.68	2.10	2.52	2.80	3.10	3.72	4.47	4.96	5.57	6.7	8.0	8.9	11.1	13.4	15.3	18.3	19.6	19.6	19.6	19.6	19.6

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□H	kg-cm	10.3	12.3	17.1	20.6	25.7	30.9	34.3	38.0	45.6	54.7	60.8	68.2	81.8	98.2	109	136	164	187	200	200	200	200	200	200
	N-m	1.01	1.21	1.68	2.02	2.52	3.02	3.36	3.72	4.47	5.36	5.96	6.68	8.0	9.6	10.7	13.4	16.0	18.3	19.6	19.6	19.6	19.6	19.6	19.6

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어든 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

90W

INDUCTION MOTOR

90mm

LEAD WIRE TYPE

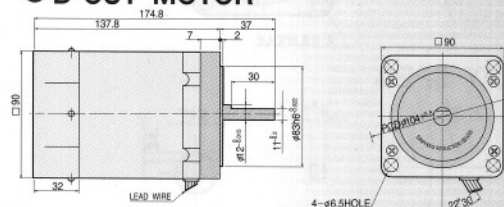


● MOTOR SPECIFICATIONS

Model	Output	Input			Mag. Poles	Run Duty	Ratings				Start Torque		Condenser
		Volt	Phase	Freq. Hz			Current	Speed	Torque				
	Watt	V				min	Amp	rpm	Kg-cm	N-m	Kg-cm	N-m	(μF)
SM9N90GA	90	110	1Ø	60	4	Cont.	1.66	1600	6.80	0.666	3.64	0.356	19.0
SM9N90GB	90	220	1Ø	60	4	Cont.	0.85	1600	7.08	0.694	4.28	0.419	5.0
SM9N90GC	90	100	1Ø	50 60	4	Cont.	1.74 1.70	1300 1600	7.24 6.20	0.709 0.607	4.08 4.20	0.399 0.411	23.0
SM9N90GE	90	115	1Ø	60	4	Cont.	1.71	1600	7.24	0.709	3.80	0.372	19.0
SM9N90GS	90	380	3 Ø	50	4	Cont.	0.39	1300	7.84	0.768	16.92	1.658	
				60			0.33	1600	5.32	0.521	13.60	1.333	
		440		50			0.45	1300	10.16	0.995	21.80	2.136	
				60			0.38	1600	7.68	0.752	18.40	1.803	
SM9N90GT	90	220	3 Ø	50	4	Cont.	0.71	1300	8.80	0.862	17.32	1.697	
				60			0.66	1600	6.36	0.623	14.20	1.391	
SM9N90GU	90	200	3 Ø	50	4	Cont.	0.72	1300	7.88	0.772	14.92	1.462	
				60			0.66	1550	6.24	0.611	11.92	1.168	
SM9N90GX	90	220	1Ø	50	4	Cont.	0.79	1300	7.52	0.737	4.20	0.411	4.5
		240					0.85	1300	8.96	0.878	5.00	0.49	

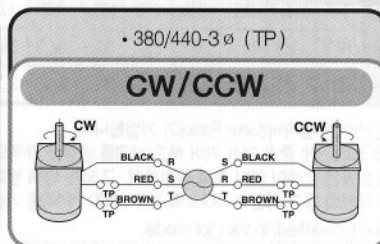
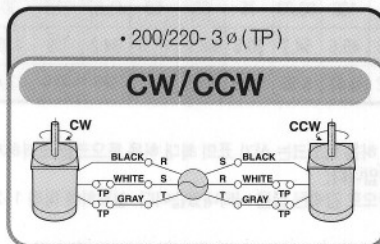
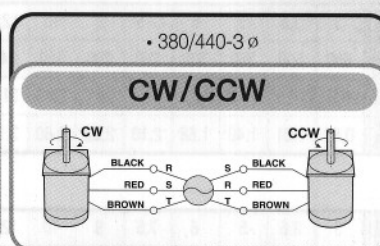
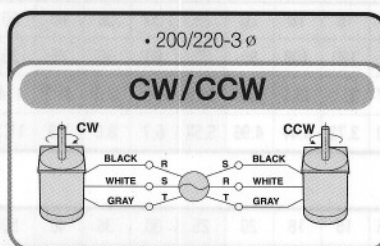
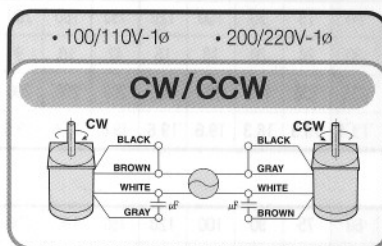
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications, Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch

● D-CUT MOTOR



결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다. Directions of rotation are view at the end of motor shaft.

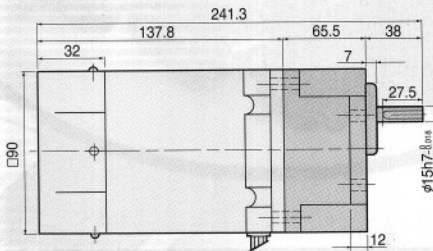


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

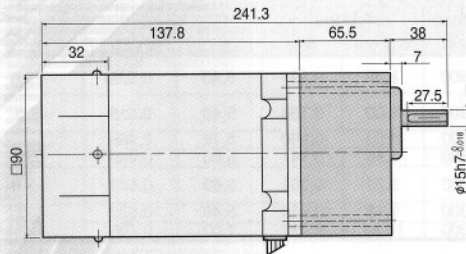
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

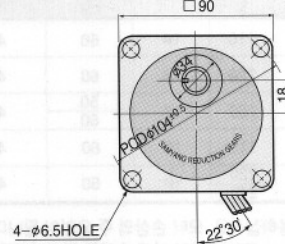
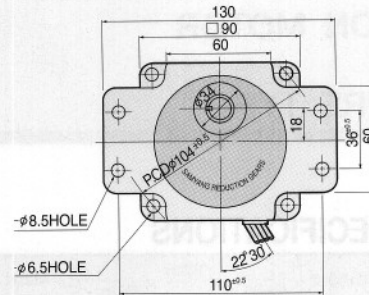
GEARED MOTOR



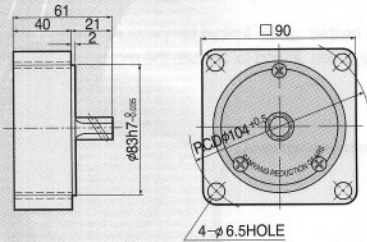
◀ HF TYPE ▶



◀ H TYPE ▶



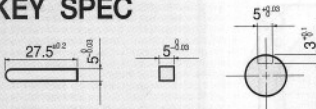
BOOST-IN GEAR HEAD (BST 90H 10)



WEIGHT

PART		WEIGHT(kg)
MOTOR		3.00
BOOST- IN GEAR HEAD		0.65
GEAR HEAD	1/3~1/10	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

KEY SPEC



GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□H	kg-cm	12.9	15.4	21.4	25.7	32.1	38.6	42.9	47.5	57.0	68.4	76.0	85.2	102	123	136	170	200	200	200	200	200	200	200	200
	N-m	1.26	1.51	2.10	2.52	3.15	3.78	4.20	4.65	5.58	6.70	7.45	8.35	10.0	12.0	13.4	16.7	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□H	kg-cm	15.4	18.5	25.7	30.9	38.6	46.3	51.4	57.0	68.4	82.0	91.2	102	123	147	164	200	200	200	200	200	200	200	200	200
	N-m	1.51	1.81	2.52	3.02	3.78	4.54	5.04	5.58	6.70	8.04	8.93	10.02	12.0	14.4	16.0	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored.
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

120W

INDUCTION MOTOR

□90mm

LEAD WIRE TYPE

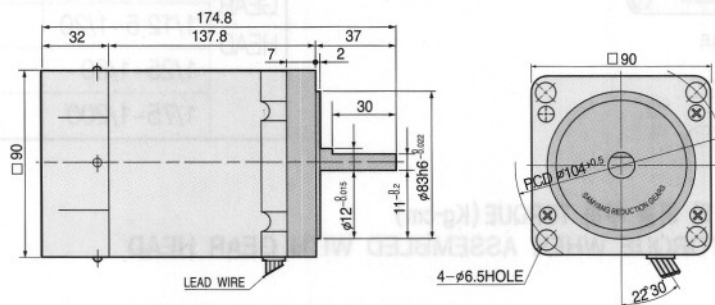


● MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque Kg-cm	Torque N-m	Kg-cm	N-m	
SM9N120GA	120	110	1 ϕ	60	4	Cont.	1.97	1600	8.48	0.831	5.40	0.529	25.0
SM9N120GB	120	220	1 ϕ	60	4	Cont.	0.98	1600	8.00	0.784	5.40	0.529	6.0
SM9N120GC	120	100	1 ϕ	50	4	Cont.	2.03	1300	9.08	0.890	4.76	0.466	28.0
				60			2.03	1600	7.56	0.741	5.00	0.490	
SM9N120GE	120	115	1 ϕ	60	4	Cont.	2.02	1600	9.20	0.901	5.60	0.549	23.0
SM9N120GX	120	220	1 ϕ	50	4	Cont.	0.98	1300	9.48	0.929	5.40	0.529	6.0
		240					1.06	1300	10.84	1.027	7.00	0.686	

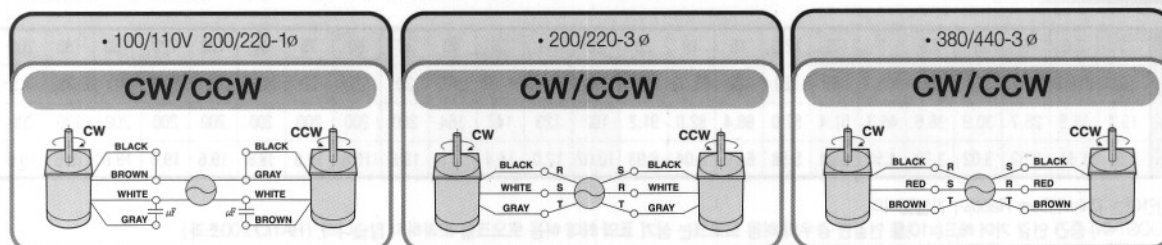
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR



결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다. Directions of rotation are view at the end of motor shaft.

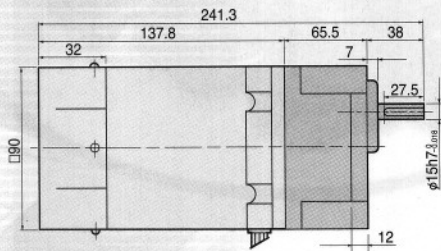


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

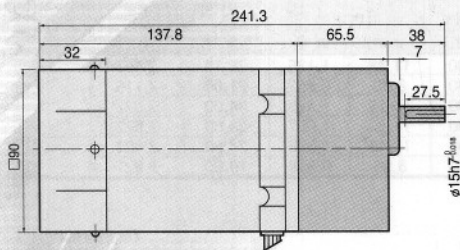
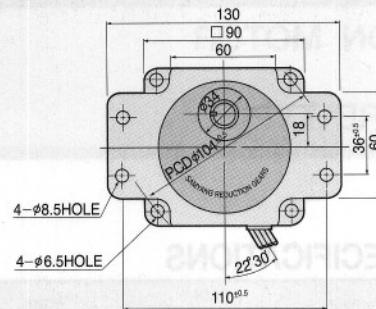
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

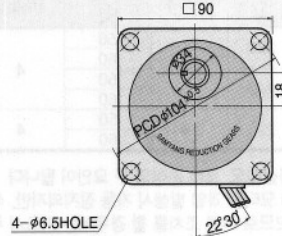
GEARED MOTOR



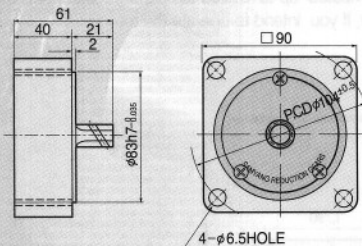
◀ HF TYPE ▶



◀ H TYPE ▶



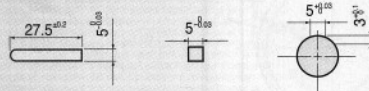
BOOST-IN GEAR HEAD (BST 90H 10)



WEIGHT

PART		WEIGHT(kg)
MOTOR		3.00
BOOST- IN GEAR HEAD		0.65
GEAR HEAD	1/3~1/10	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

KEY SPEC



GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□H	kg-cm	17.1	20.6	28.6	34.3	42.9	51.4	57.1	63.3	76.0	91.2	101	114	136	164	182	200	200	200	200	200	200	200	200	200
	N-m	1.68	2.02	2.80	3.36	4.20	5.04	5.60	6.20	7.45	8.93	9.93	11.1	13.4	16.0	17.8	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□H	kg-cm	20.6	24.7	34.3	41.1	51.4	61.7	68.6	76.0	91.2	109	122	136	164	196	200	200	200	200	200	200	200	200	200	200
	N-m	2.02	2.42	3.36	4.03	5.04	6.05	6.72	7.45	8.93	10.7	11.9	13.4	16.0	19.2	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

150W

INDUCTION MOTOR

□90mm

LEAD WIRE TYPE

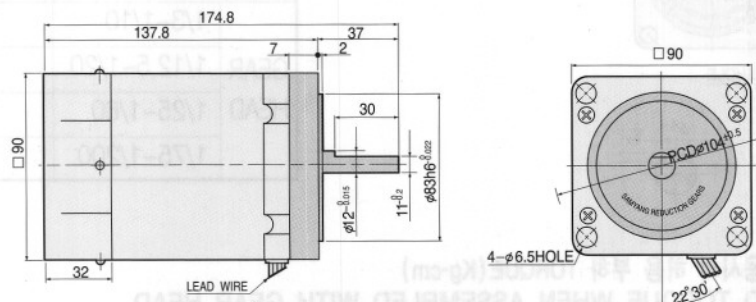


● MOTOR SPECIFICATIONS

Model	Output	Input			Mag. Poles	Run Duty	Ratings				Start Torque		Condenser
		Volt	Phase	Freq.			Current	Speed	Torque		Kg-cm	N-m	
	Watt	V		Hz	min	Amp	rpm	Kg-cm	N-m	Kg-cm	N-m	(μ F)	
SM9N150GS	150	380	3 ϕ	50	4	Cont.	0.55	1300	11.48	1.125	26.16	2.563	
				60			0.44	1600	8.80	0.862	21.60	2.116	
		440		50			0.68	1300	15.16	1.485	34.00	3.332	
				60			0.51	1600	11.20	1.097	28.80	2.822	
				60			0.85	1600	8.96	0.878	19.60	1.921	
SM9N150GT	150	220	3 ϕ	4	Cont.	1.02	1300	12.48	1.223	24.80	2.403		
						0.85	1600	8.96	0.878	19.60	1.921		

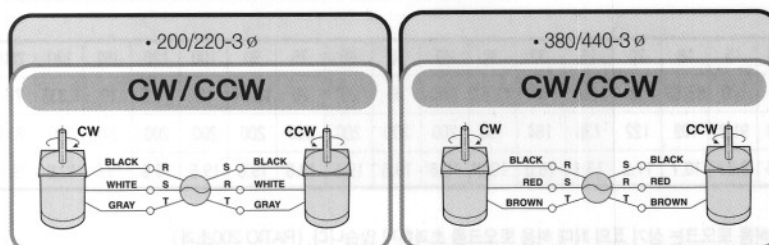
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR



결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

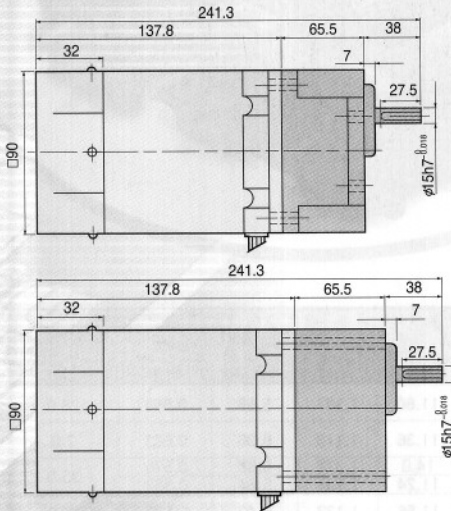


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

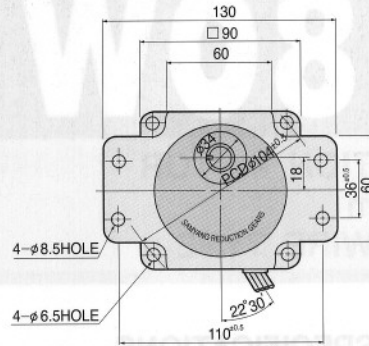
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

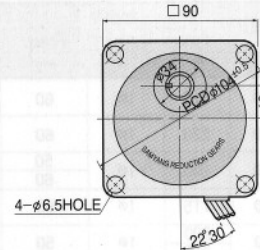
● GEARED MOTOR



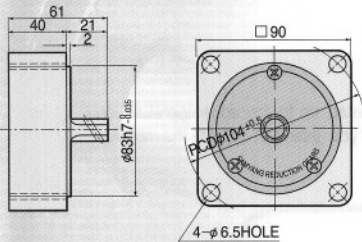
◀ HF TYPE ▶



◀ H TYPE ▶



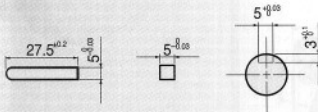
● BOOST-IN GEAR HEAD (BST 90H 10)



● WEIGHT

PART		WEIGHT(kg)
MOTOR		3.10
BOOST- IN GEAR HEAD		0.65
GEAR HEAD	1/3~1/10	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

● KEY SPEC



● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF P9K□H	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	21.4	25.7	35.7	42.9	53.6	64.3	71.4	79.1	95.0	114	127	142	170	205	227	284	300	300	300	300	300	300	300	300
	N-m	2.10	2.52	3.50	4.20	5.25	6.30	7.00	7.76	9.31	11.2	12.4	13.9	16.7	20.0	22.3	27.8	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF P9K□H	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	25.7	30.9	42.9	51.4	64.3	77.1	85.7	95.0	114	137	152	170	205	245	273	300	300	300	300	300	300	300	300	300
	N-m	2.52	3.02	4.20	5.04	6.30	7.56	8.40	9.31	11.17	13.4	14.9	16.7	20.0	24.1	26.7	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

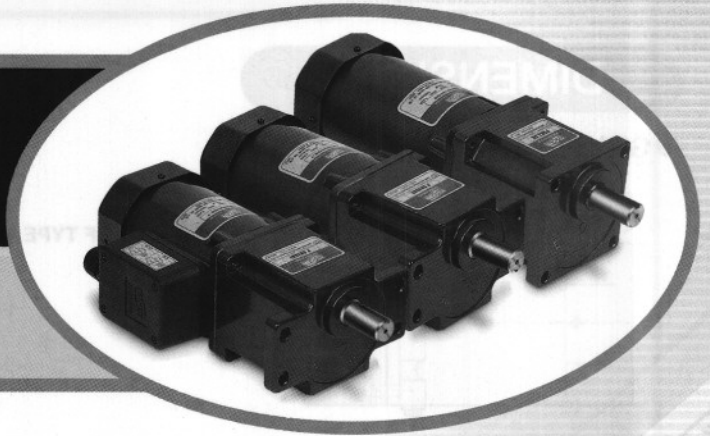
- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토오크는 상기 표의 최대 허용 토오크를 초과하지 않습니다. (RATIO 200 초과)
- 출력축의 회전 방향은 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed/filled in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored.
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

180W

INDUCTION MOTOR

□90mm

LEAD WIRE TYPE

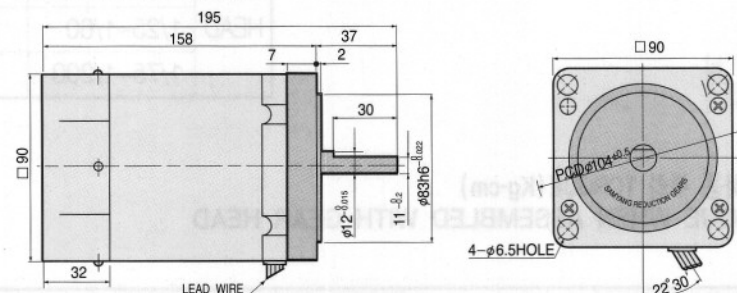


MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9N180GA	180	110	1 ϕ	60	4	Cont.	2.73	1600	11.60	1.137	5.68	0.556	28.0
SM9N180GB	180	220	1 ϕ	60	4	Cont.	1.34	1600	11.36	1.113	6.36	0.623	7.0
SM9N180GC	180	100	1 ϕ	50	4	Cont.	14.0	1250	14.0	1.372	5.88	0.576	35.0
				60			11.24	1600	11.24	1.101	5.64	0.552	
SM9N180GE	180	115	1 ϕ	60	4	Cont.	2.76	1600	11.56	1.133	5.40	0.529	25.0
SM9N180GX	180	220	1 ϕ	50	4	Cont.	1.32	1200	13.24	1.297	6.52	0.639	7.0
		240					1.27	1300	14.00	1.372	7.48	0.733	

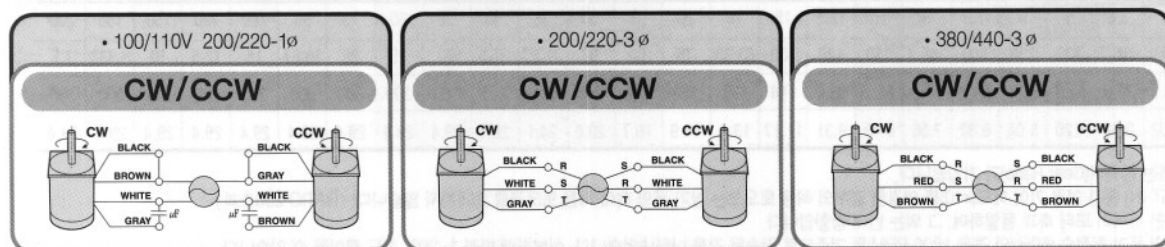
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

D-CUT MOTOR



결선도 (WIRINGS)

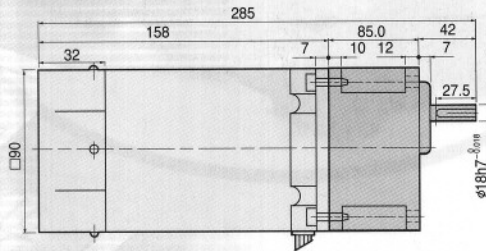
회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다. Directions of rotation are view at the end of motor shaft.



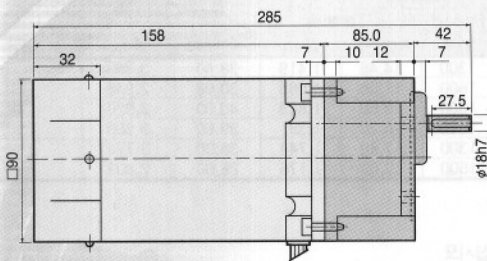
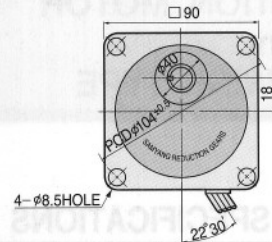
- 주의:** MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.
- NOTICE:** Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

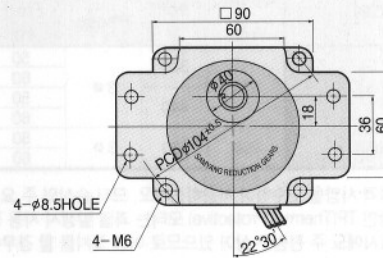
GEARED MOTOR



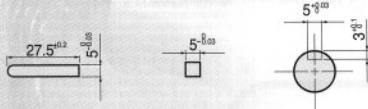
◀ K TYPE ▶



◀ KF TYPE ▶



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
GEAR HEAD	MOTOR	3.80
	1/3~1/10	1.70
	1/12.5~1/20	1.83
	1/25~1/200	1.93
	1/75~1/200	1.98

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□KF P9K□K	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	25.7	30.9	42.9	51.4	64.3	77.1	85.7	95.0	114	137	152	170	205	245	273	300	300	300	300	300	300	300	300	300
	N-m	2.52	3.02	2.20	5.04	6.30	7.56	8.40	9.31	11.17	13.4	14.9	16.7	20.0	24.1	26.7	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□KF P9K□K	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	30.9	37.0	51.4	61.7	77.1	92.6	103	114	137	164	182	205	245	295	300	300	300	300	300	300	300	300	300	300
	N-m	3.02	3.63	5.04	6.05	7.56	9.07	10.1	11.2	13.40	16.1	17.9	20.0	24.1	28.9	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과).
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

200W

INDUCTION MOTOR

□90mm

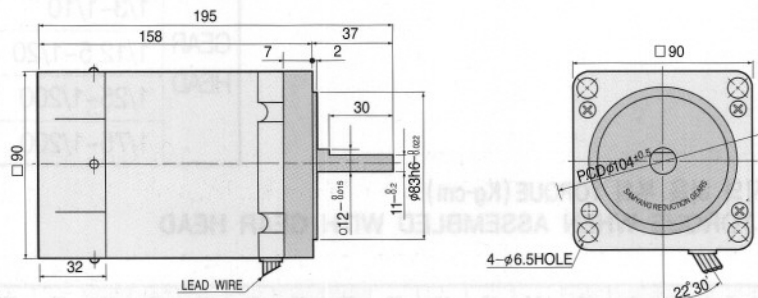
LEAD WIRE TYPE

● MOTOR SPECIFICATIONS

Model	Output	Input			Mag. Poles	Run Duty	Ratings				Start Torque		Condenser
		Volt	Phase	Freq.			Current	Speed	Torque		Kg-cm	N-m	
	Watt	V		Hz					min	Amp			
SM9N200GS	200	380	3 ϕ	50	4	Cont.	0.65	1300	14.48	1.419	38.40	3.763	
				60			0.57	1600	11.08	1.085	30.08	2.948	
		440		50			0.82	1300	18.60	1.823	40.00	3.920	
				60			0.66	1600	14.20	1.391	39.80	3.900	
				50			1.45	1300	17.80	1.744	38.00	3.724	
SM9N200GT	200	220	3 ϕ	60	4	Cont.	1.16	1600	12.00	1.176	28.60	2.803	

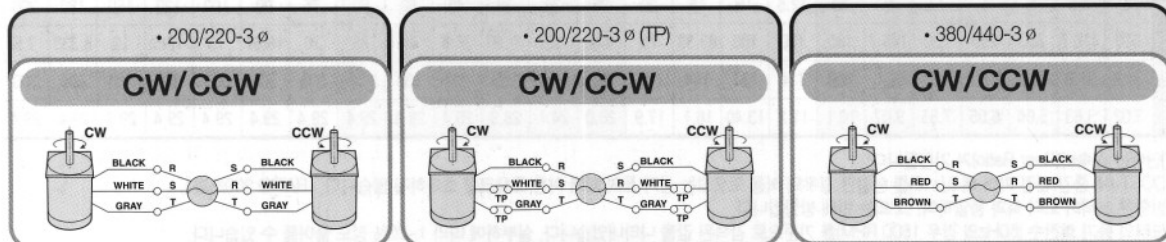
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR



결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다. Directions of rotation are view at the end of motor shaft.

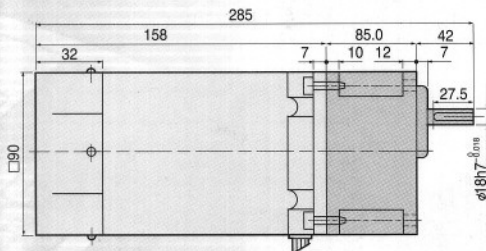


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

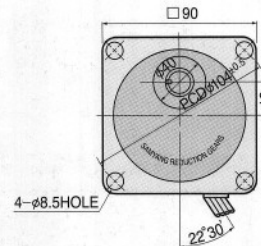
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
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DIMENSIONS

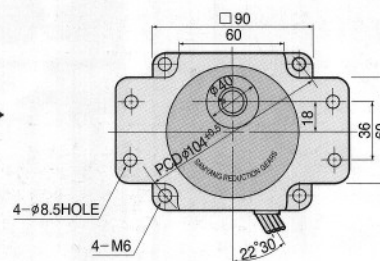
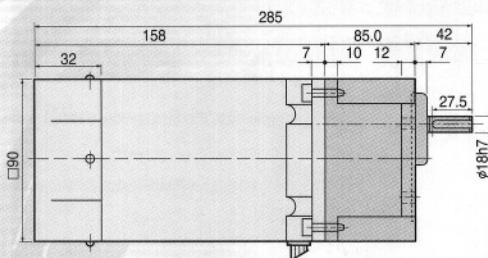
● GEARED MOTOR



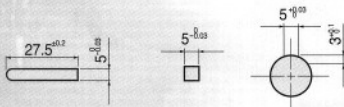
◀ K TYPE ▶



◀ KF TYPE ▶



● KEY SPEC



● WEIGHT

PART		WEIGHT(kg)
MOTOR		3.90
GEAR HEAD	1/3~1/10	1.70
	1/12.5~1/20	1.83
	1/25~1/60	1.93
	1/75~1/200	1.98

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

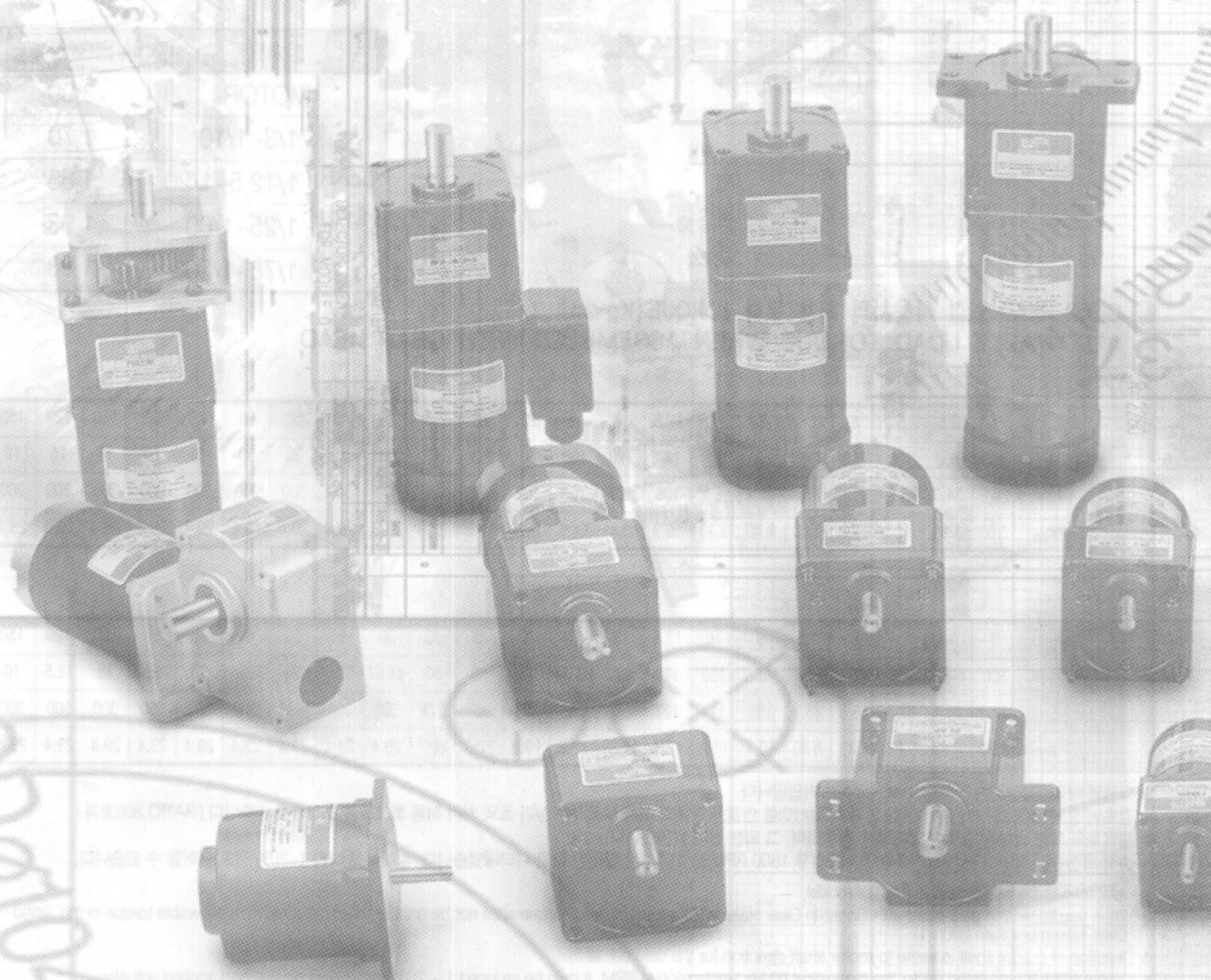
60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□KF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□K	kg-cm	28.6	34.3	47.6	57.1	71.4	85.7	95.2	106	127	152	169	189	227	273	300	300	300	300	300	300	300	300	300	300
	N-m	2.80	3.36	4.67	5.60	7.00	8.40	9.33	10.3	12.41	14.9	16.5	18.6	22.3	26.7	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

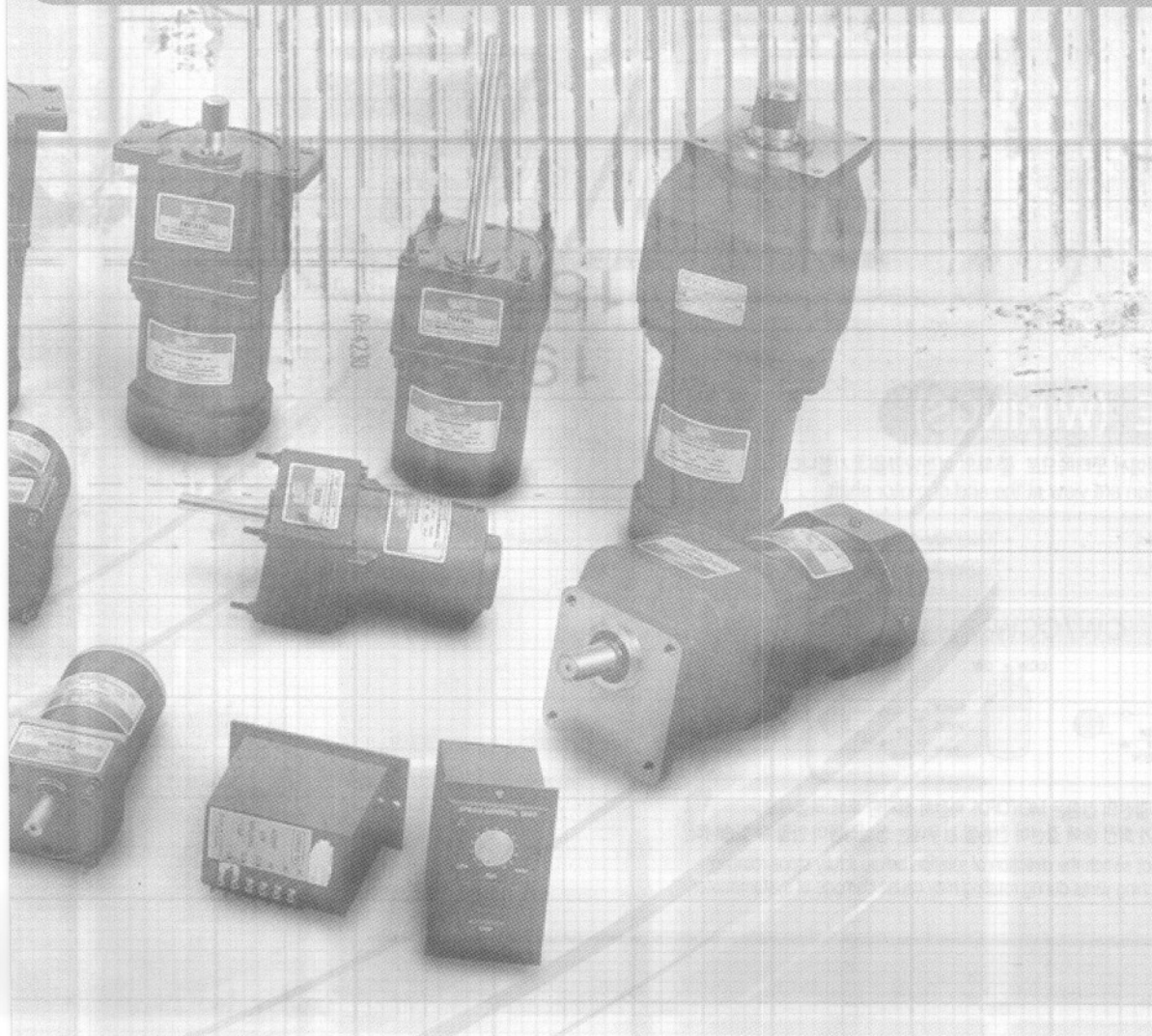
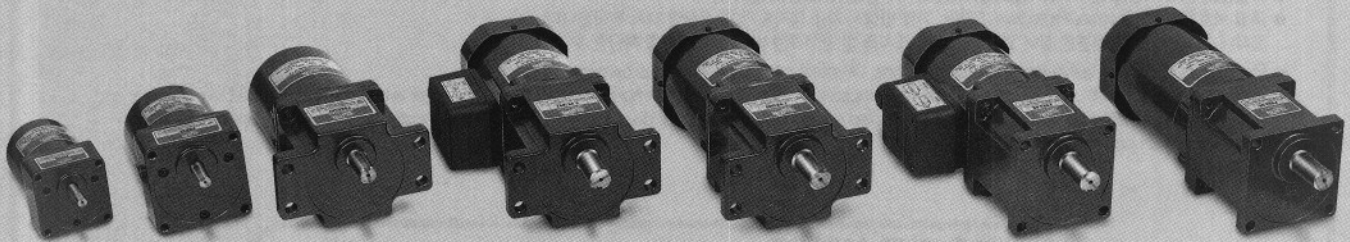
50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□KF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□K	kg-cm	34.3	41.1	57.1	68.6	85.7	103	114	127	152	182	203	227	273	300	300	300	300	300	300	300	300	300	300	300
	N-m	3.36	4.03	5.60	6.72	8.40	10.1	11.2	12.4	14.89	17.9	19.9	22.3	26.7	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
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- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.



REVERSIBLE MOTOR



6W

REVERSIBLE MOTOR

□60mm

LEAD WIRE TYPE

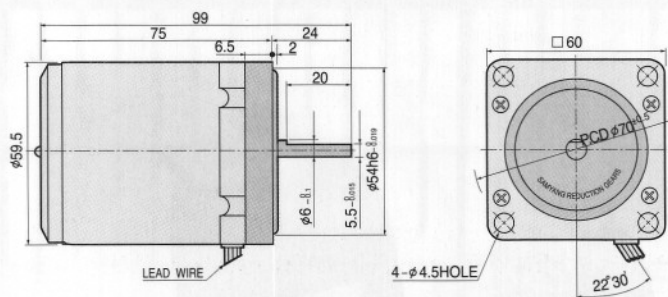


● MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM6R06GB	6	220	1 ϕ	60	4	30	0.12	1550	0.42	0.041	0.71	0.069	0.8

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR

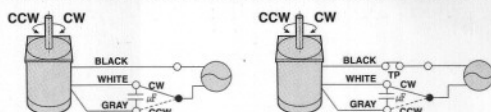


결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 200/220V-1 ϕ
- 100/110V-1 ϕ (TP)
- 200/220V-1 ϕ (TP)

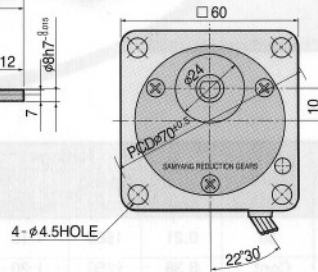
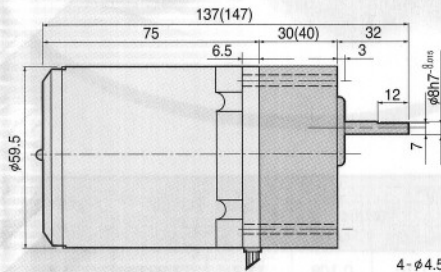
CW/CCW



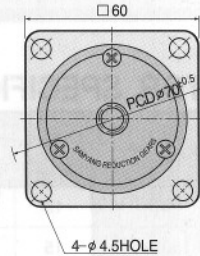
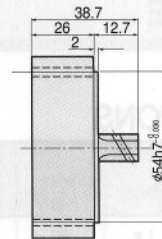
주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

● GEARED MOTOR



● BOOST-IN GEAR HEAD



● WEIGHT

PART		WEIGHT(kg)
MOTOR		0.75
BOOST-IN GEAR HEAD		0.18
GEAR HEAD	1/3~1/18	0.25
	1/20~1/40	0.30
	1/50~1/200	0.33

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P6D□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	0.9	1.0	1.4	1.7	2.1	2.6	2.9	3.6	4.3	5.1	5.1	6.3	7.6	9.1	10.1	11.4	13.6	17.0	20.5	22.7	27.3	30.0	30.0	30.0
	N-m	0.08	0.10	0.14	0.17	0.21	0.25	0.28	0.35	0.42	0.50	0.50	0.62	0.74	0.89	0.99	1.11	1.34	1.67	2.00	2.23	2.67	2.94	2.94	2.94

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P6D□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	1.0	1.2	1.7	2.1	2.6	3.1	3.4	4.3	5.1	6.2	6.1	7.6	9.1	10.9	12.2	13.6	16.4	20.5	24.5	27.3	30.0	30.0	30.0	30.0
	N-m	0.10	0.12	0.17	0.20	0.25	0.30	0.34	0.42	0.50	0.60	0.60	0.74	0.89	1.07	1.19	1.34	1.60	2.00	2.41	2.67	2.94	2.94	2.94	2.94

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

15W

REVERSIBLE MOTOR

70mm

LEAD WIRE TYPE

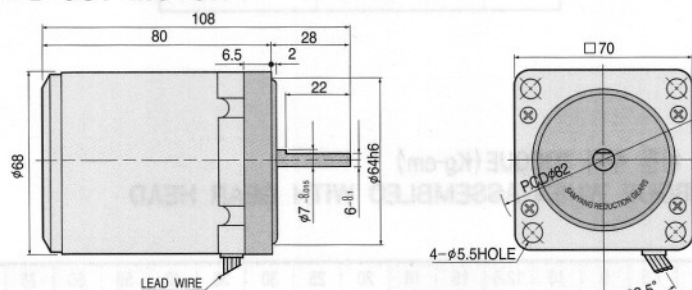


MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque Kg-cm	Torque N-m	Kg-cm	N-m	
SM7R15GB	15	220	1 ϕ	60	4	30	0.21	1600	1.10	0.108	13.2	1.293	1.5
SM7R15GC	15	100	1 ϕ	50	4	Cont.	0.38	1250	1.20	0.117	11.5	1.127	6.0
				60		-	0.40	1600	0.92	0.090	12.0	1.176	
SM7R15GX	15	220	1 ϕ	50	4	-	0.17	1300	1.14	0.111	1.21	0.118	1.3
		240				Cont.	0.19	1300	1.35	0.106	1.45	0.142	

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
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D-CUT MOTOR

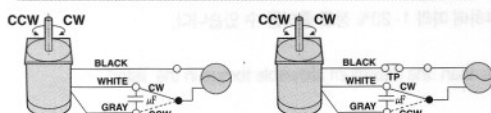


결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 200/220V-1 ϕ
- 100/110V-1 ϕ (TP)
- 200/220V-1 ϕ (TP)

CW/CCW

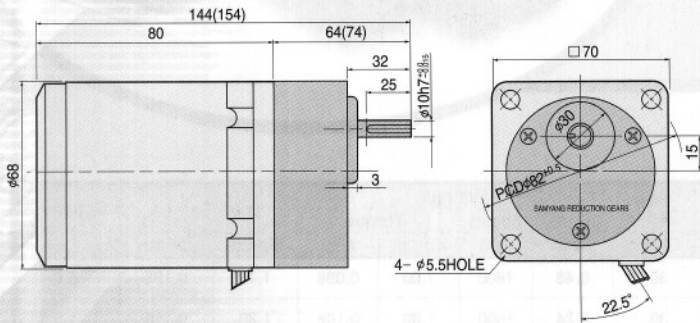


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

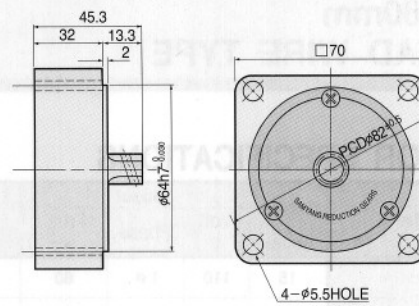
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

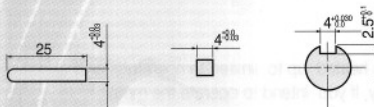
GEARED MOTOR



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		1.07
BOOST-IN GEAR HEAD		0.35
GEAR HEAD	1/3~1/18	0.36
	1/20~1/40	0.45
	1/50~1/200	0.5

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P7K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	2.1	2.6	3.6	4.3	5.4	6.4	7.1	8.9	10.7	12.9	12.7	15.8	19.0	22.8	25.3	28.4	34.1	42.6	51.1	56.8	60.0	60.0	60.0	60.0
	N-m	0.21	0.25	0.35	0.42	0.52	0.63	0.70	0.87	1.05	1.26	1.24	1.55	1.86	2.23	2.48	2.78	3.34	4.18	5.01	5.57	5.88	5.88	5.88	5.88

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P7K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	2.6	3.1	4.3	5.1	6.4	7.7	8.6	10.7	12.9	15.4	15.2	19.0	22.8	27.3	30.4	34.1	40.9	51.1	60.0	60.0	60.0	60.0	60.0	60.0
	N-m	0.25	0.30	0.42	0.50	0.63	0.76	0.84	1.05	1.26	1.51	1.49	1.86	2.23	2.68	2.98	3.34	4.01	5.01	5.88	5.88	5.88	5.88	5.88	5.88

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

15W

REVERSIBLE MOTOR

80mm

LEAD WIRE TYPE

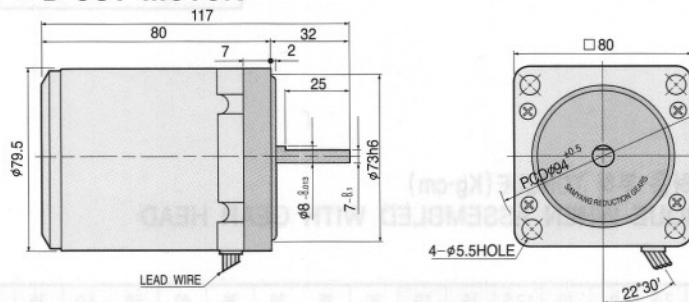


MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings			Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque Kg-cm N-m	Kg-cm	N-m	
SM8R15GA	15	110	1 ϕ	60	4	30	0.48	1600	1.00 0.098	1.10	0.108	5.0
SM8R15GB	15	220	1 ϕ	60	4	30	0.24	1600	1.00 0.108	1.20	0.118	1.5

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

D-CUT MOTOR

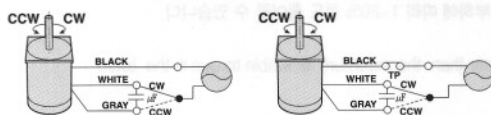


결선도 (WIRINGS)

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Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 200/220V-1 ϕ
- 100/110V-1 ϕ (TP)
- 200/220V-1 ϕ (TP)

CW/CCW

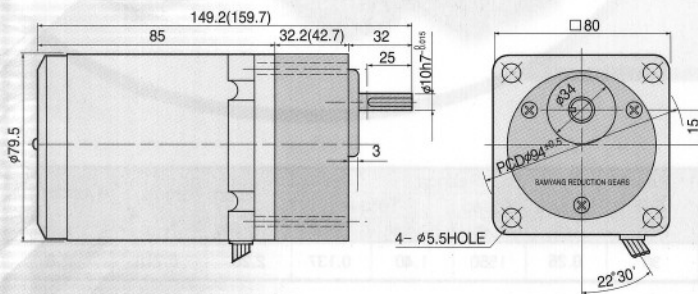


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

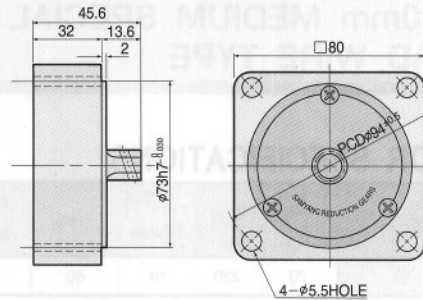
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

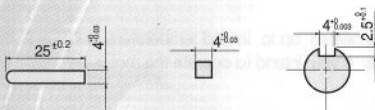
GEARED MOTOR



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		1.46
BOOST-IN GEAR HEAD		0.43
GEAR HEAD	1/3~1/18	0.43
	1/20~1/40	0.57
	1/50~1/200	0.60

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P7K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	2.1	2.6	3.6	4.3	5.4	6.4	7.1	8.9	10.7	12.9	12.7	15.8	19.0	22.8	25.3	28.4	34.1	42.6	51.1	56.8	68.2	80.0	80.0	80.0
	N-m	0.21	0.25	0.35	0.42	0.52	0.63	0.70	0.87	1.05	1.26	1.24	1.55	1.86	2.23	2.48	2.78	3.34	4.18	5.01	5.57	6.68	7.84	7.84	7.84

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P7K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	2.6	3.1	4.3	5.1	6.4	7.7	8.6	10.7	12.9	15.4	15.2	19.0	22.8	27.3	30.4	34.1	40.9	51.1	61.4	68.2	80.0	80.0	80.0	80.0
	N-m	0.25	0.30	0.42	0.50	0.63	0.76	0.84	1.05	1.26	1.51	1.49	1.86	2.23	2.68	2.98	3.34	4.01	5.01	6.01	6.68	7.84	7.84	7.84	7.84

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
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- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM, it may be reduced 1 ~ 20% dependent on the load applied actually.

20W

REVERSIBLE MOTOR

☐ 80mm MEDIUM SPECIAL
LEAD WIRE TYPE

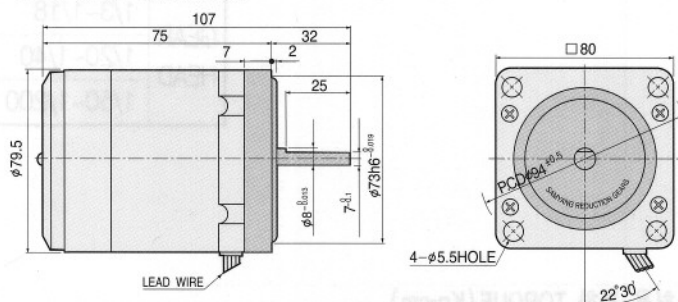


● MOTOR SPECIFICATIONS

Model	Output	Input			Mag. Poles	Run Duty	Ratings				Start Torque		Condenser
		Volt	Phase	Freq. Hz			Current	Speed rpm	Torque				
	Watt	V			Hz	Amp			kg-cm	N-m	kg-cm	N-m	(μF)
SM8R20GB	20	220	1Ø	60	4	30	0.26	1550	1.40	0.137	2.20	0.216	3.0

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원을 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
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● D-CUT MOTOR

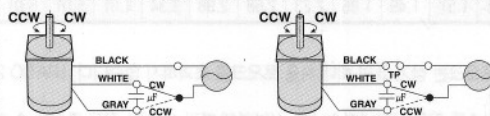


결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1ø
- 200/220V-1ø
- 100/110V-1ø (TP)
- 200/220V-1ø (TP)

CW/CCW

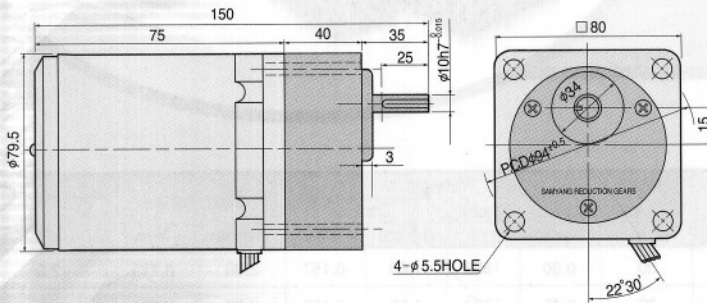


주의: MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

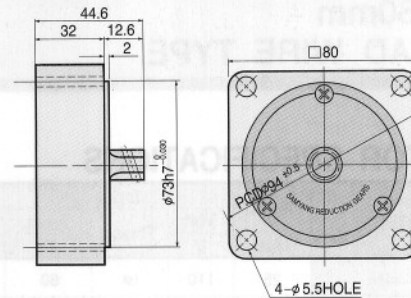
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

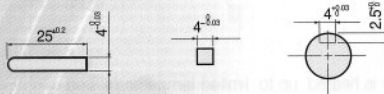
GEARED MOTOR



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		1.30
BOOST-IN GEAR HEAD		0.43
GEAR HEAD	1/3~1/18	0.38
	1/20~1/40	0.52
	1/50~1/200	0.55

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L-MD	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	2.9	3.4	4.8	5.7	7.1	8.6	9.5	11.9	14.3	17.1	16.9	21.1	25.3	30.4	33.8	37.9	45.5	56.8	68.2	75.8	80.0	80.0	80.0	80.0
	N-m	0.28	0.34	0.47	0.56	0.70	0.84	0.93	1.17	1.40	1.68	16.5	2.07	2.48	2.98	3.31	3.71	4.45	5.57	6.68	7.42	7.84	7.84	7.84	7.84

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L-MD	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	3.4	4.1	5.7	6.9	8.6	10.3	11.4	14.3	17.1	20.6	20.3	25.3	30.4	36.5	40.5	45.5	54.5	68.2	80.0	80.0	80.0	80.0	80.0	80.0
	N-m	0.34	0.40	0.56	0.67	0.84	1.01	1.12	1.40	1.68	2.02	1.99	2.48	2.98	3.57	3.97	4.45	5.35	6.68	7.84	7.84	7.84	7.84	7.84	7.84

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토오크는 상기 표의 최대 허용 토오크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM, it may be reduced 1 ~ 20% dependent on the load applied actually.

25W

REVERSIBLE MOTOR

80mm

LEAD WIRE TYPE

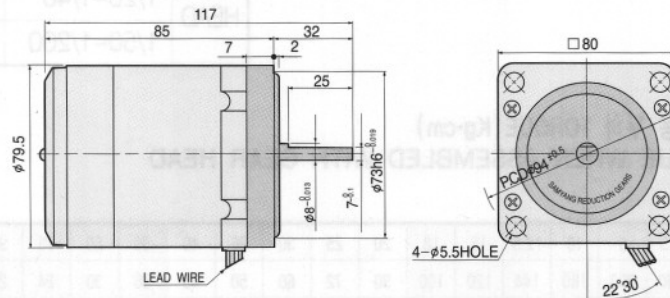


MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings			Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque Kg-cm N-m	Kg-cm	N-m	
SM8R25GA	25	110	1 ϕ	60	4	30	0.90	1550	1.60 0.157	2.80	0.275	12.0
SM8R25GB	25	220	1 ϕ	60	4	30	0.45	1550	1.65 0.162	3.00	0.294	3.0

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

D-CUT MOTOR

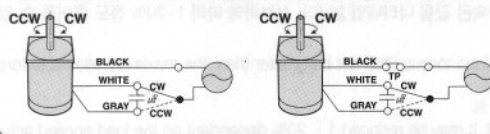


결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 100/110V-1 ϕ (TP)
- 200/220V-1 ϕ
- 200/220V-1 ϕ (TP)

CW/CCW

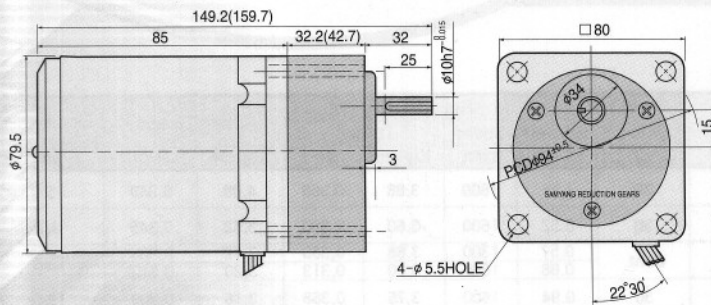


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

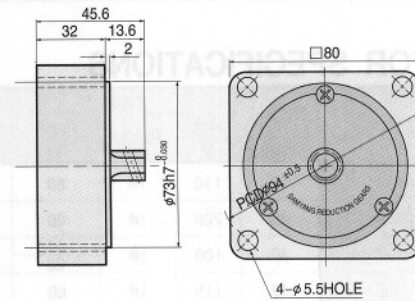
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

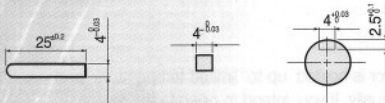
GEARED MOTOR



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		1.50
BOOST-IN GEAR HEAD		0.43
GEAR HEAD	1/3~1/18	0.43
	1/20~1/40	0.57
	1/50~1/200	0.60

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm) ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	3.6	4.3	6.0	7.1	8.9	10.7	11.9	14.9	17.9	21.4	21.1	26.4	31.7	38.0	42.2	47.3	56.8	71.0	80.0	80.0	80.0	80.0	80.0	80.0
	N-m	0.35	0.42	0.58	0.70	0.87	1.05	1.17	1.46	1.75	2.10	2.07	2.59	3.10	3.72	4.14	4.64	5.57	6.96	7.84	7.84	7.84	7.84	7.84	7.84

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	4.3	5.1	7.1	8.6	10.7	12.9	14.3	17.9	21.4	25.7	25.3	31.7	38.0	45.6	50.6	56.8	68.2	80.0	80.0	80.0	80.0	80.0	80.0	80.0
	N-m	0.42	0.50	0.70	0.84	1.05	1.26	1.40	1.75	2.10	2.52	2.48	3.10	3.72	4.47	4.96	5.57	6.68	7.84	7.84	7.84	7.84	7.84	7.84	7.84

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

40W

REVERSIBLE MOTOR

90mm

LEAD WIRE TYPE

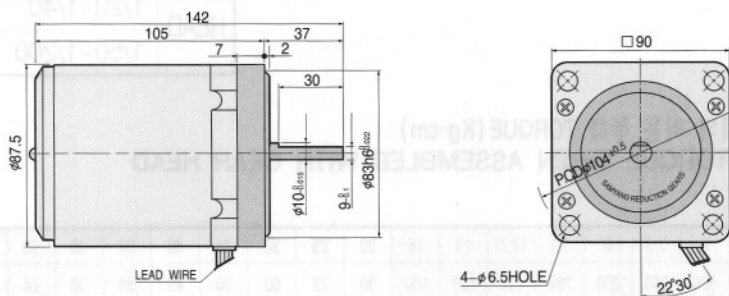


MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9R40GA	40	110	1 ϕ	60	4	30	1.11	1600	3.88	0.380	4.08	0.340	15.0
SM9R40GB	40	220	1 ϕ	60	4	30	0.52	1600	3.60	0.353	3.52	0.345	3.7
SM9R40GC	40	100	1 ϕ	50	4	Cont.	0.57	1300	3.88	0.380	3.12	0.305	15.0
				60			0.68	1600	3.20	0.313	3.20	0.313	
SM9R40GE	40	115	1 ϕ	60	4	30	0.94	1600	3.76	0.368	3.16	0.309	12.0

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

D-CUT MOTOR

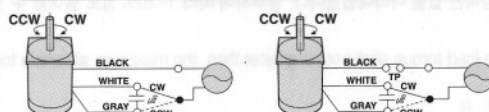


결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 100/110V-1 ϕ (TP)
- 200/220V-1 ϕ
- 200/220V-1 ϕ (TP)

CW/CCW

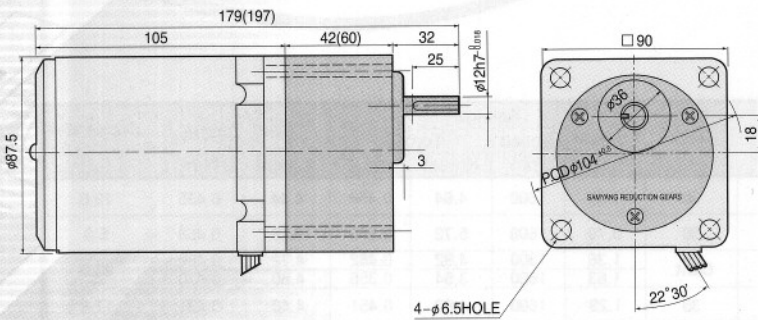


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
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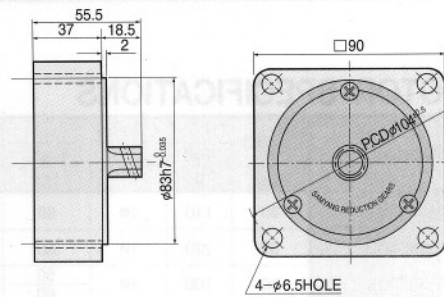
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DIMENSIONS

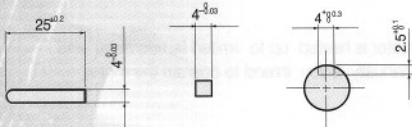
GEARED MOTOR



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		2.40
BOOST-IN GEAR HEAD		0.60
GEAR HEAD	1/3~1/18	0.75
	1/20~1/40	1.05
	1/50~1/200	1.15

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm) ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	5.7	6.9	9.5	11.4	14.3	17.1	19.0	23.8	28.6	34.3	33.8	42.2	50.6	60.8	67.5	75.8	90.9	100	100	100	100	100	100	100
	N-m	0.56	0.67	0.93	1.12	1.40	1.68	1.87	2.33	2.80	3.36	3.31	4.14	4.96	5.96	6.62	7.42	8.91	9.80	9.80	9.80	9.80	9.80	9.80	9.80

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	6.9	8.2	11.4	13.7	17.1	20.6	22.9	28.6	34.3	41.1	40.5	50.6	60.8	72.9	81.0	90.9	100	100	100	100	100	100	100	100
	N-m	0.67	0.81	1.12	1.34	1.68	2.02	2.24	2.80	3.36	4.03	3.97	4.96	5.96	7.15	7.94	8.91	9.80	9.80	9.80	9.80	9.80	9.80	9.80	9.80

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
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- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

60W

REVERSIBLE MOTOR

☐ 90mm

LEAD WIRE TYPE

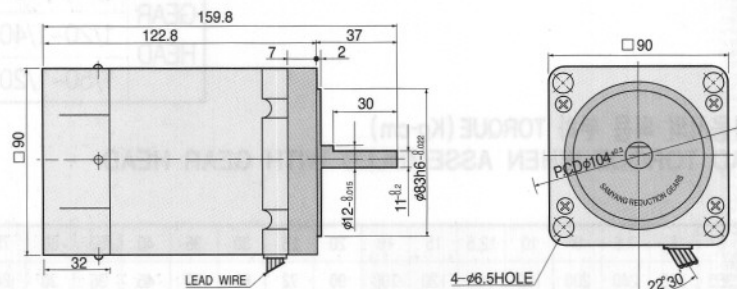


● MOTOR SPECIFICATIONS

Model	Output	Input			Mag. Poles	Run Duty	Ratings				Start Torque		Condenser
		Volt	Phase	Freq.			Current	Speed	Torque		Kg-cm	N-m	
	Watt	V		Hz	Amp	rpm			Kg-cm	N-m			
SM9R60GA	60	110	1Ø	60	4	30	1.38	1600	4.64	0.454	4.44	0.435	19.0
SM9R60GB	60	220	1Ø	60	4	30	0.79	1600	5.72	0.560	4.68	0.458	5.0
SM9R60GC	60	100	1Ø	50	4	Cont.	1.36	1300	4.92	0.482	4.72	0.462	23.0
				60			1.63	1600	3.64	0.356	4.80	0.470	
SM9R60GE	60	115	1Ø	60	4	30	1.29	1600	4.60	0.451	4.40	0.431	17.0

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
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● D-CUT MOTOR

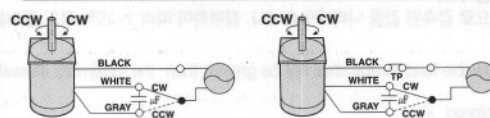


결선도 (WIRINGS)

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Directions of rotation are view at the end of motor shaft.

- 100/110V-1ø
- 200/220V-1ø
- 100/110V-1ø (TP)
- 200/220V-1ø (TP)

CW/CCW

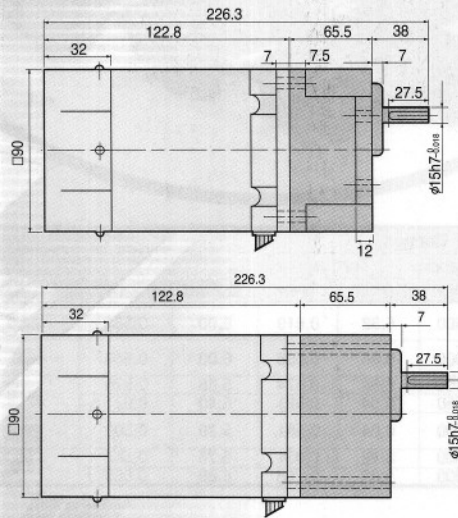


주의 : MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.

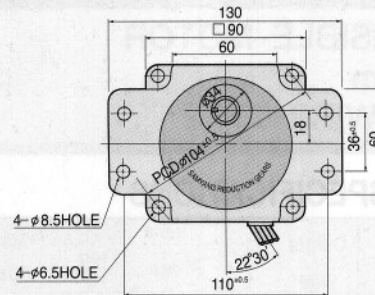
NOTICE : Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

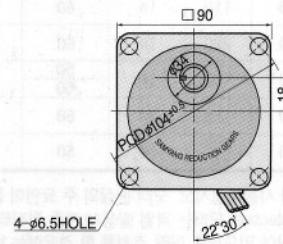
GEARED MOTOR



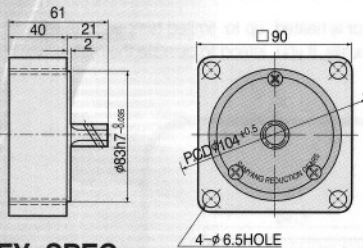
◀ HF TYPE ▶



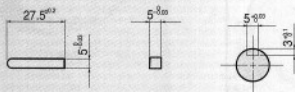
◀ H TYPE ▶



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		2.55
BOOST- IN GEAR HEAD		0.65
GEAR HEAD	1/3~1/10	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	8.6	10.3	14.3	17.1	21.4	25.7	28.6	31.7	38.0	45.6	50.6	56.8	68.2	81.8	90.9	114	136	156	187	200	200	200	200	200
	N-m	0.84	1.01	1.40	1.68	2.10	2.52	2.80	3.10	3.72	4.47	4.96	5.57	6.7	8.0	8.9	11.1	13.4	15.3	18.3	19.6	19.6	19.6	19.6	19.6

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	10.3	12.3	17.1	20.6	25.7	30.9	34.3	38.0	45.6	54.7	60.8	68.2	81.8	98.2	109	136	164	187	200	200	200	200	200	200
	N-m	1.01	1.21	1.68	2.02	2.52	3.02	3.36	3.72	4.47	5.36	5.96	6.68	8.0	9.6	10.7	13.4	16.0	18.3	19.6	19.6	19.6	19.6	19.6	19.6

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실제로에 따라 1~20% 정도 줄어들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

90W

REVERSIBLE MOTOR

□90mm

LEAD WIRE TYPE

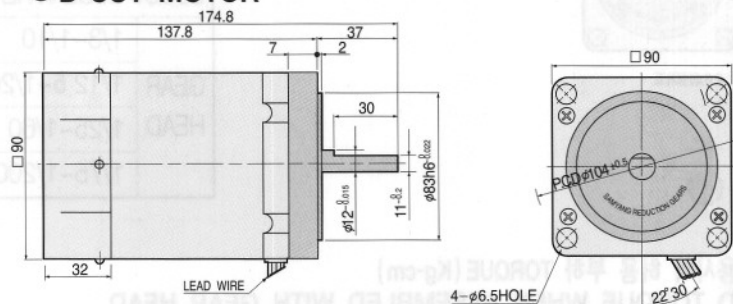


● MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μF)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9R90GA	90	110	1ø	60	4	30	1.72	1600	6.32	0.619	6.00	0.588	24.0
SM9R90GB	90	220	1ø	60	4	30	0.86	1600	6.08	0.596	6.00	0.588	6.0
SM9R90GC	90	100	1ø	50	4	Cont.	1.81	1300	6.88	0.674	5.88	0.576	30.0
				60			2.09	1550	6.04	0.591	6.40	0.627	
SM9R90GE	90	115	1ø	60	4	30	1.54	1600	6.04	0.591	5.20	0.509	20.0
SM9R90GX	90	220	1ø	50	4	Cont.	0.84	1300	8.48	0.831	5.76	0.564	6.0
		240					0.92	1300	9.88	0.968	6.80	0.666	

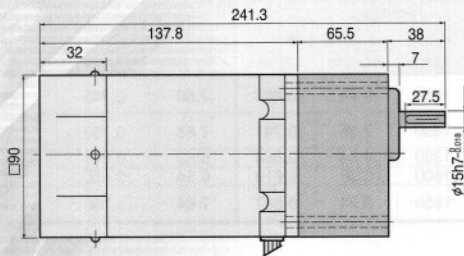
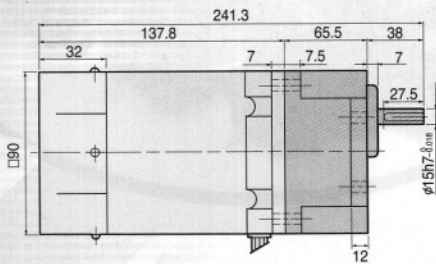
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications, Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR

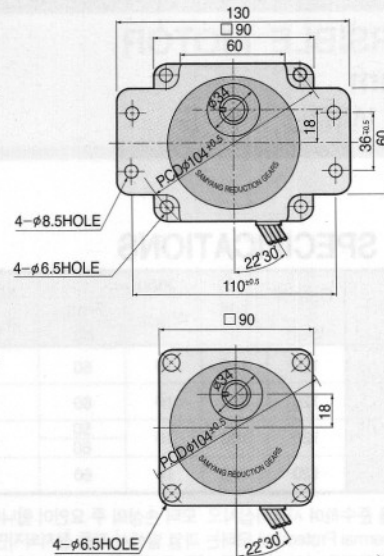


DIMENSIONS

● GEARED MOTOR

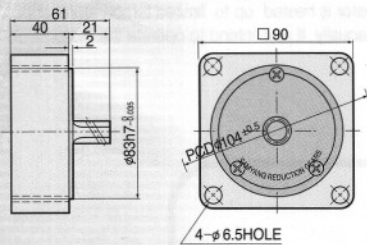


◀ HF TYPE ▶

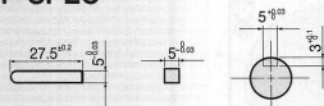


◀ H TYPE ▶

● BOOST-IN GEAR HEAD



● KEY SPEC



● **WEIGHT**

PART		WEIGHT(kg)
MOTOR		3.10
BOOST- IN GEAR HEAD		0.65
GEAR HEAD	1/3~1/10	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

[illegible]

50Hz

[illegible]

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed/filled in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually

120W

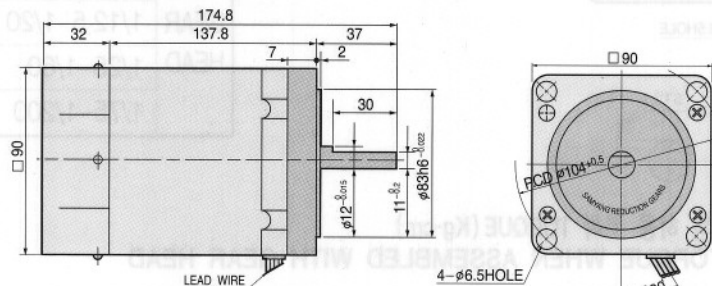
REVERSIBLE MOTOR
90mm
LEAD WIRE TYPE


● MOTOR SPECIFICATIONS

Model	Output Watt	Input Volt V	Input Phase	Input Freq. Hz	Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
							Current Amp	Speed rpm	Torque Kg-cm N-m		Kg-cm	N-m	
SM9R120GA	120	110	1 ϕ	60	4	30	2.17	1550	8.24	0.807	7.60	0.745	28.0
SM9R120GB	120	220	1 ϕ	60	4	30	1.01	1600	7.56	0.741	7.68	0.752	7.0
SM9R120GC	120	100	1 ϕ	50	4	Cont.	2.24	1300	9.84	0.964	6.60	0.647	35.0
				60			2.46	1600	8.36	0.819	6.64	0.650	
SM9R120GE	120	115	1 ϕ	60	4	30	1.96	1550	8.24	0.807	7.04	0.690	25.0

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR

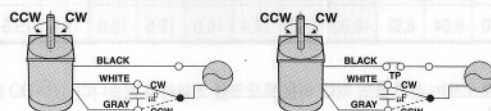


결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 100/110V-1 ϕ (TP)
- 200/220V-1 ϕ
- 200/220V-1 ϕ (TP)

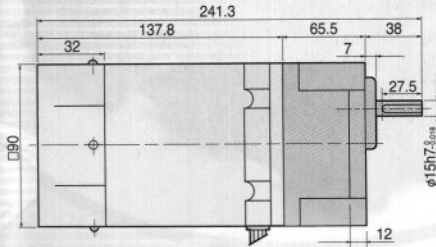
CW/CCW



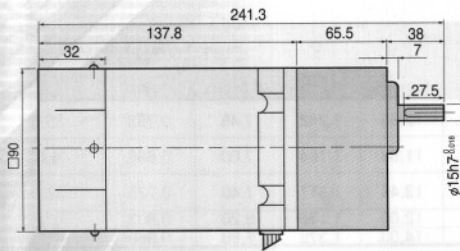
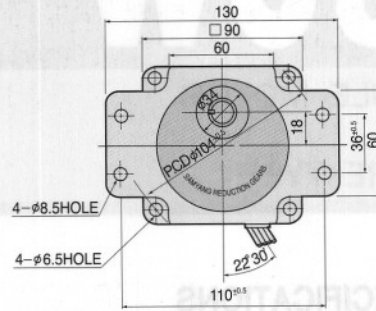
- 주의 :** MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.
- NOTICE :** Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

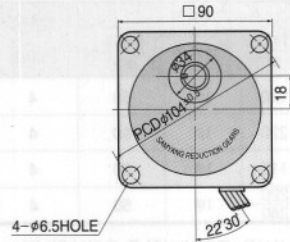
GEARED MOTOR



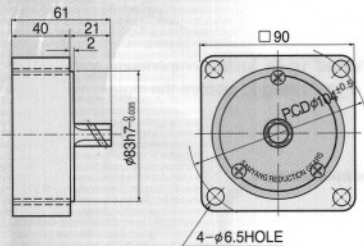
◀ HF TYPE ▶



◀ H TYPE ▶



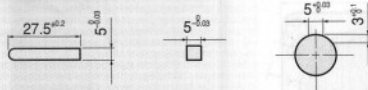
BOOST-IN GEAR HEAD (BST 90H 10)



WEIGHT

PART		WEIGHT(kg)
MOTOR		3.00
BOOST- IN GEAR HEAD		0.65
GEAR HEAD	1/3~1/10	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

KEY SPEC



GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□H	kg-cm	17.1	20.6	28.6	34.3	42.9	51.4	57.1	63.3	76.0	91.2	101	114	136	164	182	200	200	200	200	200	200	200	200	200
	N-m	1.68	2.02	2.80	3.36	4.20	5.04	5.60	6.20	7.45	8.93	9.93	11.1	13.4	16.0	17.8	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□H	kg-cm	20.6	24.7	34.3	41.1	51.4	61.7	68.6	76.0	91.2	109	122	136	164	196	200	200	200	200	200	200	200	200	200	200
	N-m	2.02	2.42	3.36	4.03	5.04	6.05	6.72	7.45	8.93	10.7	11.9	13.4	16.0	19.2	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

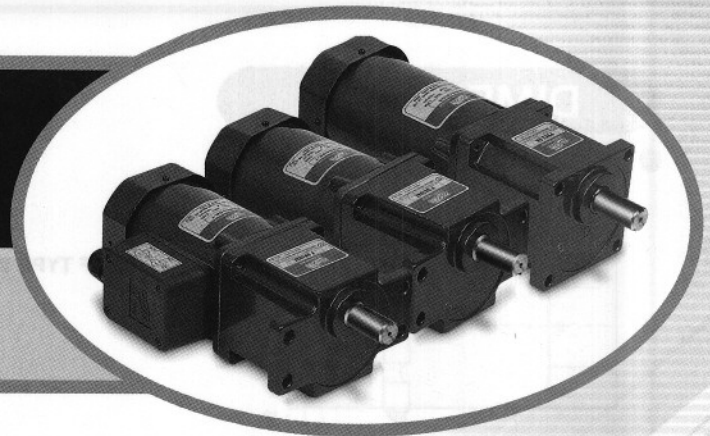
- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

180W

REVERSIBLE MOTOR

□90mm

LEAD WIRE TYPE

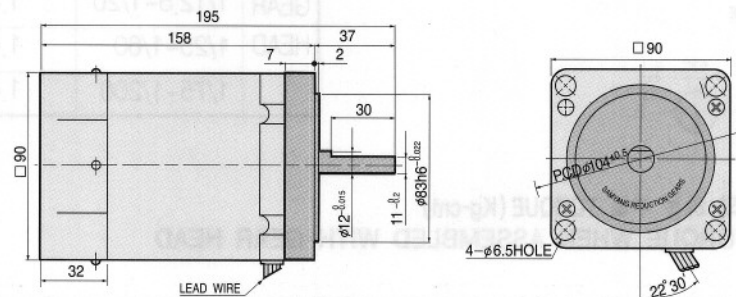


● MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9R180GA	180	110	1 ϕ	60	4	30	2.87	1600	12.68	1.242	7.48	0.733	35.0
SM9R180GB	180	220	1 ϕ	60	4	30	1.38	1600	11.88	1.164	7.00	0.686	8.0
SM9R180GE	180	115	1 ϕ	60	4	30	2.98	1600	13.44	1.317	7.40	0.725	32.0
SM9R180GX	180	220	1 ϕ	50	4	-	1.17	1300	12.00	1.176	8.20	0.803	8.0
		240				Cont.	1.25	1300	14.00	1.376	9.80	0.960	

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR

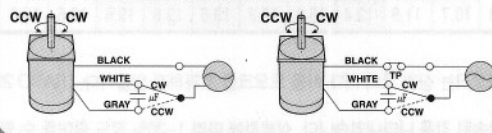


결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1 ϕ
- 100/110V-1 ϕ (TP)
- 200/220V-1 ϕ
- 200/220V-1 ϕ (TP)

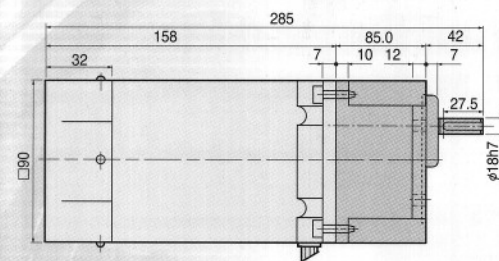
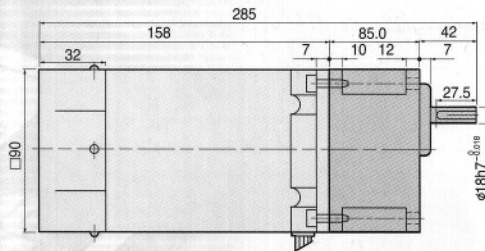
CW/CCW



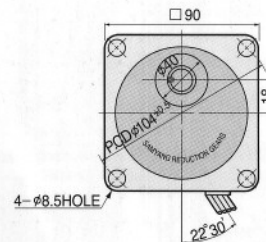
- 주의 :** MOTOR 결선의 전환은 MOTOR가 완전히 정지한 후에 하십시오.
MOTOR가 회전 중에 결선이 전환될 경우에는 정상작동이 안될 수 있습니다.
- NOTICE :** Do not switch the direction of rotation before it fully stops rotating.
Switching wires during rotating may cause damage of system/motor.

DIMENSIONS

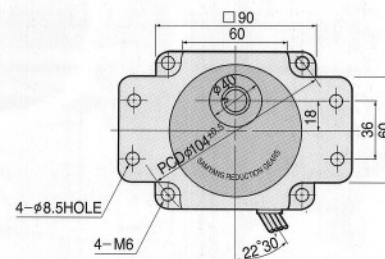
● GEARED MOTOR



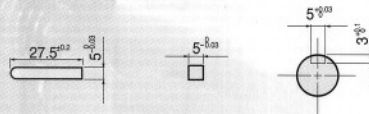
◀ K TYPE ▶



◀ KF TYPE ▶



● KEY SPEC



● **WEIGHT**

PART		WEIGHT(kg)
MOTOR		3.80
GEAR HEAD	1/3~1/10	1.70
	1/12.5~1/20	1.83
	1/25~1/200	1.93
	1/75~1/200	1.98

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

[illegible]

50Hz

[illegible]

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과).
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

DIMENSIONS



ELECTRO MAGNETIC BRAKE MOTOR



6W

ELECTRO MAGNETIC BRAKE MOTOR

60mm

LEAD WIRE TYPE

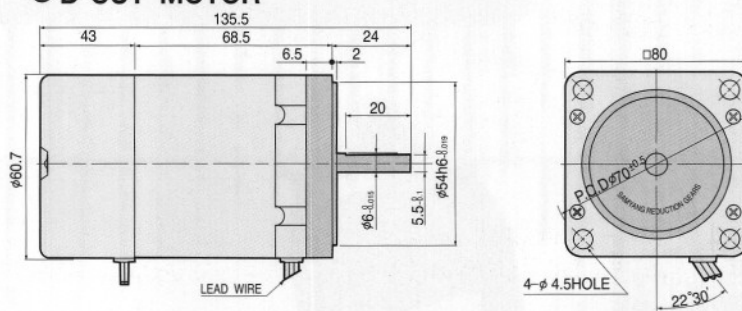


● MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt	Phase	Freq. Hz			Current Amp	Speed rpm	Torque				
		V							Kg-cm	N-m			
SM6R06GB-E	6	220	1Ø	60	4	30	0.12	1550	0.42	0.041	0.71	0.069	0.8

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR



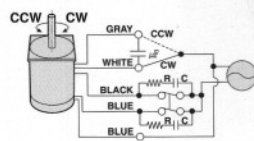
결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

• 100/110V-1ø • 200/220V-1ø

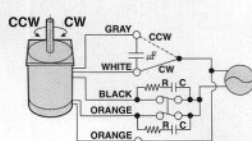
- 100/110V-1Ø

CW/CCW

 $R=10\sim 100\ \Omega$ $C=0.1\sim 0.50\mu F$

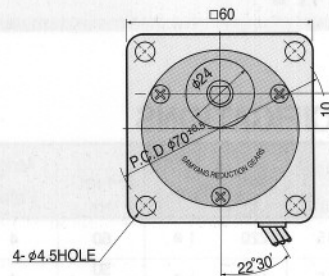
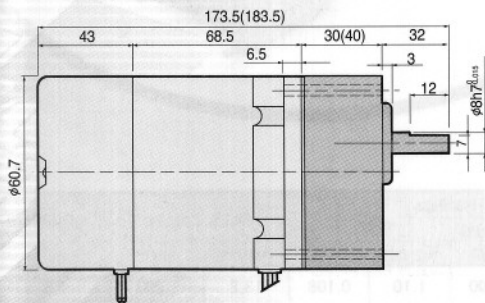
- 200/220V-1ø

CW/CCW

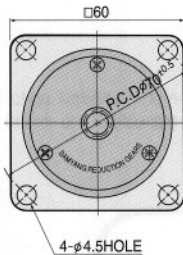
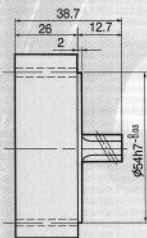


DIMENSIONS

● GEARED MOTOR



● BOOST-IN GEAR HEAD



● WEIGHT

PART		WEIGHT(kg)
MOTOR		0.95
BOOST-IN GEAR HEAD		0.18
GEAR HEAD	1/3 ~ 1/18	0.25
	1/20 ~ 1/40	0.30
	1/50 ~1/200	0.33

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P6D□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	0.9	1.0	1.4	1.7	2.1	2.6	2.9	3.6	4.3	5.1	5.1	6.3	7.6	9.1	10.1	11.4	13.6	17.0	20.5	22.7	27.3	30.0	30.0	30.0
	N-m	0.08	0.10	0.14	0.17	0.21	0.25	0.28	0.35	0.42	0.50	0.50	0.62	0.74	0.89	0.99	1.11	1.34	1.67	2.00	2.67	2.67	2.94	2.94	2.94

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P6D□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	1.0	1.2	1.7	2.1	2.6	3.1	3.4	4.3	5.1	6.2	6.1	7.6	9.1	10.9	12.2	13.6	16.4	20.5	24.5	27.3	30.0	30.0	30.0	30.0
	N-m	0.10	0.12	0.17	0.20	0.25	0.30	0.34	0.42	0.50	0.60	0.60	0.74	0.89	1.07	1.19	1.34	1.60	2.00	2.41	2.67	2.94	2.94	2.94	2.94

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- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

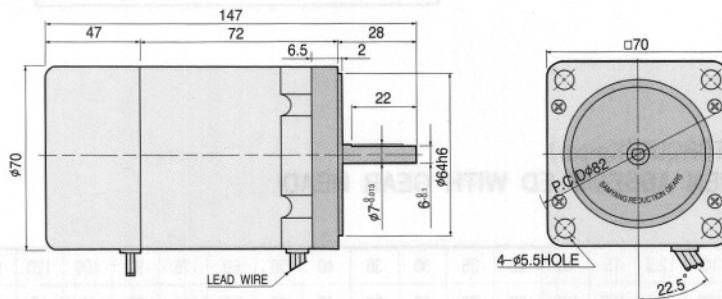
15W**ELECTRO MAGNETIC BRAKE MOTOR**

□70mm

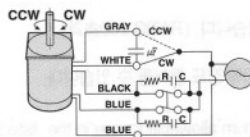
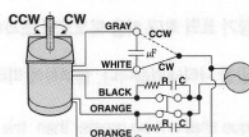
LEAD WIRE TYPE**● MOTOR SPECIFICATIONS**

Model	Output Watt	Input Volt V	Phase	Freq. Hz	Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
							Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM7R15GB-E	15	220	1 ϕ	60	4	30	0.21	1600	1.10	0.108	13.2	1.293	1.5
SM7R15GC-E	15	100	1 ϕ	50	4	Cont.	0.38	1250	1.20	0.117	11.5	1.127	6.0
				60		-	0.40	1600	0.92	0.090	12.0	1.176	
SM7R15GX-E	15	220	1 ϕ	50	4	-	0.17	1300	1.14	0.111	1.21	0.118	1.3
		240				Cont.	0.19	1300	1.35	0.106	1.45	0.142	

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
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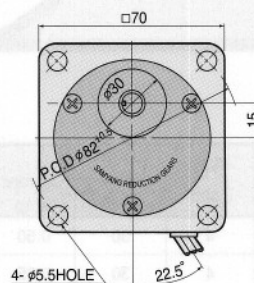
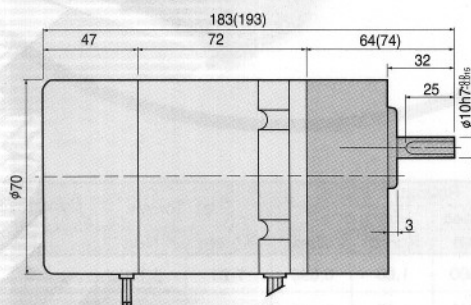
● D-CUT MOTOR**결선도 (WIRINGS)**

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

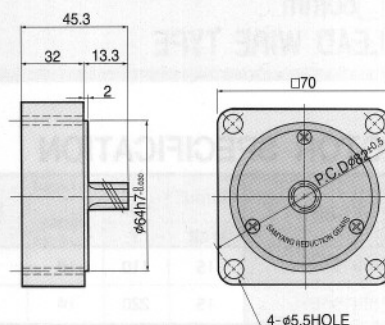
• 100/110V-1 ϕ **CW/CCW**• 200/220V-1 ϕ **CW/CCW**R=10~100 Ω C=0.1~0.50 μ F

DIMENSIONS

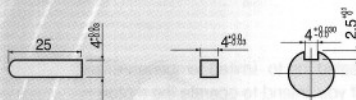
● GEARED MOTOR



● BOOST-IN GEAR HEAD



● KEY SPEC



● WEIGHT

PART		WEIGHT(kg)
MOTOR		1.46
BOOST-IN GEAR HEAD		0.35
GEAR HEAD	1/3 ~ 1/18	0.36
	1/20 ~ 1/40	0.45
	1/50 ~ 1/200	0.5

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P7K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	2.1	2.6	3.6	4.3	5.4	6.4	7.1	8.9	10.7	12.9	12.7	15.8	19.0	22.8	25.3	28.4	34.1	42.6	51.1	56.8	60.0	60.0	60.0	60.0
	N-m	0.21	0.25	0.35	0.42	0.52	0.63	0.70	0.87	1.05	1.26	1.24	1.55	1.86	2.23	2.48	2.78	3.34	4.18	5.01	5.57	5.88	5.88	5.88	5.88

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P7K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	2.6	3.1	4.3	5.1	6.4	7.7	8.6	10.7	12.9	15.4	15.2	19.0	22.8	27.3	30.4	34.1	40.9	51.1	60.0	60.0	60.0	60.0	60.0	60.0
	N-m	0.25	0.30	0.42	0.50	0.63	0.76	0.84	1.05	1.26	1.51	1.49	1.86	2.23	2.68	2.98	3.34	4.01	5.01	5.88	5.88	5.88	5.88	5.88	5.88

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- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

80mm

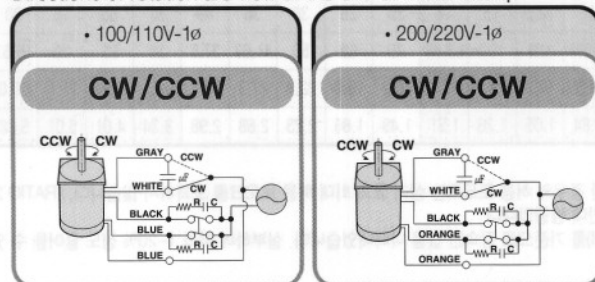
LEAD WIRE TYPE



Model	Output	Input			Mag. Poles	Run Duty	Ratings				Start Torque		Condenser
		Volt	Phase	Freq. Hz			Current	Speed	Torque				
	Watt	V			min	Amp	rpm	Kg-cm	N-m	Kg-cm	N-m	(uF)	
SM8R15GA-E	15	110	1Ø	60	4	30	0.50	1600	1.00	0.098	1.20	0.118	5.0
SM8R15GB-E	15	220	1Ø	60	4	30	0.25	1600	1.10	0.108	1.30	0.128	1.5

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
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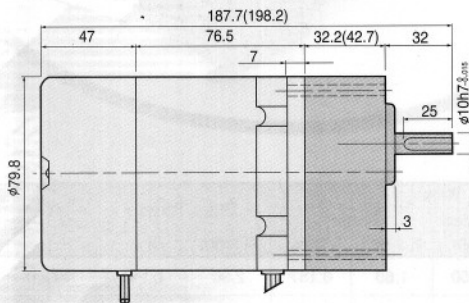
회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.



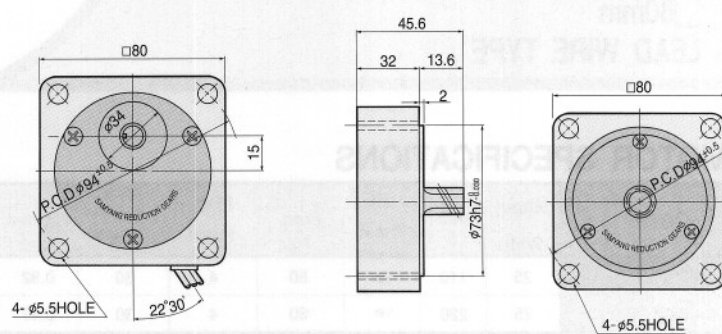
C=0.1~0.50 μ F

DIMENSIONS

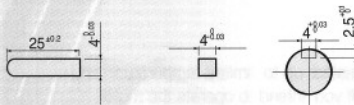
● GEARED MOTOR



● BOOST-IN GEAR HEAD



● KEY SPEC



● WEIGHT

PART		WEIGHT(kg)
MOTOR		1.85
BOOST-IN GEAR HEAD		0.43
GEAR HEAD	1/3 ~ 1/18	0.43
	1/20 ~ 1/40	0.57
	1/50 ~ 1/200	0.60

● GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	2.1	2.6	3.6	4.3	5.4	6.4	7.1	8.9	10.7	12.9	12.7	15.8	19.0	22.8	25.3	28.4	34.1	42.6	51.1	56.8	68.2	80.0	80.0	80.0
	N-m	0.21	0.25	0.35	0.42	0.52	0.63	0.70	0.87	1.05	1.26	1.24	1.55	1.86	2.23	2.48	2.78	3.34	4.18	5.01	5.57	6.68	7.84	7.84	7.84

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	2.6	3.1	4.3	5.1	6.4	7.7	8.6	10.7	12.9	15.4	15.2	19.0	22.8	27.3	30.4	34.1	40.9	51.1	61.4	68.2	80.0	80.0	80.0	80.0
	N-m	0.25	0.30	0.42	0.50	0.63	0.76	0.84	1.05	1.26	1.51	1.49	1.86	2.23	2.68	2.98	3.34	4.01	5.01	6.01	6.68	7.84	7.84	7.84	7.84

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- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM, It may be reduced 1 ~ 20% dependent on the load applied actually.

25W

ELECTRO MAGNETIC BRAKE MOTOR

80mm

LEAD WIRE TYPE

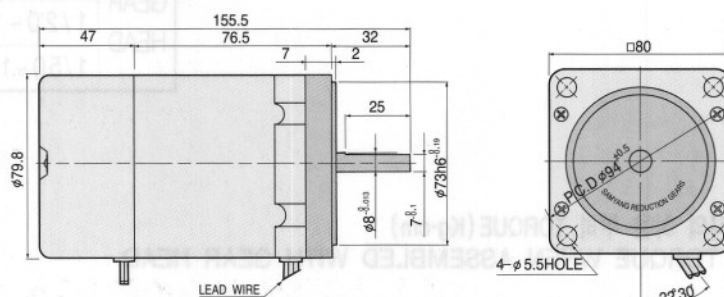


● MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μF)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque				
		Kg-cm							N-m				
SM8R25GA-E	25	110	1ø	60	4	30	0.92	1550	1.60	0.157	2.90	0.284	12.0
SM8R25GB-E	25	220	1ø	60	4	30	0.47	1550	1.65	0.162	3.10	0.304	3.0

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR



결선도 (WIRINGS)

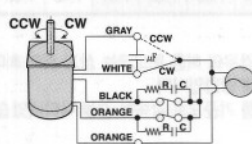
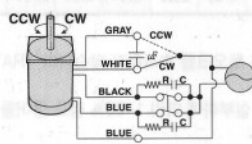
회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

- 100/110V-1ø

- 200/220V-1ø

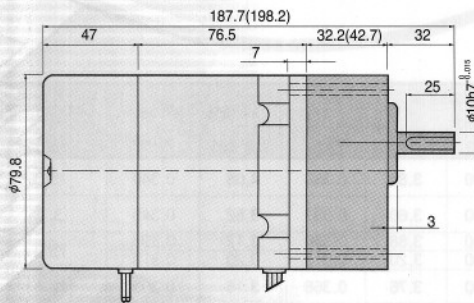
CW/CCW

CW/CCW

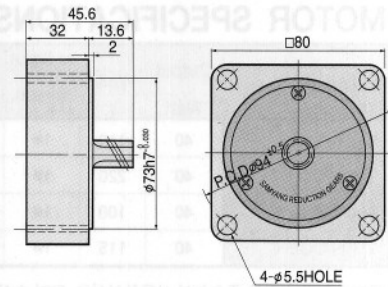
 $R=10\sim 100\ \Omega$ $C=0.1\sim0.50\mu F$

DIMENSIONS

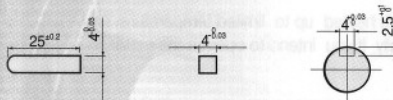
GEARED MOTOR



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		1.90
BOOST-IN GEAR HEAD		0.43
GEAR HEAD	1/3 ~ 1/18	0.43
	1/20 ~ 1/40	0.57
	1/50 ~ 1/200	0.60

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	3.6	4.3	6.0	7.1	8.9	10.7	11.9	14.9	17.9	21.4	21.1	26.4	31.7	38.0	42.2	47.3	56.8	71.0	80.0	80.0	80.0	80.0	80.0	80.0
	N-m	0.35	0.42	0.58	0.70	0.87	1.05	1.17	1.46	1.75	2.10	2.07	2.59	3.10	3.72	4.14	4.64	5.57	6.96	7.84	7.84	7.84	7.84	7.84	7.84

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P8K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	4.3	5.1	7.1	8.6	10.7	12.9	14.3	17.9	21.4	25.7	25.3	31.7	38.0	45.6	50.6	56.8	68.2	80.0	80.0	80.0	80.0	80.0	80.0	80.0
	N-m	0.42	0.50	0.70	0.84	1.05	1.26	1.40	1.75	2.10	2.52	2.48	3.10	3.72	4.47	4.96	5.57	6.68	7.84	7.84	7.84	7.84	7.84	7.84	7.84

- 모델명 내의 □위치에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

40W

ELECTRO MAGNETIC BRAKE MOTOR

□90mm

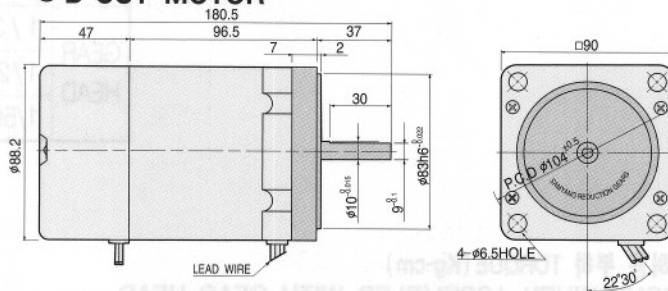
LEAD WIRE TYPE

● MOTOR SPECIFICATIONS

Model	Output Watt	Input Volt V	Phase	Freq. Hz	Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
							Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9R40GA-E	40	110	1 ϕ	60	4	30	1.11	1600	3.88	0.380	4.08	0.340	15.0
SM9R40GB-E	40	220	1 ϕ	60	4	30	0.52	1600	3.60	0.353	3.52	0.345	3.7
SM9R40GC-E	40	100	1 ϕ	50	4	Cont.	0.57	1300	3.88	0.380	3.12	0.305	15.0
				60			0.68	1600	3.20	0.313	3.20	0.313	
SM9R40GE-E	40	115	1 ϕ	60	4	30	0.94	1600	3.76	0.368	3.16	0.309	12.0

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원을 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

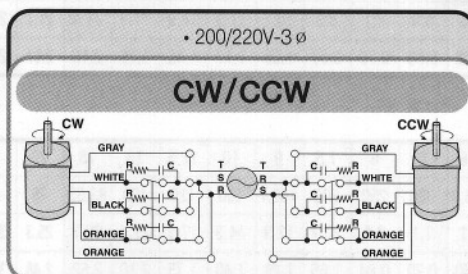
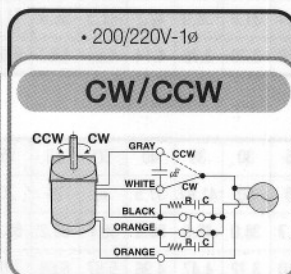
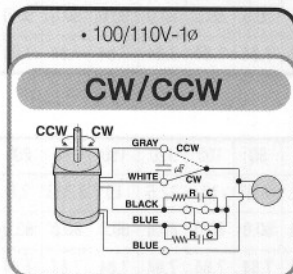
● D-CUT MOTOR



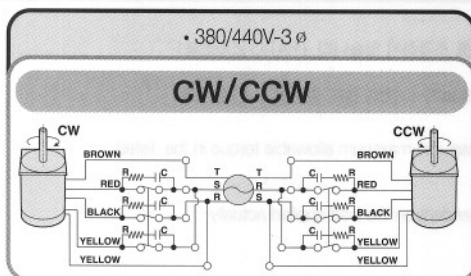
결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.

Directions of rotation are view at the end of motor shaft.



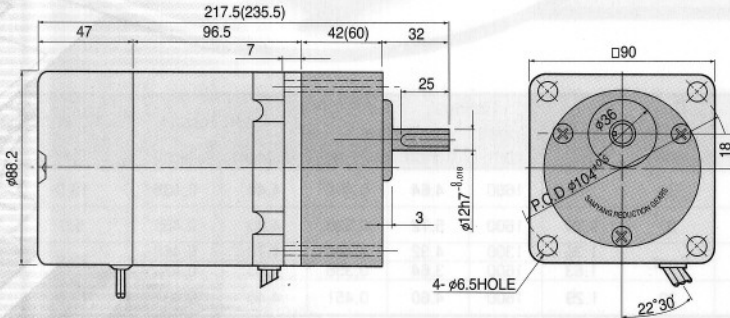
$R=10\sim 100\ \Omega$
 $C=0.1\sim 0.50\ \mu F$



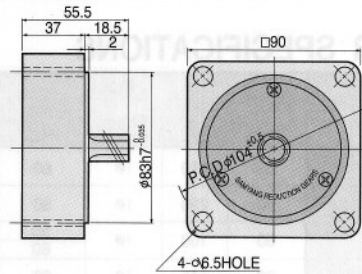
$R=10\sim 200\ \Omega$
 $C=0.1\sim 0.50\ \mu F$

DIMENSIONS

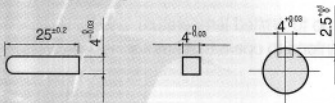
GEARED MOTOR



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		2.75
BOOST-IN GEAR HEAD		0.60
GEAR HEAD	1/3 ~ 1/18	0.75
	1/20 ~ 1/40	1.05
	1/50 ~ 1/200	1.15

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm) ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□L	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	5.7	6.9	9.5	11.4	14.3	17.1	19.0	23.8	28.6	34.3	33.8	42.2	50.6	60.8	67.5	75.8	90.9	100	100	100	100	100	100	100
	N-m	0.56	0.67	0.93	1.12	1.40	1.68	1.87	2.33	2.80	3.36	3.31	4.14	4.96	5.96	6.62	7.42	8.91	9.80	9.80	9.80	9.80	9.80	9.80	9.80

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□L	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	6.9	8.2	11.4	13.7	17.1	20.6	22.9	28.6	34.3	41.1	40.5	50.6	60.8	72.9	81.0	90.9	100	100	100	100	100	100	100	100
	N-m	0.67	0.81	1.12	1.34	1.68	2.02	2.24	2.80	3.36	4.03	3.97	4.96	5.96	7.15	7.94	8.91	9.80	9.80	9.80	9.80	9.80	9.80	9.80	9.80

- 모델명 내의 □위치에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(X10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실제로 따라 1~20% 정도 줄어들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM, It may be reduced 1 ~ 20% dependent on the load applied actually.

60W

ELECTRO MAGNETIC BRAKE MOTOR

□ 90mm

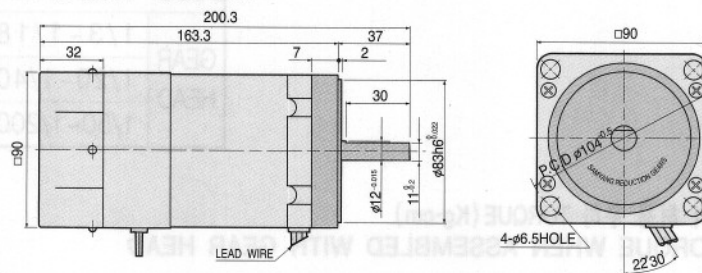
LEAD WIRE TYPE

● MOTOR SPECIFICATIONS

Model	Output	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
	Watt	Kg-cm			N-m								
SM9R60GA-E	60	110	1 $\emptyset$	60	4	30	1.38	1600	4.64	0.454	4.44	0.435	19.0
SM9R60GB-E	60	220	1 $\emptyset$	60	4	30	0.79	1600	5.72	0.560	4.68	0.458	5.0
SM9R60GC-E	60	100	1 $\emptyset$	50	4	Cont.	1.36	1300	4.92	0.482	4.72	0.462	23.0
				60			1.63	1600	3.64	0.356	4.80	0.470	
SM9R60GE-E	60	115	1 $\emptyset$	60	4	30	1.29	1600	4.60	0.451	4.40	0.431	17.0

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
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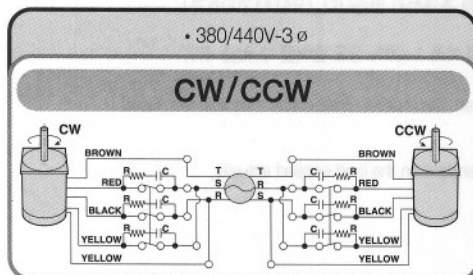
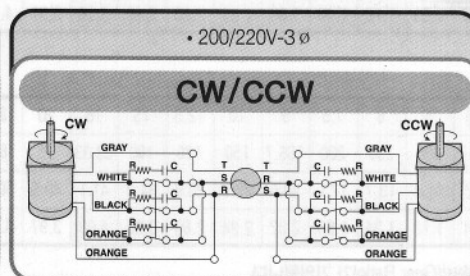
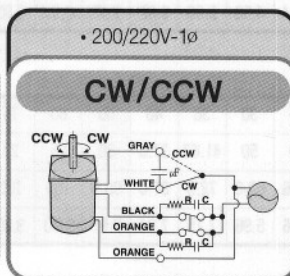
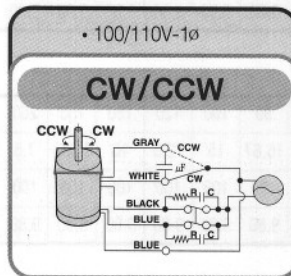
● D-CUT MOTOR



결선도 (WIRINGS)

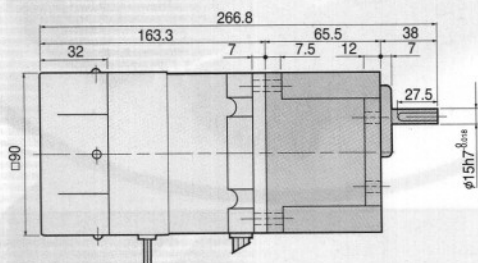
회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.

Directions of rotation are view at the end of motor shaft.

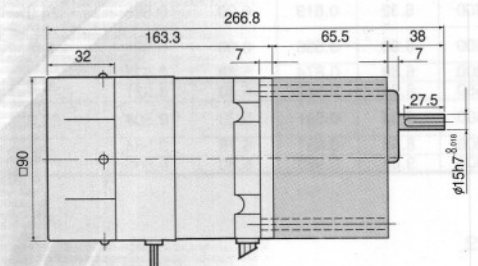
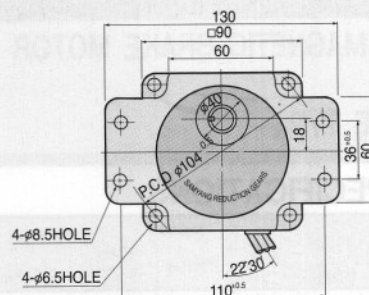
R=10~200 Ω C=0.1~0.50 μ FR=10~100 Ω C=0.1~0.50 μ F

DIMENSIONS

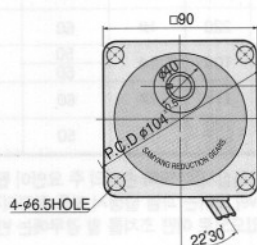
GEARED MOTOR



◀ HF TYPE ▶

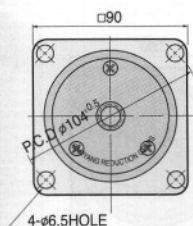
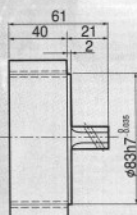


◀ H TYPE ▶

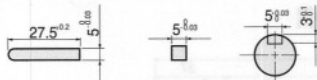


WEIGHT

BOOST-IN GEAR HEAD



KEY SPEC



PART		WEIGHT(kg)
MOTOR		2.90
BOOST-IN GEAR HEAD		0.65
GEAR HEAD	1 / 3 ~1 / 1 0	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm) ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□H	kg-cm	8.6	10.3	14.3	17.1	21.4	25.7	28.6	31.7	38.0	45.6	50.6	56.8	68.2	81.8	90.9	114	136	156	187	200	200	200	200	200
	N-m	0.84	1.01	1.40	1.68	2.10	2.52	2.80	3.10	3.72	4.47	4.96	5.57	6.7	8.0	8.9	11.1	13.4	15.3	18.3	19.6	19.6	19.6	19.6	19.6

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□H	kg-cm	10.3	12.3	17.1	20.6	25.7	30.9	34.3	38.0	45.6	54.7	60.8	68.2	81.8	98.2	109	136	164	187	200	200	200	200	200	200
	N-m	1.01	1.21	1.68	2.02	2.52	3.02	3.36	3.72	4.47	5.36	5.96	6.68	8.0	9.6	10.7	13.4	16.0	18.3	19.6	19.6	19.6	19.6	19.6	19.6

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

90W

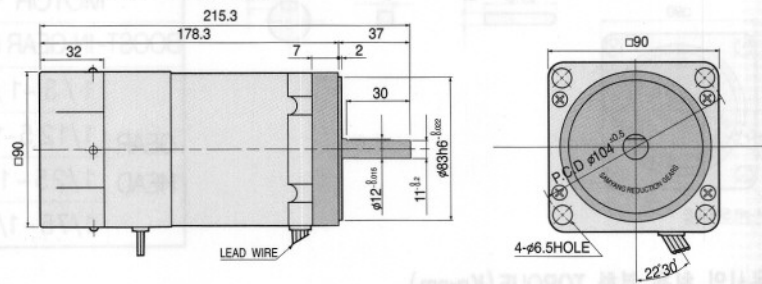
ELECTRO MAGNETIC BRAKE MOTOR

□90mm

LEAD WIRE TYPE**● MOTOR SPECIFICATIONS**

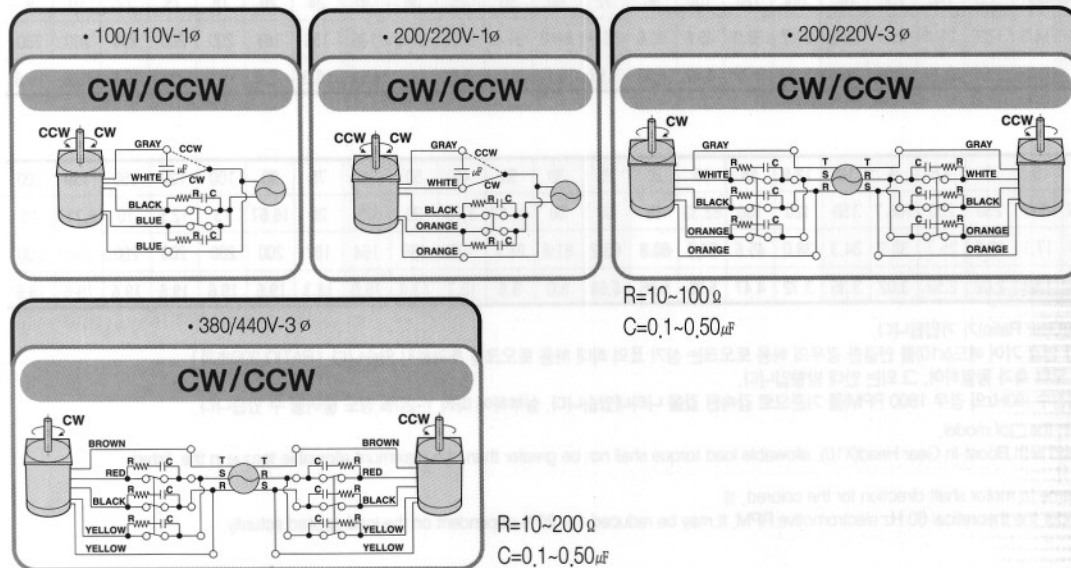
Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9R90GA-E	90	110	1 ϕ	60	4	30	1.72	1600	6.32	0.619	6.00	0.588	24.0
SM9R90GB-E	90	220	1 ϕ	60	4	30	0.86	1600	6.08	0.596	6.00	0.588	6.0
SM9R90GC-E	90	100	1 ϕ	50	4	Cont.	1.81	1300	6.88	0.674	5.88	0.576	30.0
				60			2.09	1550	6.04	0.591	6.40	0.627	
SM9R90GE-E	90	115	1 ϕ	60	4	30	1.54	1600	6.04	0.591	5.20	0.509	20.0
SM9R90GX-E	90	220	1 ϕ	50	4	Cont.	0.84	1300	8.48	0.831	5.76	0.564	6.0
		240					0.92	1300	9.88	0.968	6.80	0.666	

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다.
그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR**결선도 (WIRINGS)**

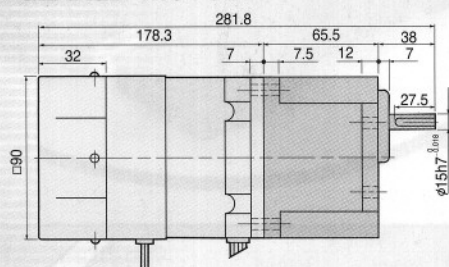
회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.

Directions of rotation are view at the end of motor shaft.

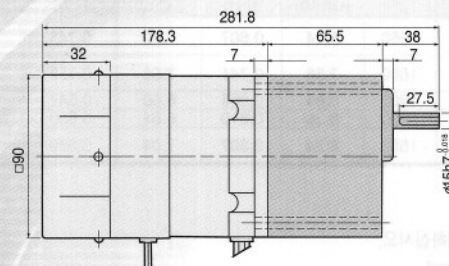
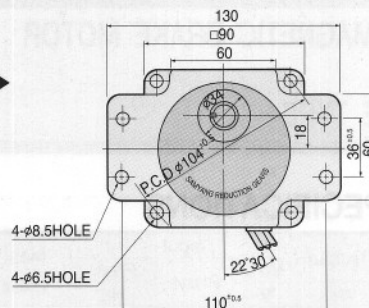


DIMENSIONS

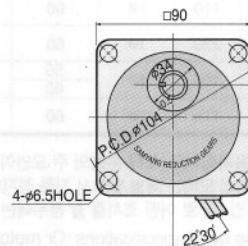
GEARED MOTOR



◀ HF TYPE ▶



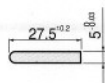
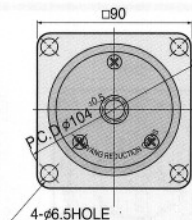
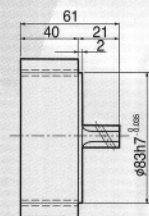
◀ H TYPE ▶



BOOST-IN GEAR HEAD

KEY SPEC

WEIGHT



PART		WEIGHT(kg)
MOTOR		3.45
BOOST-IN GEAR HEAD		0.65
GEAR HEAD	1/3~1/10	1.20
	1/12.5~1/20	1.30
	1/25~1/60	1.40
	1/75~1/200	1.45

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□H	kg-cm	12.9	15.4	21.4	25.7	32.1	38.6	42.9	47.5	57.0	68.4	76.0	85.2	102	123	136	170	200	200	200	200	200	200	200	200
	N-m	1.26	1.51	2.10	2.52	3.15	3.78	4.20	4.65	5.58	6.70	7.45	8.35	10.0	12.0	13.4	16.7	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

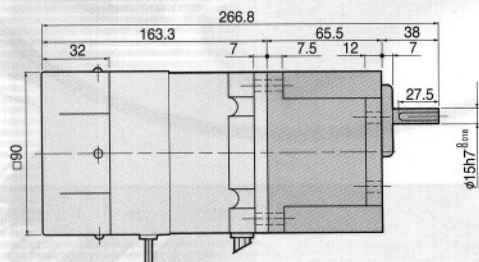
50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□H	kg-cm	15.4	18.5	25.7	30.9	38.6	46.3	51.4	57.0	68.4	82.0	91.2	102	123	147	164	200	200	200	200	200	200	200	200	200
	N-m	1.51	1.81	2.52	3.02	3.78	4.54	5.04	5.58	6.70	8.04	8.93	10.02	12.0	14.4	16.0	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

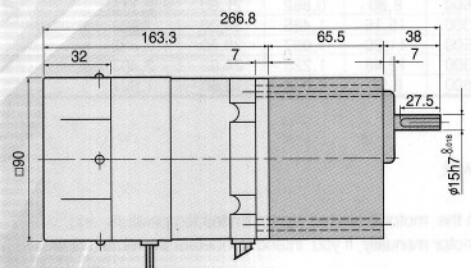
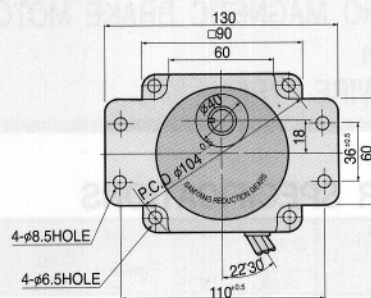
- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM, it may be reduced 1 ~ 20% dependent on the load applied actually.

DIMENSIONS

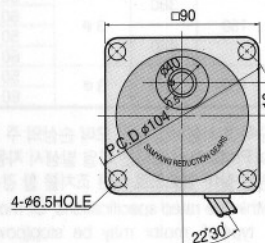
GEARED MOTOR



◀ HF TYPE ▶

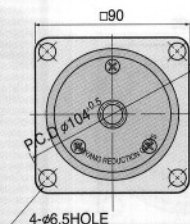
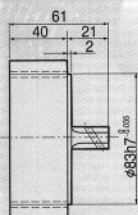


◀ H TYPE ▶

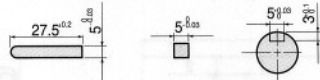


WEIGHT

BOOST-IN GEAR HEAD



KEY SPEC



PART		WEIGHT(kg)
MOTOR		3.50
BOOST-IN GEAR HEAD		0.65
GEAR HEAD	1/3 ~ 1/10	1.20
	1/12.5 ~ 1/20	1.30
	1/25 ~ 1/60	1.40
	1/75 ~ 1/200	1.45

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□H	kg-cm	17.1	20.6	28.6	34.3	42.9	51.4	57.1	63.3	76.0	91.2	101	114	136	164	182	200	200	200	200	200	200	200	200	200
	N-m	1.68	2.02	2.80	3.36	4.20	5.04	5.60	6.20	7.45	8.93	9.93	11.1	13.4	16.0	17.8	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□H	kg-cm	20.6	24.7	34.3	41.1	51.4	61.7	68.6	76.0	91.2	109	122	136	164	196	200	200	200	200	200	200	200	200	200	200
	N-m	2.02	2.42	3.36	4.03	5.04	6.05	6.72	7.45	8.93	10.7	11.9	13.4	16.0	19.2	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6	19.6

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- 기어헤드의 허용 부하 토크는 H, HF형일 때의 값이며, K, KF형일 경우에는 최대 허용 토크가 300Kg-cm까지 증가될 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM, it may be reduced 1 ~ 20% dependent on the load applied actually,

150W

ELECTRO MAGNETIC BRAKE MOTOR

□90mm

LEAD WIRE TYPE

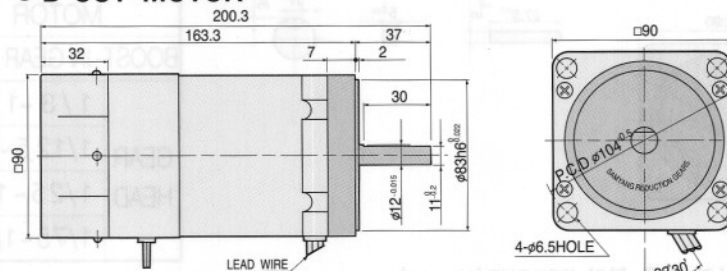


● MOTOR SPECIFICATIONS

Model	Output	Input			Mag. Poles	Run Duty	Ratings				Start Torque		Condenser
		Volt	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
	Watt	V				min			Kg-cm	N-m			
SM9N150GS-E	150	380	3 ϕ	50	4	Cont.	0.55	1300	11.48	1.125	26.16	2.563	
				60			0.44	1600	8.80	0.862	21.60	2.116	
		440		50			0.68	1300	15.16	1.485	34.00	3.332	
				60			0.51	1600	11.20	1.097	28.80	2.822	
SM9N150GT-E	150	220	3 ϕ	50	4	Cont.	1.02	1300	12.48	1.223	24.80	2.403	
				60			0.85	1600	8.96	0.878	19.60	1.921	

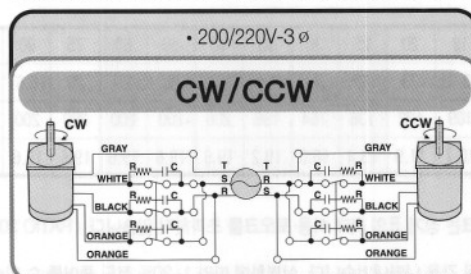
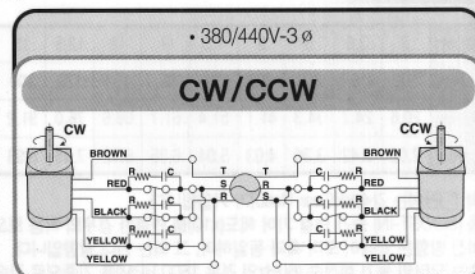
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

● D-CUT MOTOR



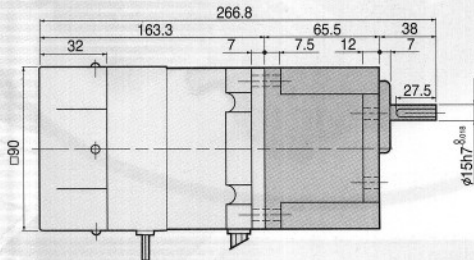
결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

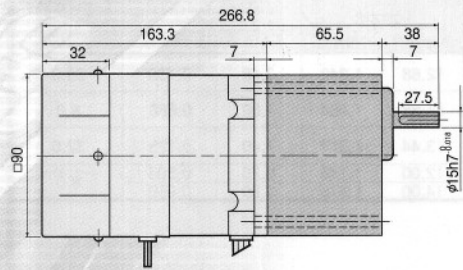
R=10~100 Ω C=0.1~0.50 μ FR=10~200 Ω C=0.1~0.50 μ F

DIMENSIONS

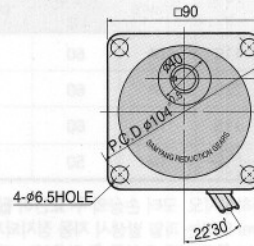
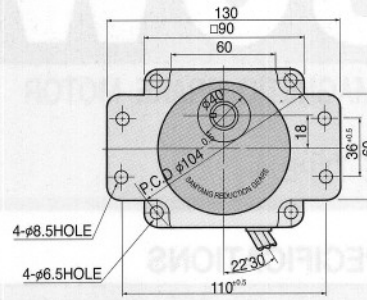
GEARED MOTOR



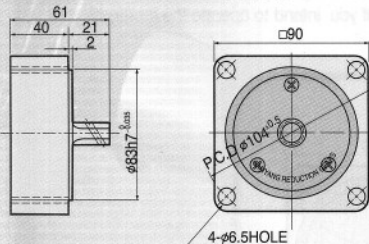
◀ HF TYPE ▶



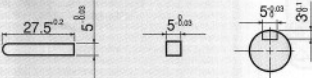
◀ H TYPE ▶



BOOST-IN GEAR HEAD



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
MOTOR		3.55
BOOST-IN GEAR HEAD		0.65
GEAR HEAD	1/3 ~ 1/10	1.20
	1/12.5 ~ 1/20	1.30
	1/25 ~ 1/60	1.40
	1/75 ~ 1/200	1.45

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF P9K□H	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	21.4	25.7	35.7	42.9	53.6	64.3	71.4	79.1	95.0	114	127	142	170	205	227	284	300	300	300	300	300	300	300	300
	N-m	2.10	2.52	3.50	4.20	5.25	6.30	7.00	7.76	9.31	11.2	12.4	13.9	16.7	20.0	22.3	27.8	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□HF P9K□H	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	25.7	30.9	42.9	51.4	64.3	77.1	85.7	95.0	114	137	152	170	205	245	273	300	300	300	300	300	300	300	300	300
	N-m	2.52	3.02	4.20	5.04	6.30	7.56	8.40	9.31	11.17	13.4	14.9	16.7	20.0	24.1	26.7	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- 기어헤드의 허용 부하 토크는 H, HF형일 때의 값이며, K, KF형일 경우에는 최대 허용 토크가 300Kg-cm까지 증가될 수 있습니다.
- Gear ratio to be typed(filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

180W

ELECTRO MAGNETIC BRAKE MOTOR

90mm

LEAD WIRE TYPE

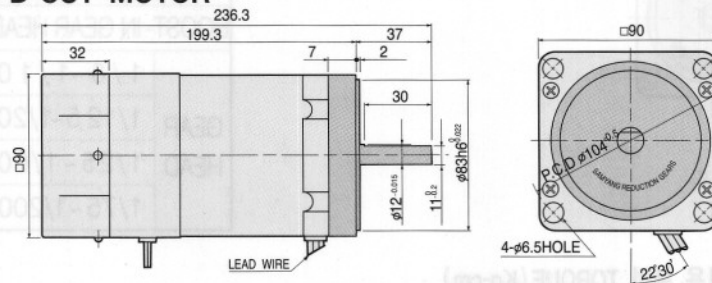


MOTOR SPECIFICATIONS

Model	Output Watt	Input			Mag. Poles	Run Duty min	Ratings				Start Torque		Condenser (μ F)
		Volt V	Phase	Freq. Hz			Current Amp	Speed rpm	Torque		Kg-cm	N-m	
SM9R180GA-E	180	110	1 ϕ	60	4	30	2.87	1600	12.68	1.242	7.48	0.733	35.0
SM9R180GB-E	180	220	1 ϕ	60	4	30	1.38	1600	11.88	1.164	7.00	0.686	8.0
SM9R180GE-E	180	115	1 ϕ	60	4	30	2.98	1600	13.44	1.317	7.40	0.725	32.0
SM9R180GX-E	180	220	1 ϕ	50	4	-	1.17	1300	12.00	1.176	8.20	0.803	8.0
		240				Cont.	1.25	1300	14.00	1.376	9.80	0.960	

- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

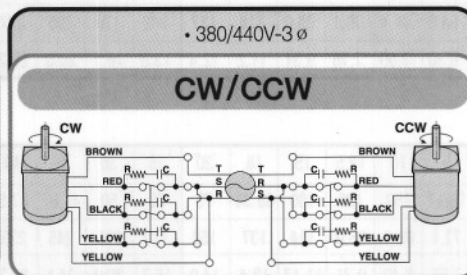
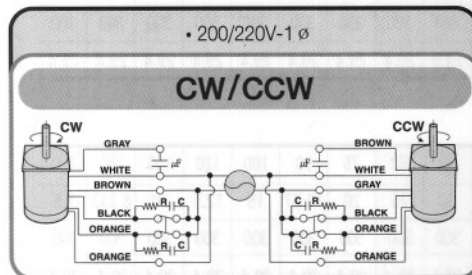
D-CUT MOTOR



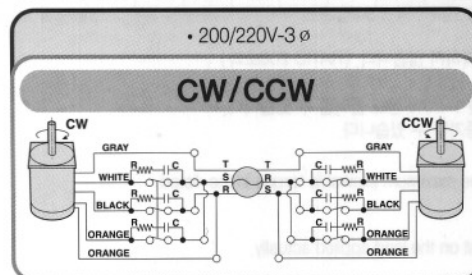
결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.

Directions of rotation are view at the end of motor shaft.



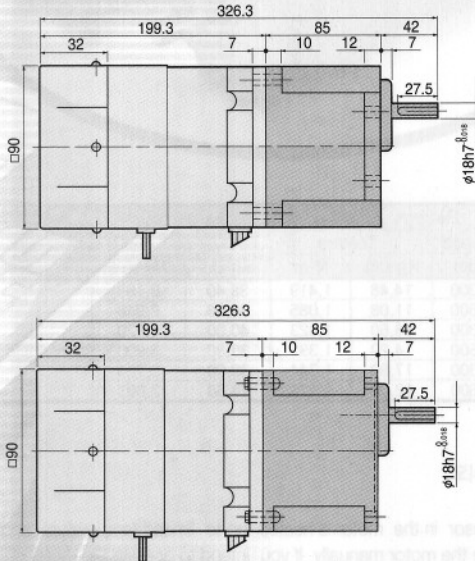
R=10~200 Ω
C=0.1~0.50 μ F



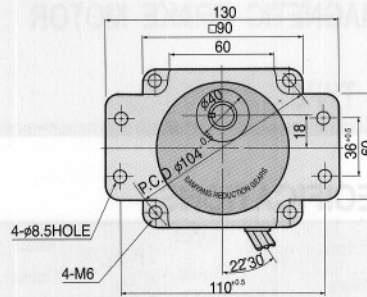
R=10~100 Ω
C=0.1~0.50 μ F

DIMENSIONS

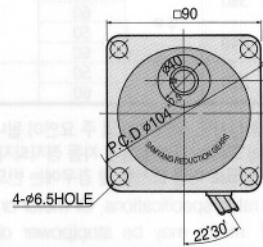
GEARED MOTOR



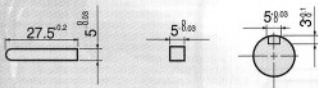
◀ KF TYPE ▶



◀ K TYPE ▶



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
GEAR HEAD	MOTOR	4.25
	1/3 ~ 1/10	1.70
	1/12.5 ~ 1/20	1.83
	1/25 ~ 1/60	1.93
	1/75 ~ 1/200	1.98

GEAR HEAD 연결 사용시의 허용 부하 TORQUE (Kg-cm)

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□KF P9K□K	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
	kg-cm	25.7	30.9	42.9	51.4	64.3	77.1	85.7	95.0	114	137	152	170	205	245	273	300	300	300	300	300	300	300	300	300
	N-m	2.52	3.02	4.20	5.04	6.30	7.56	8.40	9.31	11.17	13.4	14.9	16.7	20.0	24.1	26.7	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

50Hz

Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□KF P9K□K	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
	kg-cm	30.9	37.0	51.4	61.7	77.1	92.6	103	114	137	164	182	205	245	295	300	300	300	300	300	300	300	300	300	300
	N-m	3.02	3.63	5.04	6.05	7.56	9.07	10.1	11.2	13.40	16.1	17.9	20.0	24.1	28.9	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
- 감속비 증폭 (BOOST-IN) 중간 연결 기어 헤드(x10)를 연결한 경우의 허용 토크는 상기 표의 최대 허용 토크를 초과하지 않습니다. (RATIO 200초과)
- 출력축의 회전 방향은 ■ 색이 모터 축과 동일하며, 그 외는 반대 방향입니다.
- 출력 회전수는 모터의 동기 회전수 (60Hz의 경우 1800 RPM)를 기준으로 감속된 값을 나타내었습니다. 실부하에 따라 1~20% 정도 줄어 들 수 있습니다.
- Gear ratio to be typed (filled) in the □ of model.
- When you assemble gear head with Boost-In Gear Head(X10), allowable load torque shall not be greater than the maximum allowable torque in the listed (Gear ratio more than 200 : 1)
- Direction of output shaft is same to motor shaft direction for the colored, ■
- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

200W

ELECTRO MAGNETIC BRAKE MOTOR

□90mm

LEAD WIRE TYPE

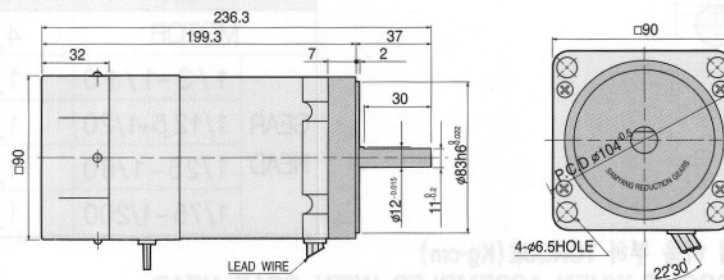


MOTOR SPECIFICATIONS

Model	Output	Input			Mag. Poles	Run Duty	Ratings				Start Torque		Condenser
		Volt	Phase	Freq.			Current	Speed	Torque		Kg-cm	N-m	
	Watt	V		Hz	min	Amp			rpm	Kg-cm			N-m
SM9N200GS	200	380	3 ϕ	50	4	Cont.	0.65	1300	14.48	1.419	38.40	3.763	
				60			0.57	1600	11.08	1.085	30.08	2.948	
		440		50			0.82	1300	18.60	1.823	40.00	3.920	
				60			0.66	1600	14.20	1.391	39.80	3.900	
SM9N200GT	200	220	3 ϕ	50	4	Cont.	1.45	1300	17.80	1.744	38.00	3.724	
				60			1.16	1600	12.00	1.176	28.60	2.803	

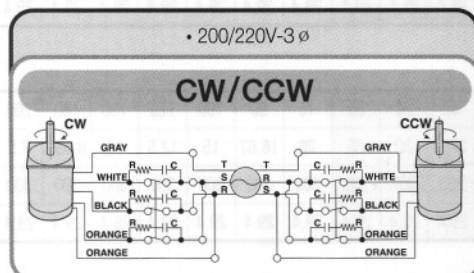
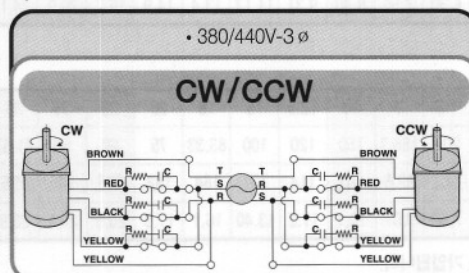
- 모델별로 정격 사양을 준수하여 사용하십시오. 모터 손상의 주 요인이 됩니다.
- 과열 보호형인 TP(Thermal Protective) 모터는 과열 발생시 자동 정지되지만, 식으면 다시 작동됩니다. 그러나 정지시에도 주 전원은 살아 있으므로 어떤 조치를 할 경우에는 반드시 주 전원을 차단한 후 조작하십시오.
- Please load and install within the rated specifications. Or motor or gear head may be damaged.
- TP(Thermally Protected) type of motor may be stop(power off) itself when temperature sensor in the motor is heated up to limited temperature and then restart again after the motor and sensor is cooled down. But during stops, do not operate the motor manually. If you intend to operate the motor, disconnect main power switch before touch.

D-CUT MOTOR



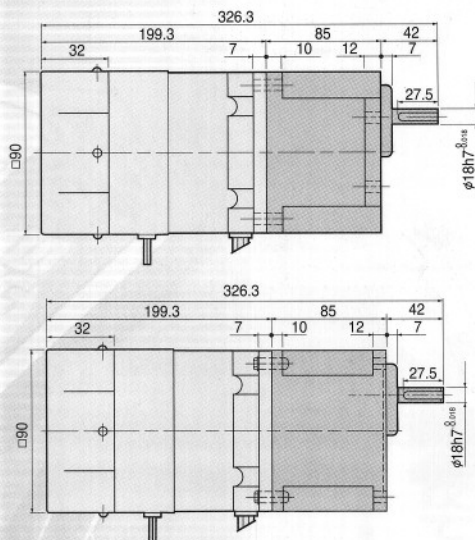
결선도 (WIRINGS)

회전방향은 모터축 끝에서 모터쪽으로 볼 때의 회전방향을 표시합니다.
Directions of rotation are view at the end of motor shaft.

R=10~100 Ω C=0.1~0.50 μ FR=10~200 Ω C=0.1~0.50 μ F

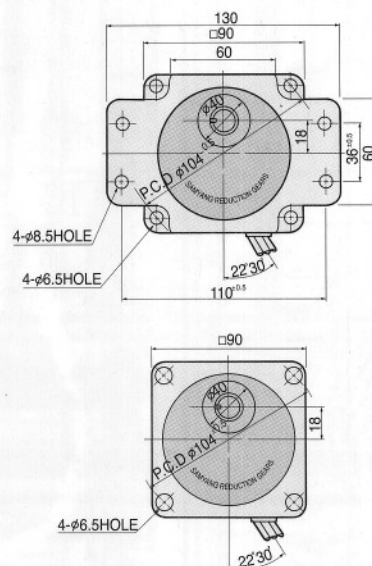
DIMENSIONS

GEARED MOTOR

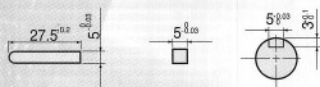


◀ KF TYPE ▶

◀ K TYPE ▶



KEY SPEC



WEIGHT

PART		WEIGHT(kg)
GEAR HEAD	MOTOR	4.30
	1/3 ~ 1/10	1.70
	1/12.5 ~ 1/20	1.83
	1/25 ~ 1/60	1.93
	1/75 ~ 1/200	1.98

ALLOWABLE LOAD TORQUE WHEN ASSEMBLED WITH GEAR HEAD

60Hz

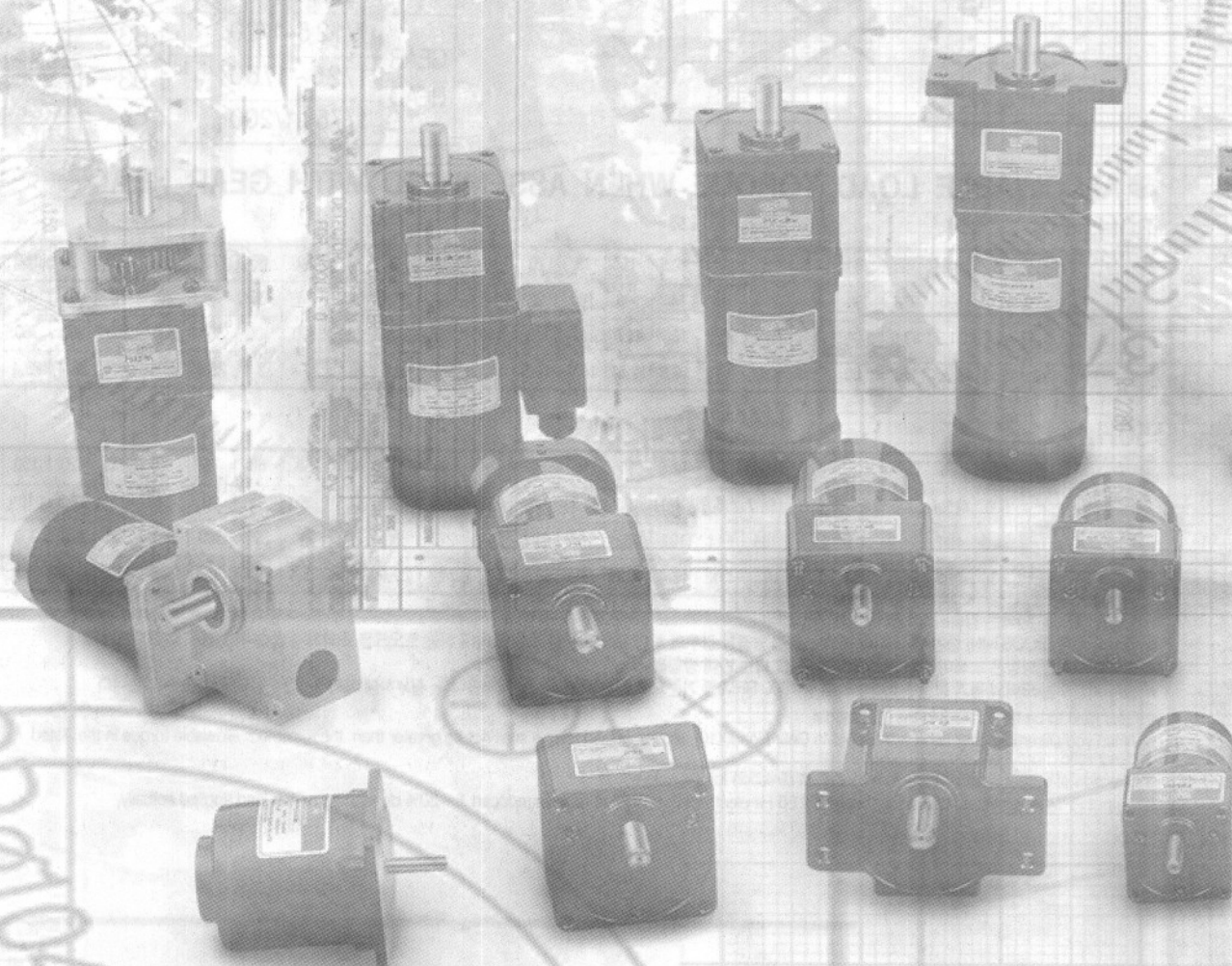
Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□KF	rpm	600	500	360	300	240	200	180	144	120	100	90	72	60	50	45	36	30	24	20	18	15	12	10	9
P9K□K	kg-cm	28.6	34.3	47.6	57.1	71.4	85.7	95.2	106	127	152	169	189	227	273	300	300	300	300	300	300	300	300	300	300
	N-m	2.80	3.36	4.67	5.60	7.00	8.40	9.33	10.3	12.41	14.9	16.5	18.6	22.3	26.7	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

50Hz

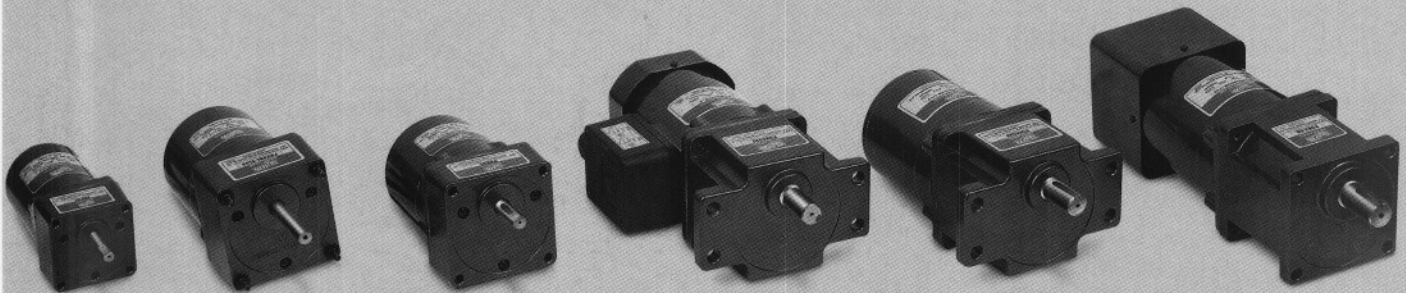
Model	RATIO	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	36	40	50	60	75	90	100	120	150	180	200
P9K□KF	rpm	500	416.7	300	250	200	166.7	150	120	100	83.33	75	60	50	41.67	37.5	30	25	20	16.67	15	12.5	10	8.333	7.5
P9K□K	kg-cm	34.3	41.1	57.1	68.6	85.7	103	114	127	152	182	203	227	273	300	300	300	300	300	300	300	300	300	300	300
	N-m	3.36	4.03	5.60	6.72	8.40	10.1	11.2	12.4	14.89	17.9	19.9	22.3	26.7	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4	29.4

- 모델명 내의 □안에는 감속비(Gear Ratio)가 기입됩니다.
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- Output RPM is calculated under the theoretical 60 Hz electromotive RPM. It may be reduced 1 ~ 20% dependent on the load applied actually.

DIMENSIONS



SPEED CONTROL MOTOR



SPEED CONTROL MOTOR



SPEED CONTROLLER (UNIT TYPE)

MAKER

ST

SAMYANG

CONTROLLER TYPE

U

U : Unit Type

OUTPUT

A

A : Analogue Type
D : Digital Type

VOLTAGE

60

06 : 6W
15 : 15W (702, 702)
25 : 25W
40 : 40W
60 : 60W
90 : 90W
120 : 120W
180 : 180W

T·G VOLTAGE

V12

V12 : T·G Voltage

A : 1 ϕ AC 110V 60Hz (4Pple)
B : 1 ϕ AC 220V 60Hz (4Pple)
C : 1 ϕ AC 100V 50/60Hz (4Pple)
D : 1 ϕ AC 200V 50/60Hz (4Pple)
E : 1 ϕ AC 115V 60Hz (4Pple)
X : 1 ϕ AC 220/240V 50Hz (4Pple)

SPEED CONTROLLER (SOCKET TYPE)

MAKER

ST

SAMYANG

TYPE

S

S : Socket Type

OUTPUT

01

01 : 6W, 15W
02 : 15W, 40W, 60W, 90W
03 : 120W, 180W

VOLATGE

B

A : 1 ϕ AC 110V 60Hz (4Pple)
B : 1 ϕ AC 220V 60Hz (4Pple)
C : 1 ϕ AC 100V 50/60Hz (4Pple)
D : 1 ϕ AC 200V 50/60Hz (4Pple)
E : 1 ϕ AC 115V 60Hz (4Pple)
X : 1 ϕ AC 220/240V 50Hz (4Pple)

UNIT TYPE



사진의 Gearhead는 별매입니다.
You may order motor, gear
head, control unit separately.



분리형 Control Unit와 Control Motor의 Unit제품입니다.
Separate control unit of speed control motor.

● 일반사양 (GENERAL SPECIFICATIONS)

항목	(ITEM)	사 양 (SPECIFICATION)
절연저항	Insulation Resistance	상온 상습에서 정격으로 운전후 MOTOR의 권선과 CASE 간에 DC 500V MEGA로 측정하여 100MΩ 이상. More than 100 MΩ between case and wires measured by MEGA at DC 500 V after running 30 minutes under the rating load at room temperature and humidity
절연내압	Dielectric Strength	MOTOR를 상온 상습에서 정격으로 운전후 MOTOR의 권선과 CASE 간에 1500V AC, 60Hz 를 1분간 인가하여 견딜것 Endure 1 minute applied 1500 VAC, 60 Hz between case and wiring after running under the rating load at room temperature and room humidity.
온도상승	Temperature Rise	MOTOR를 정격운전후 온도계법으로 측정하여 표면 온도 상승량이 60°C 이내 Surface temperature rises not greater 60 °C than environments running under the rating load.
절연등급	Insulation	E중 (120°C) E(120°C)
과열보호 장치(T/P)	Temperature Protection	THERMAL PROTECTOR 내장형(Optional) 자동복귀형 (개방 120°C ± 5°C, 복귀 80°C ± 15°C) Optional for TP (Temperature Protection) inclosed. TP : self recovering type (open : 120 ± 5 °C, close : 80 ± 15 °C)
사용온도	Environmental Temperature	-10°C ~ +50°C
사용습도	Environmental Humidity	90%R 이하 (단, 결로없는곳) maximum 90 %R (no dews allowed)

● SPECIFICATION OF UNIT TYPE SPEED CONTROL MOTOR

CONTINUOUS RATING - INDUCTION MOTOR(6W~90W)

Output	Type	Pole	Input	Frequency	Speed Control Range	Torque				Starting Torque		Capacitor
			(V)	(Hz)		at1200rpm		at900rpm		(Kg-cm)	(N-m)	
					(rpm)	(Kg-cm)	(N-m)	(Kg-cm)	(N-m)			(Kg-cm)
6W	SM6N06GA-V12	4	1 ∅ 110	60	60-1700	0.55	0.055	0.40	0.040	0.52	0.051	2.5
	SM6N06GB-V12	4	1 ∅ 220	60	60-1700	0.55	0.055	0.40	0.040	0.52	0.051	0.8
15W	SM8N15GA-V12	4	1 ∅ 110	60	60-1700	1.50	0.150	0.65	0.065	1.10	0.108	5.0
	SM8N15GB-V12											
	SM8N15GB-V12(TP)	4	1 ∅ 220	60	60-1700	1.50	0.150	0.65	0.065	1.20	0.118	1.5
25W	SM8N25GA-V12	4	1 ∅ 110	60	60-1700	1.70	0.170	0.80	0.080	1.90	0.186	6.0
	SM8N25GA-V12(TP)											
	SM8N25GB-V12	4	1 ∅ 220	60	60-1700	1.70	0.170	0.80	0.080	1.90	0.186	2.0
40W	SM9N40GA-V12	4	1 ∅ 110	60	60-1700	2.70	0.270	1.00	0.100	2.60	0.255	10.0
	SM9N40GA-V12(TP)											
	SM9N40GB-V12	4	1 ∅ 220	60	60-1700	2.70	0.270	1.00	0.100	2.80	0.275	3.0
60W	SM9N60GA-V12	4	1 ∅ 110	60	60-1700	5.50	0.550	2.00	0.200	4.80	0.471	15.0
	SM9N60GA-V12(TP)											
	SM9N60GB-V12	4	1 ∅ 220	60	60-1700	5.50	0.550	2.00	0.200	4.50	0.441	4.0
90W	SM9N90GA-V12	4	1 ∅ 110	60	60-1700	6.30	0.630	3.00	0.300	5.10	0.500	23.0
	SM9N90GA-V12(TP)											
	SM9N90GB-V12	4	1 ∅ 220	60	60-1700	6.30	0.630	3.00	0.300	5.30	0.520	5.5

사용방법 (OPERATION GUIDE)

● 운전 (OPERATIONS)

▶ 콘덴서 내장형의 경우

Control Unit와 Motor의 Lead선 Connector를 접속하여, AC전원에 Cord를 연결합니다. Control Unit의 「RUN / STAND-BY」 SW를 「RUN」 쪽으로 하면, Motor는 출력축방향으로 시계방향(cw)으로 회전합니다.

(출하시 Control Unit는 시계 방향으로 회전하도록 Set되어 있고, 기어헤드출력축의 회전방향은 그 감속비에 따라 Motor와는 반대방향으로 회전을 할 수도 있습니다.)

▶ 콘덴서 외장형의 경우

Control Unit와 Motor의 Connector를 접속하고, Control Unit의 콘덴서용 WIRE에 콘덴서를 연결한 후에 Cord를 AC 전원에 연결합니다. Control Unit의 「RUN / STAND-BY」 SW를 「RUN」 쪽으로 하면, Motor는 출력축방향으로 시계방향(cw)으로 회전합니다.

(출하시 Control Unit는 시계 방향으로 회전하도록 Set되어 있고, 기어헤드출력축의 회전방향은 그 감속비에 따라 Motor와는 반대방향으로 회전을 할 수도 있습니다.)

▶ FOR [CONDENSER INCLOSED] TYPE

Connect the motor wires to the control unit wiring terminals and the power source wires to the specified terminals of the unit at rear side. Toggle the button to [RUN] direction to start motor run. Clockwise direction of rotation was set when the control unit for default. Rotation of gear head is dependent to the gear ratio as specified on the detail data sheet.

▶ FOR [CONDENSER EXTERNAL] TYPE

Connect the motor wires to the control unit terminals with the specified condenser simultaneously. And connect power sources to the specified terminals at the rear side. Toggle the [run/stand-by] button to [RUN] direction to start motor run.

● 회전방향의 변경 (SWITCHING DIRECTION OF ROTATION)

▶ 연속운전의 경우

GEAR HEAD 등의 전달기구에서 MOTOR의 회전방향을 반대로 할 경우 CONTROL UNIT 뒷면에 붙어있는 ③COM과 ⑤CW의 단자의 위치를 ③COM과 ④CCW의 위치로 연결되도록 단자의 위치를 교환하여 주십시오. 전원 CORD단자는 항상 ①AC, ②AC에 접속하여 주십시오. 이때 반드시 전원을 OFF로 한후에 교환및 결선하여 주십시오.

▶ 정역회전의 경우

양방향 회전세팅과 같이 전원용 SWITCH(SW1)와 정역회전 교환SWITCH(SW2)를 설치하여 회전방향을 교체하여 주십시오. 그러나 순시 정역회전은 불가능하다. 일단 전원SWITCH(SW1)를 끄고 MOTOR가 완전히 정지한후에 SWITCH(SW2)를 교체하여 주십시오.

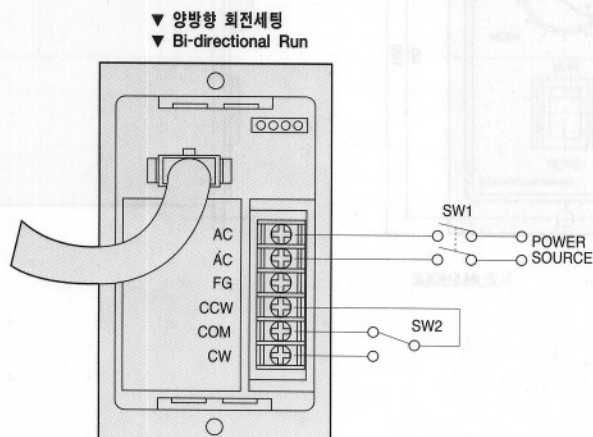
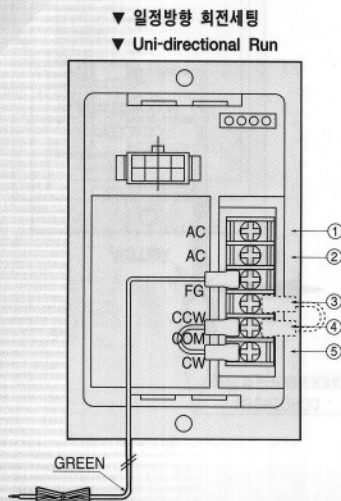
▶ FOR CONTINUOUS RUN

Off the main power first. Switch the jumper of connected between COM-CW to COM-CCW, and then on-line the main power to be ready for start.

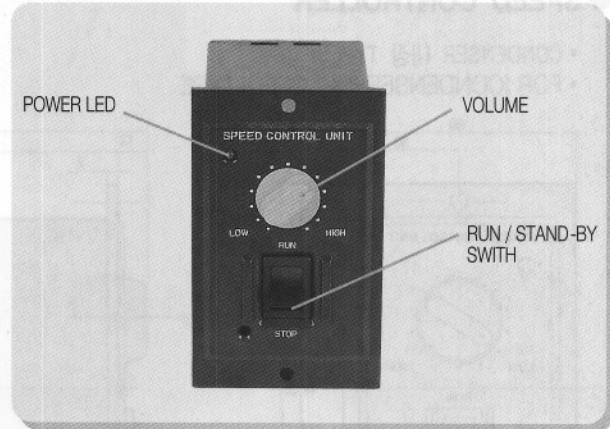
When the jumper was connected between COM-CCW, switch the jumper to COM-CW to change direction of rotation vice versa.

▶ FOR REVERSIBLE RUN

Put additional switch for you to select CCW or CW connecting with COM terminal. Toggle the selecting switch from CCW to CW or vice versa to change direction of rotation. Do not start the motor before it stops fully.



CONTROL UNIT 정면 (CONTROL UNIT (Front))



● 정지 (HOLD/STOP)

Control Unit의 「RUN / STAND-BY」 SW를 「STAND-BY」 쪽으로 하면, Motor는 정지합니다. 이 SW는 전원의 ON/OFF SW가 아니므로 Motor를 장시간 정지할 경우에는 별도로 전원 SW를 차단하여 주십시오.

Switch the toggle button to [STOP] or [STAND-BY] direction to stop the motor temporarily. Please off the main switch when you need the motor stop for long period.

● 변속 (SPEED UP/DOWN)

Control Unit의 「볼륨」의 손잡이를 시계방향으로 돌리면, Motor의 Speed가 빨라지고, 반대로 돌리면 느려집니다.

60~1700rpm의 범위에서 Motor의 Speed를 조정, 설정할 수 있습니다.

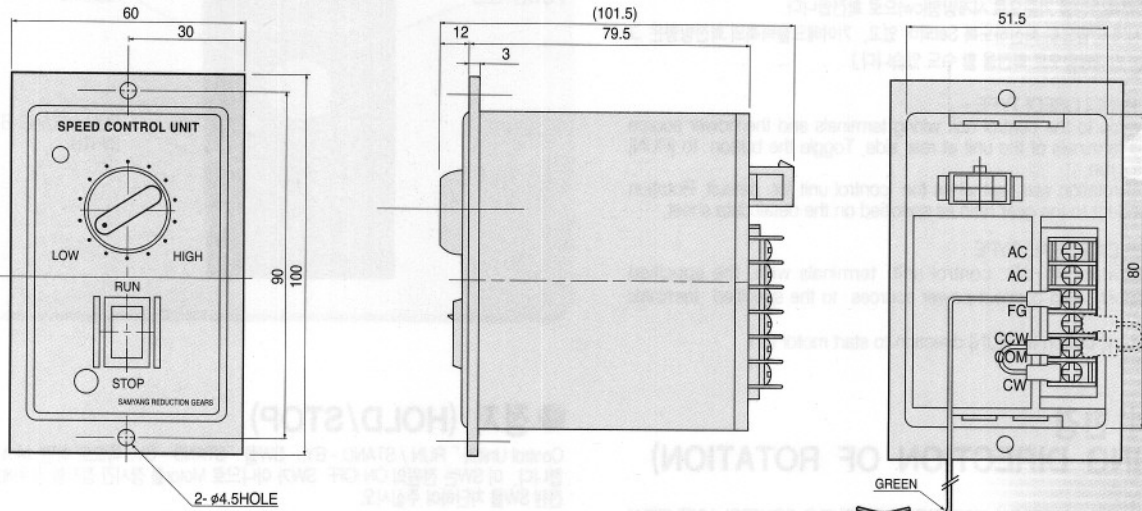
Motor speed up when you turn the volume knob to [HIGH] clockwise direction, and vice versa.

You may control motor speed between 60 ~ 1700 rpm

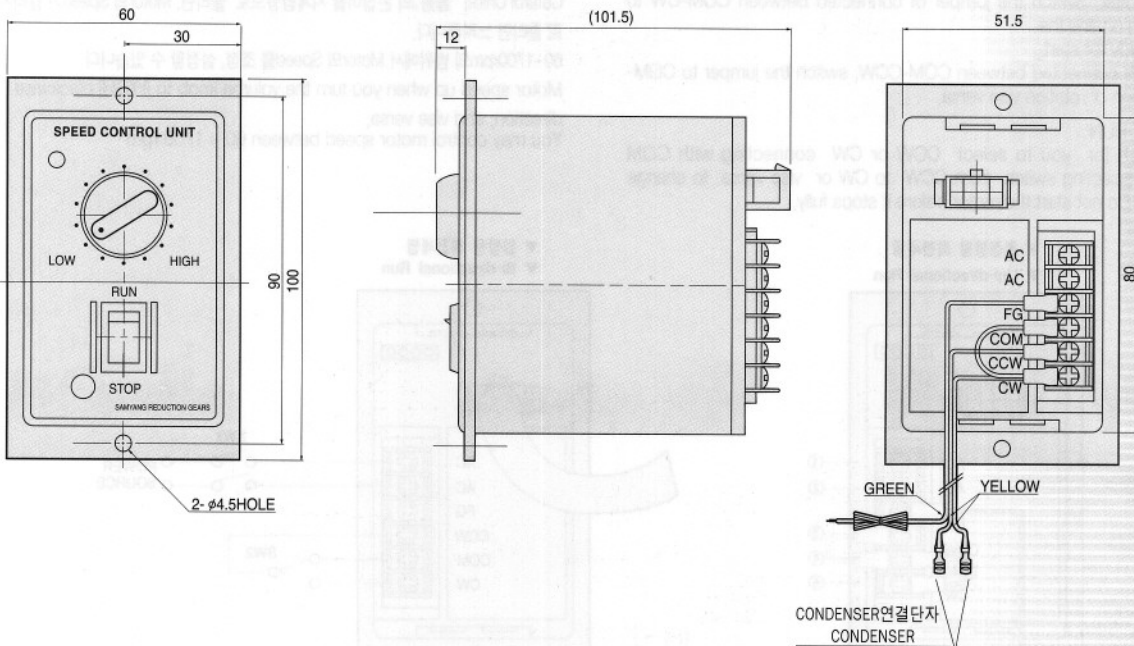
DIMENSIONS

● SPEED CONTROLLER

- CONDENSER 내장 TYPE의 경우
- FOR [CONDENSER INCLOSED] TYPE

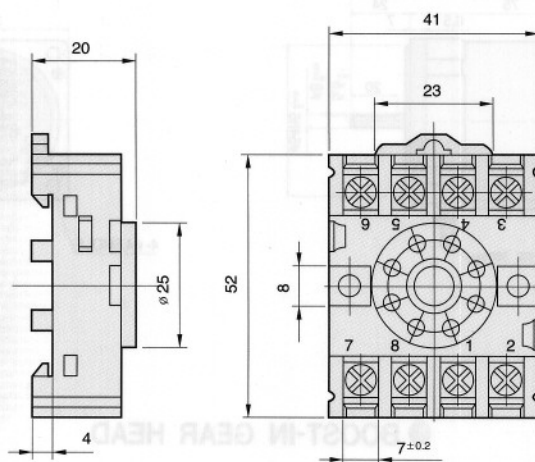
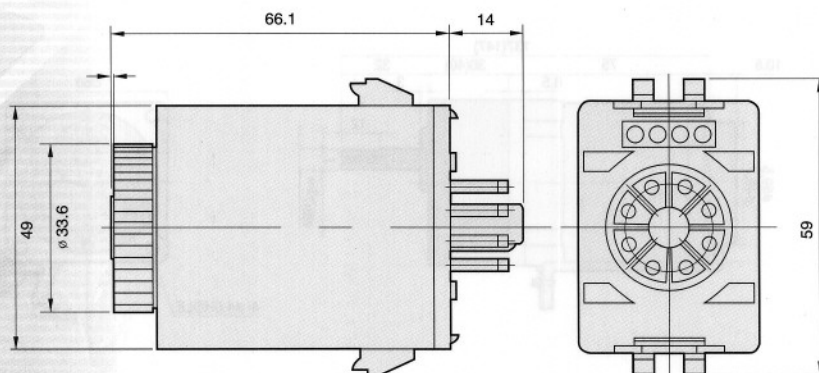


- CONDENSER외장 TYPE의 경우
- FOR [CONDENSER EXTERNAL] TYPE

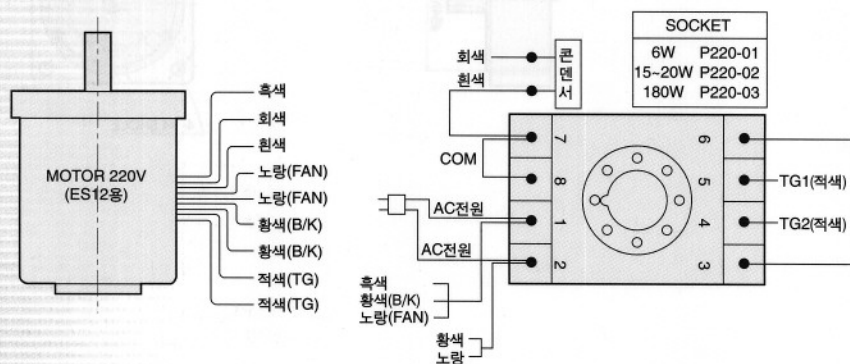


SOCKET TYPE

● 본 체



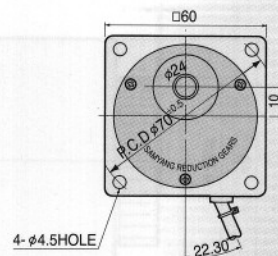
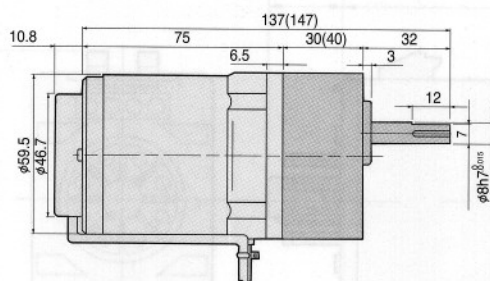
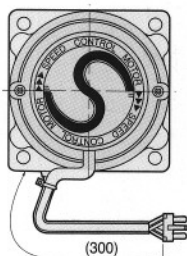
● 결선도



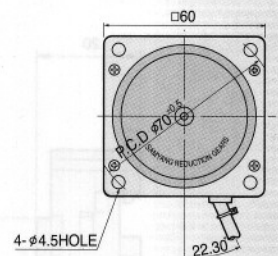
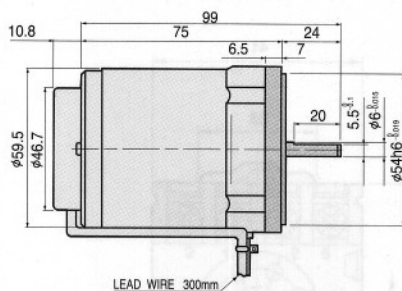
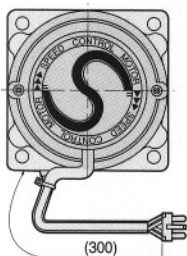
DIMENSIONS

● MOTOR (□60mm)

● GEARED MOTOR



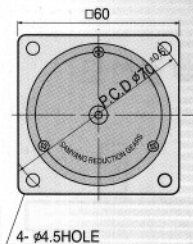
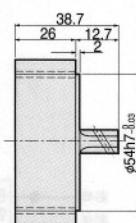
● D-CUT MOTOR



● 적용 MODEL

SM6N06GA-V12
SM6N06GB-V12
SM6N06GC-V12
SM6N06GD-V12

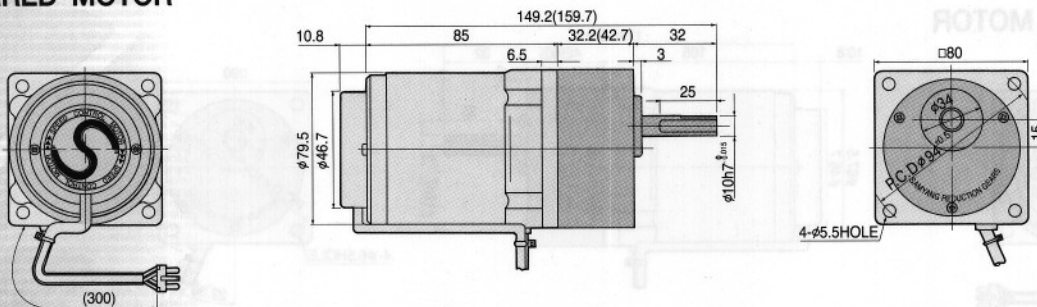
● BOOST-IN GEAR HEAD



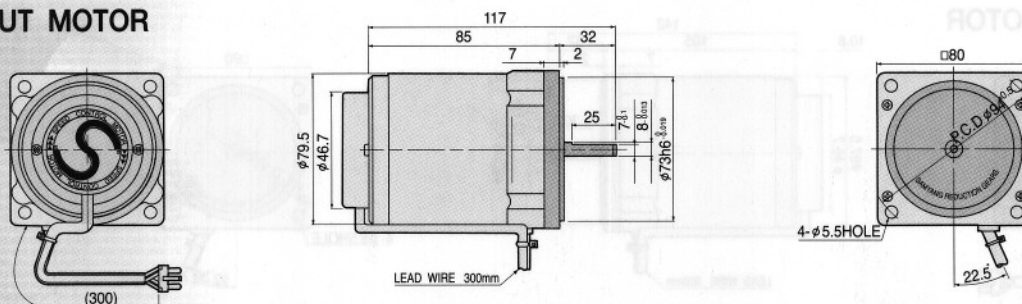
DIMENSIONS

● MOTOR (□80mm)

● GEARED MOTOR



● D-CUT MOTOR

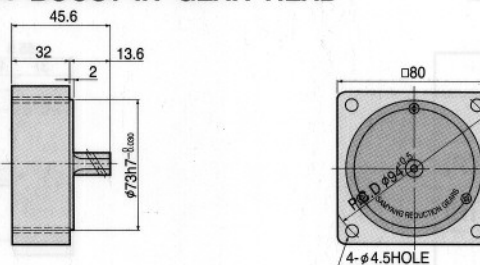


● 적용 MODEL

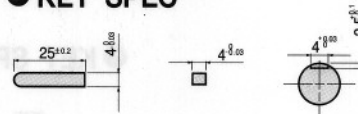
SM8N15GA-V12	SM8N25GA-V12
SM8N15GB-V12	SM8N25GB-V12
SM8N15GA-V12(TP)	SM8N25GA-V12(TP)
SM8N15GB-V12(TP)	SM8N25GB-V12(TP)
SM8N15GC-V12	SM8N25GC-V12
SM8N15GD-V12	SM8N25GD-V12

(TP Optional)

● BOOST-IN GEAR HEAD



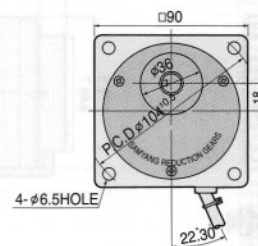
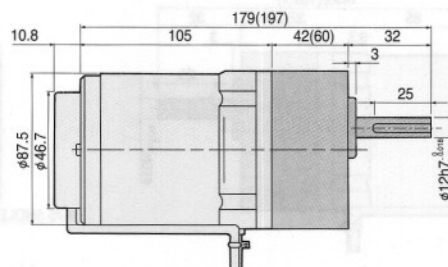
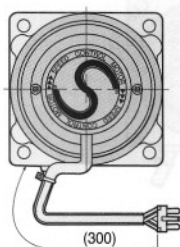
● KEY SPEC



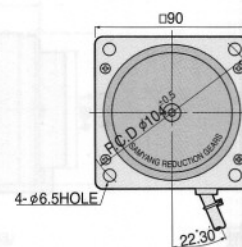
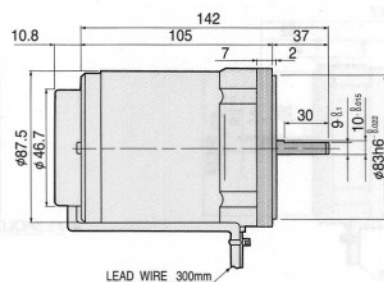
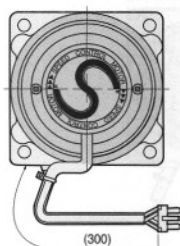
DIMENSIONS

● MOTOR (□90mm 40Watt general type)

● GEARED MOTOR



● D-CUT MOTOR

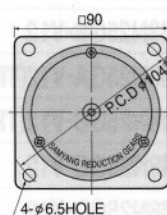
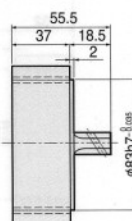


● 적용 MODEL

SM9N40GA-V12
SM9N40GB-V12
SM9N40GA-V12(TP)
SM9N40GB-V12(TP)
SM9N40GC-V12
SM9N40GD-V12

(TP Optional)

● BOOST-IN GEAR HEAD



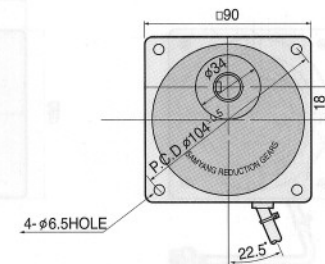
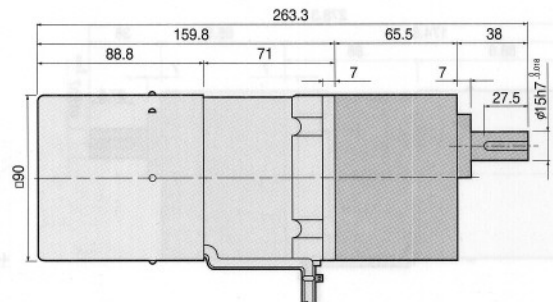
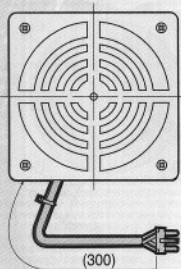
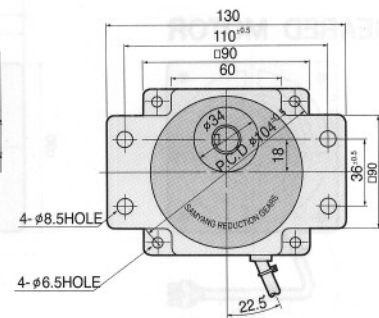
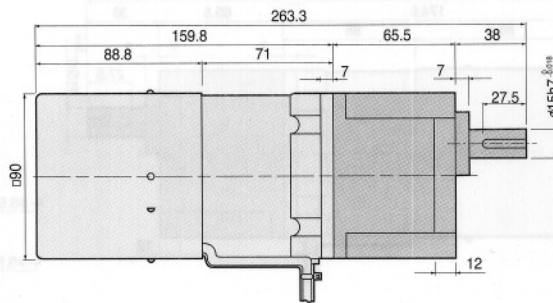
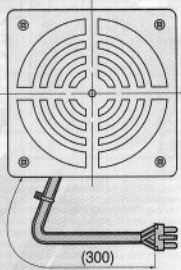
● KEY SPEC



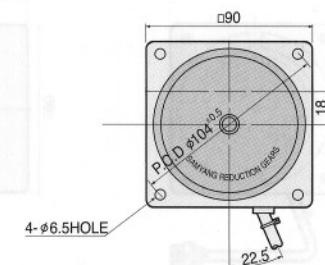
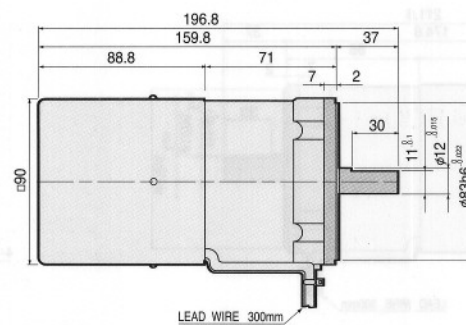
DIMENSIONS

● MOTOR (□90mm 60Watt H, HF)

● GEARED MOTOR



● D-CUT MOTOR

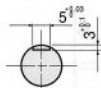
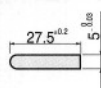


● 적용 MODEL

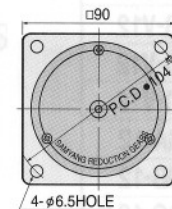
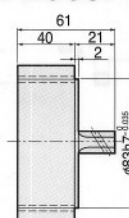
SM9N60GA-V12
SM9N60GB-V12
SM9N60GC-V12
SM9N60GD-V12

(TP Optional)

● KEY SPEC



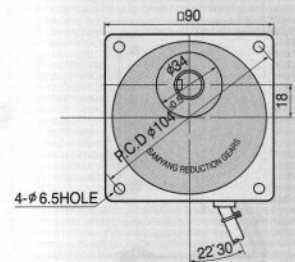
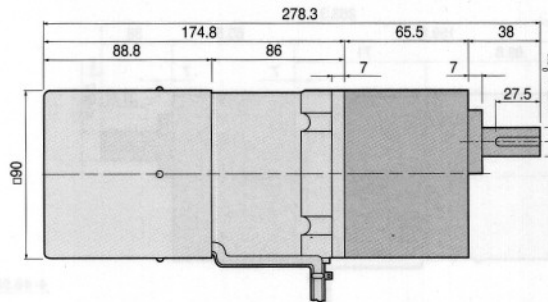
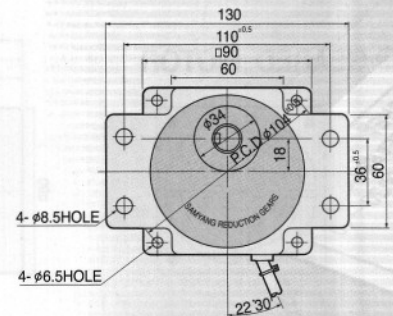
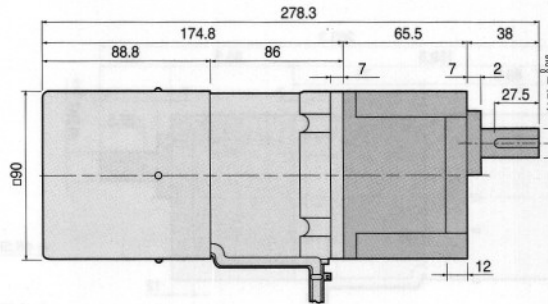
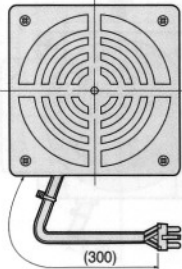
● BOOST-IN GEAR HEAD



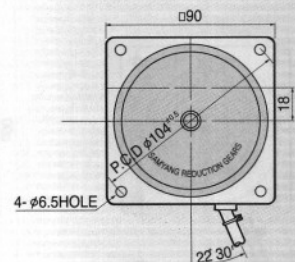
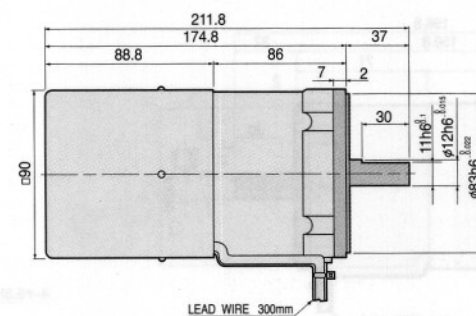
DIMENSIONS

● MOTOR (□90mm 90 · 120Watt H, HF)

● GEARED MOTOR



● D-CUT MOTOR

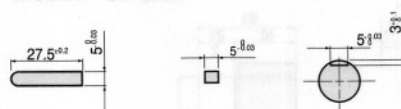


● 적용 MODEL

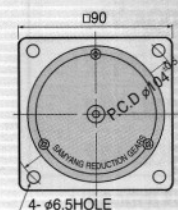
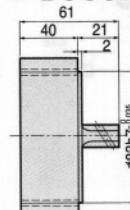
SM9N90GA-V12
SM9N90GB-V12
SM9N90GC-V12
SM9N90GD-V12
SM9N120GA-12
SM9N120GB-12
SM9N120GC-12
SM9N120GD-12

(TP Optional)

● KEY SPEC



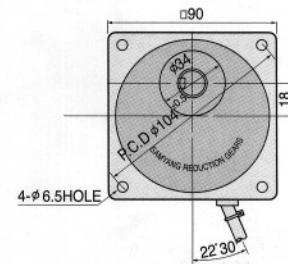
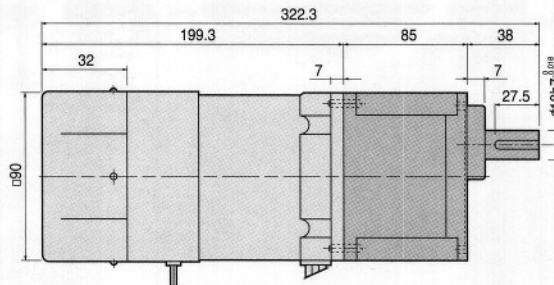
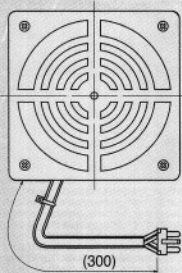
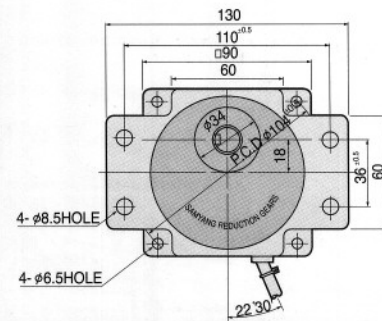
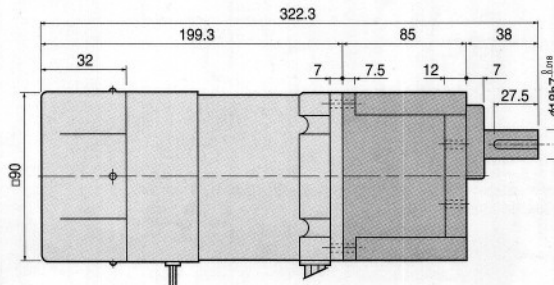
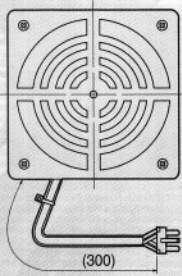
● BOOST-IN GEAR HEAD



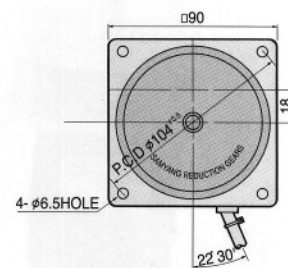
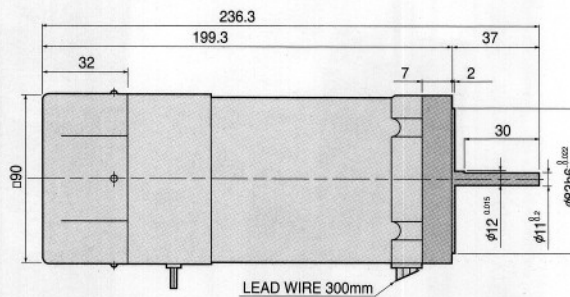
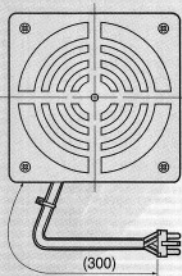
DIMENSIONS

● MOTOR (□90mm 180Watt K, KF)

● GEARED MOTOR



● D-CUT MOTOR



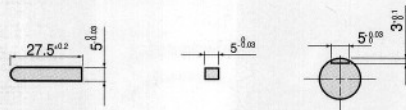
● 적용 MODEL

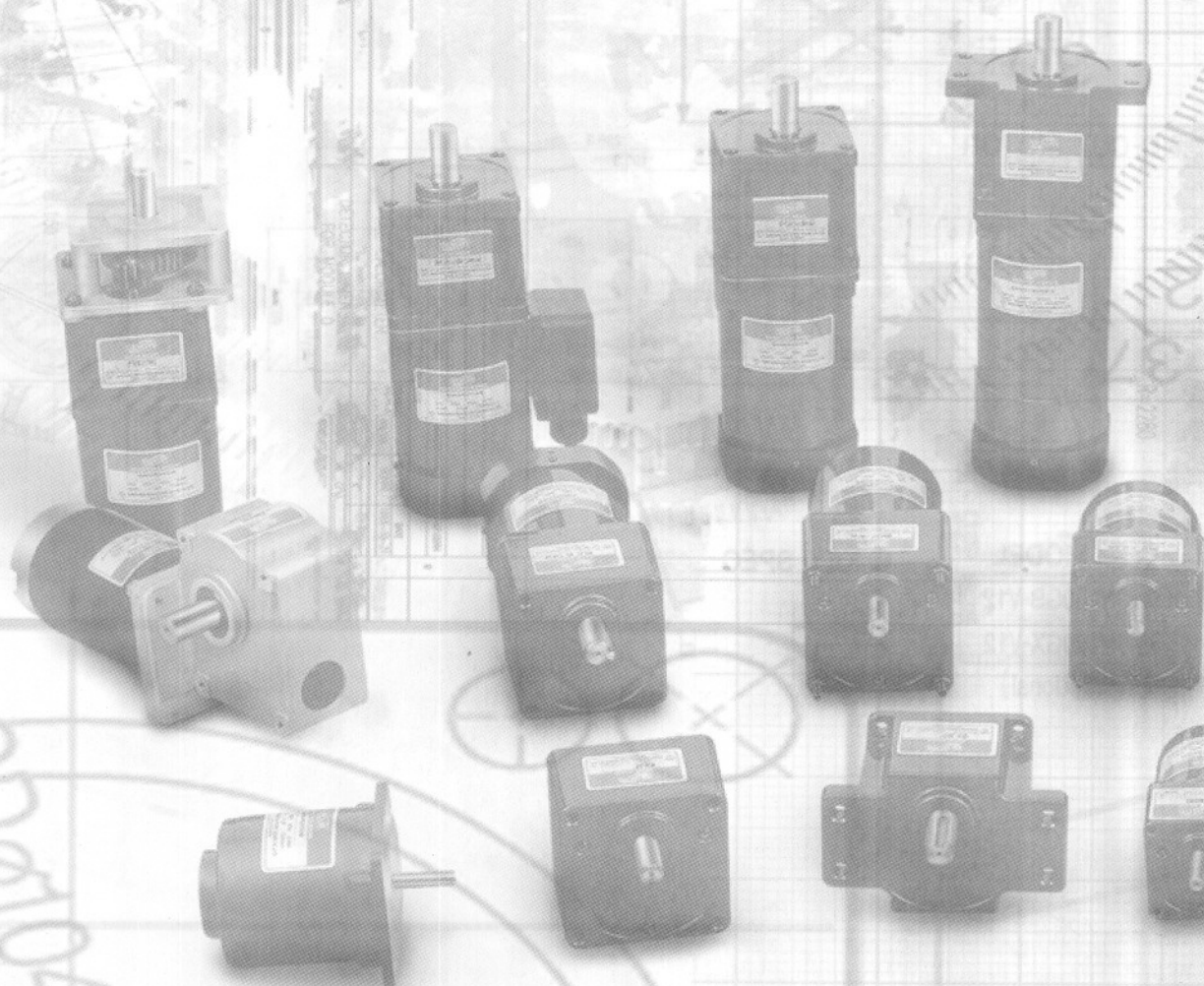
SM9N180GB-V12

SM9N180GX-V12

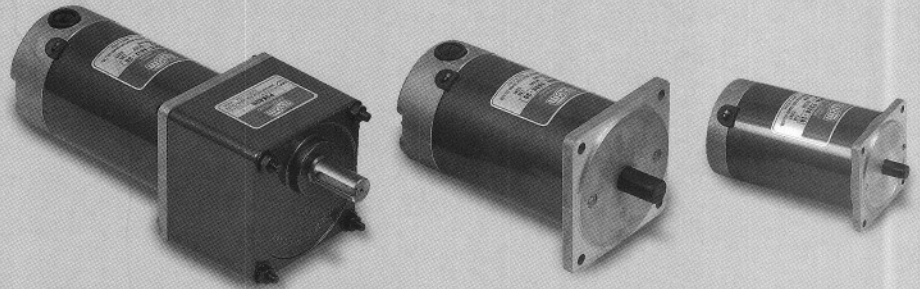
(TP Optional)

● KEY SPEC





DC Geared Motor



DC Geared Motor

MOTOR CODE

MAKER	SIZE	TYPE	POWER	VOLT	RPM	SHAFT
SM	6	D	005	090	30	G

G : Gear Shaft
S : Straight Shaft
K : Key Shaft
D : D-cut Shaft

18 : 1800 rpm
30 : 3000 rpm
40 : 4000 rpm

012 : 12 Vdc
024 : 24 Vdc
090 : 90 Vdc
110 : 110 Vdc
220 : 220 Vdc

005 : 5W
015 : 15W
025 : 25W
040 : 40W
060 : 60W
090 : 90W
120 : 120W
150 : 150W
180 : 180W
200 : 200W

DC

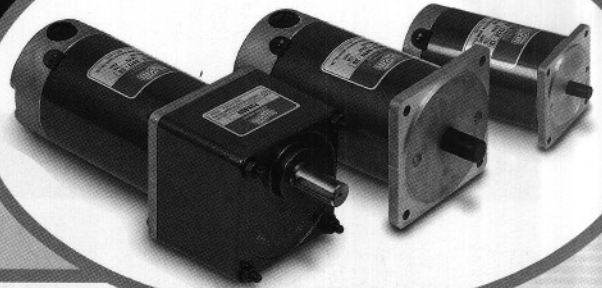
6 : ☐ 60mm
8 : ☐ 80mm
9 : ☐ 90mm

SAMYANG MOTOR

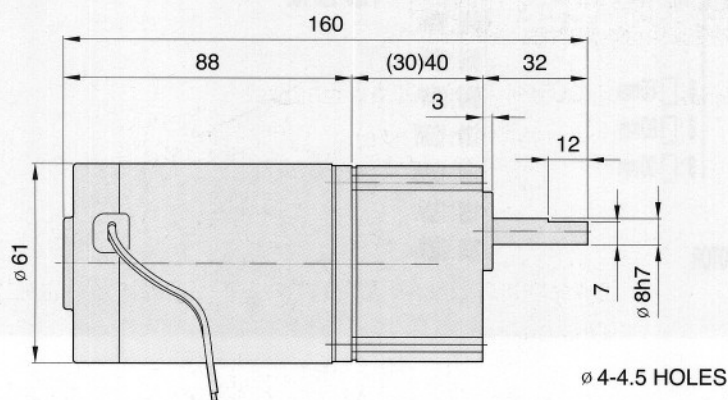
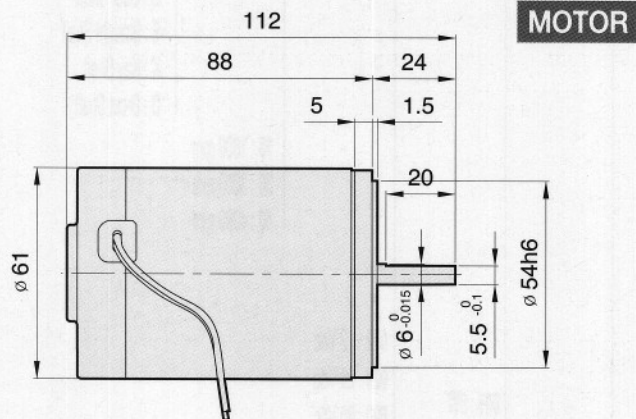
GEARED
MOTORS

5W~15W

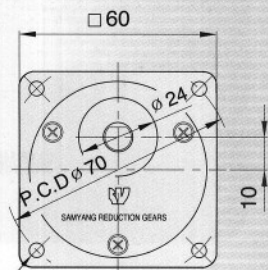
DC GEARED MOTOR
 □60mm MOTOR
 LEAD WIRE TYPE



● OUTLINE DRAWINGS



GEARED MOTOR



60mm SQUARE

Power	Voltage	Speed	Current (amo)	Time Rate	CODE
5 Watt	24 Vdc	1,800 rpm		cont	SM6D00502418G
		3,000 rpm		cont	SM6D00502430G
	90 Vdc	1,800 rpm		cont	SM6D00509018G
		3,000 rpm		cont	SM6D00509030G
10 Watt	24 Vdc	1,800 rpm		cont	SM6D00502418G
		3,000 rpm		cont	SM6D00502430G
	90 Vdc	1,800 rpm		cont	SM6D00509018G
		3,000 rpm		cont	SM6D00509030G
15 Watt	24 Vdc	1,800 rpm		cont	SM6D00502418G
		3,000 rpm	1.0	cont	SM6D00502430G
	90 Vdc	1,800 rpm		cont	SM6D00509018G
		3,000 rpm		cont	SM6D00509030G
25 Watt	24 Vdc	1,800 rpm		cont	SM6D00502418G
		3,000 rpm		cont	SM6D00502430G
	90 Vdc	1,800 rpm		cont	SM6D00509018G
		3,000 rpm		cont	SM6D00509030G

REMARKS 1. 상기 모델은 예시이며, 주문자의 요구에 따라서 세부 사양이 달라질 수 있습니다.
Detail specifications may be dependent on order.

GEARED MOTOR (기어 헤드 조립시)

1. OUTPUT SPEED (rpm) : Nout

$N_{out} = N_m / R \text{ (rpm)}$
Where = N_m : MOTOR SPEED (rpm)
R : GEAR RATIO (감속기)

2. OUTPUT TORQUE (kg-m) : Tout

$T_{out} = 0.974 \times \text{Watt} \times \eta / N_{out}$
Where = η : Efficiency (감속기 전동 효율)
 $\eta = 0.90$ (R= 1/3 ~ 1/18)
 $\eta = 0.81$ (R= 1/20 ~ 1/40)
 $\eta = 0.73$ (R= 1/41 ~ 1/200)

3. MAXIMUM ALLOWABLE TORQUE (허용 최대 부하 토크)

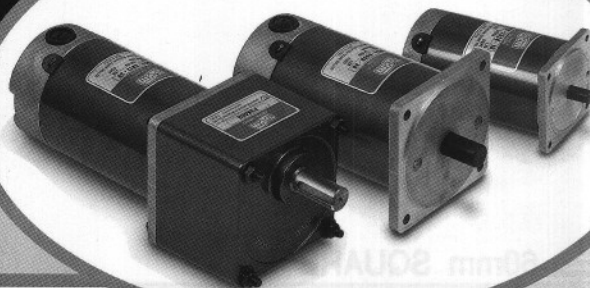
$T_{allow} = 30 \text{ kg-cm}$

20W~30W

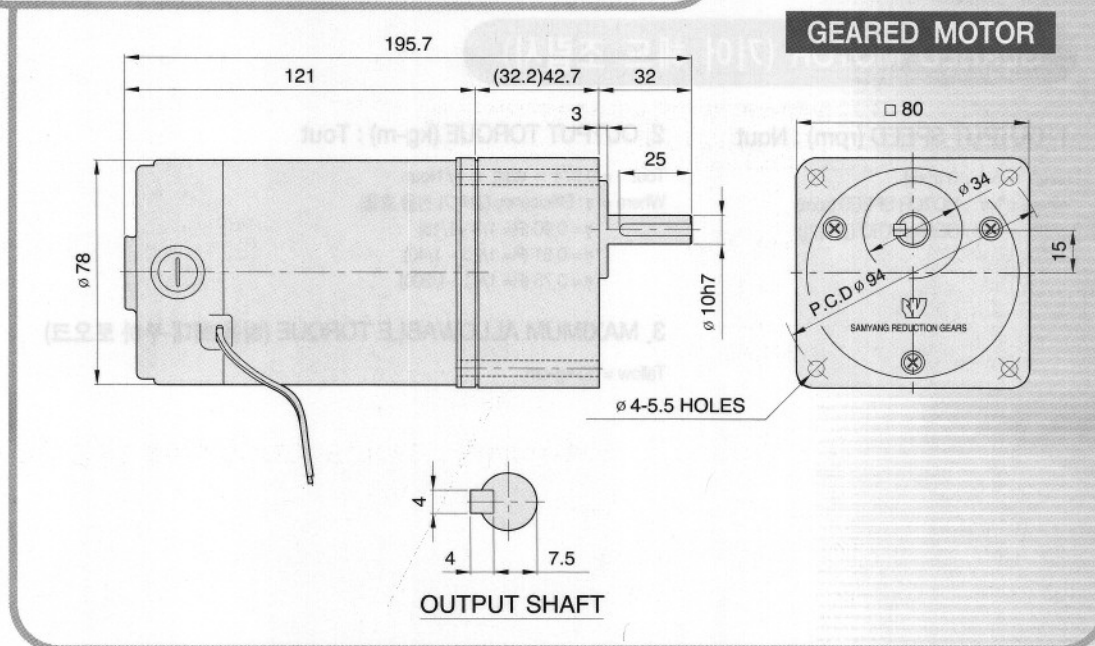
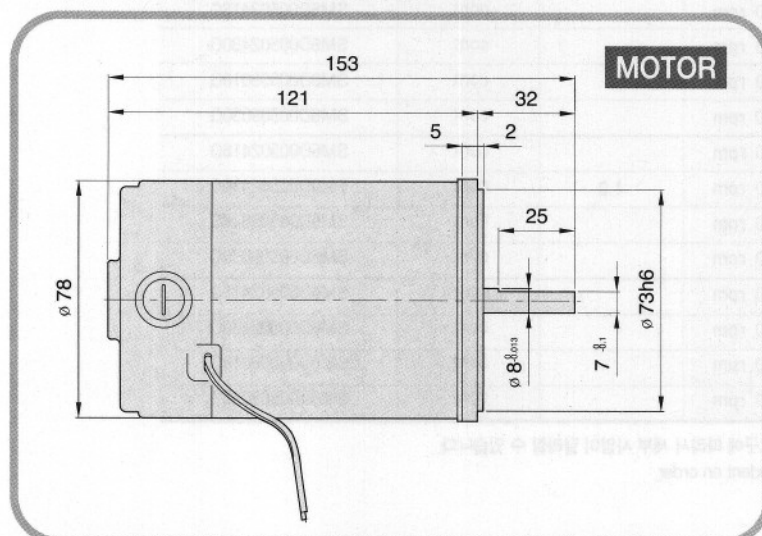
DC GEARED MOTOR

□80mm MOTOR

LEAD WIRE TYPE



● OUTLINE DRAWINGS



W02 ~ W04

80mm SQUARE

Power	Voltage	Speed	Current (amo)	Time Rate	CODE
20 Watt	24 Vdc	1,800 rpm		cont	SM8D02002418G
		3,000 rpm		cont	SM8D02002430G
	90 Vdc	1,800 rpm		cont	SM8D02009018G
		3,000 rpm		cont	SM8D02009030G
25 Watt	24 Vdc	1,800 rpm		cont	SM8D02502418G
		3,000 rpm	1.5	cont	SM8D02502430G
	90 Vdc	1,800 rpm		cont	SM8D02509018G
		3,000 rpm	0.4	cont	SM8D02509030G
30 Watt	24 Vdc	1,800 rpm		cont	SM6D03002418G
		3,000 rpm		cont	SM6D03002430G
	90 Vdc	1,800 rpm		cont	SM6D03009018G
		3,000 rpm		cont	SM6D03009030G
40 Watt	24 Vdc	1,800 rpm		cont	SM6D04002418G
		3,000 rpm	2.5	cont	SM6D04002430G
	90 Vdc	1,800 rpm		cont	SM6D04009018G
		3,000 rpm	0.6	cont	SM6D04009030G

REMARKS 1. 상기 모델은 예시이며, 주문자의 요구에 따라서 세부 사양이 달라질 수 있습니다.
Detail specifications may be dependent on order.

GEARED MOTOR (기어 헤드 조립시)

1. OUTPUT SPEED (rpm) : Nout

$N_{out} = N_m / R \text{ (rpm)}$
Where = N_m : MOTOR SPEED (rpm)
R : GEAR RATIO (감속기)

2. OUTPUT TORQUE (kg-m) : Tout

$T_{out} = 0.974 \times \text{Watt} \times \eta / N_{out}$
Where = η : Efficiency (감속기 전동 효율)
 $\eta = 0.90$ (R= 1/3 ~ 1/18)
 $\eta = 0.81$ (R= 1/20 ~ 1/40)
 $\eta = 0.73$ (R= 1/41 ~ 1/200)

3. MAXIMUM ALLOWABLE TORQUE (허용 최대 부하 토크)

Tallow = 80 kg-cm

40W~50W

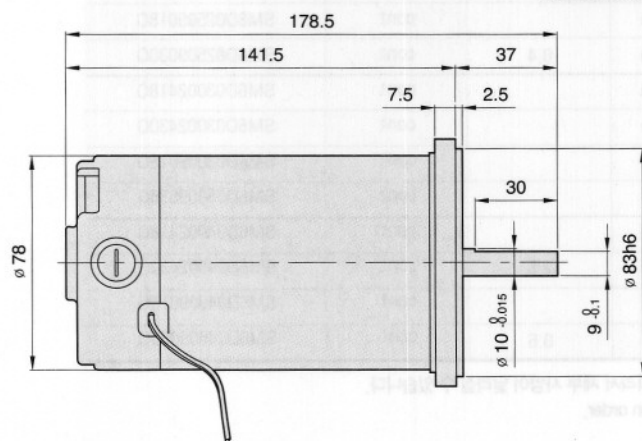
DC GEARED MOTOR

□90mm MOTOR
LEAD WIRE TYPE

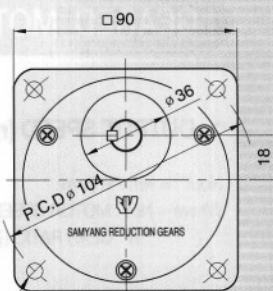
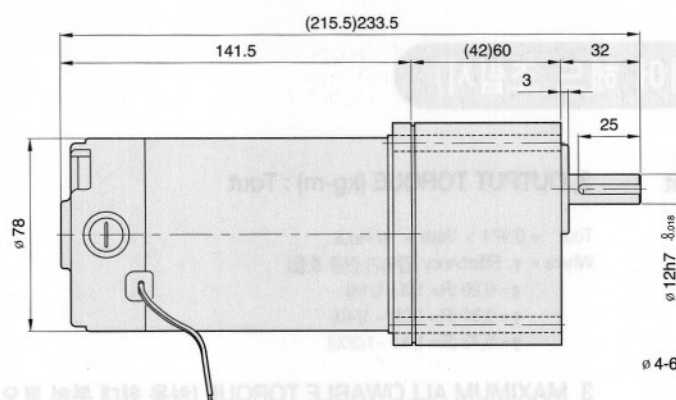


● OUTLINE DRAWINGS

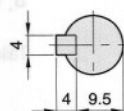
MOTOR



GEARED MOTOR



φ 4-6.5 HOLES



OUTPUT SHAFT

90mm SQUARE-N

Power	Voltage	Speed	Current (amo)	Time Rate	CODE
40 Watt	24 Vdc	1,800 rpm	2.5	cont	SM9D04002418G
		3,000 rpm		cont	SM9D04002430G
	90 Vdc	1,800 rpm	0.6	cont	SM9D04009018G
		3,000 rpm		cont	SM9D04009030G
50 Watt	24 Vdc	1,800 rpm		cont	SM9D05002418G
		3,000 rpm		cont	SM9D05002430G
	90 Vdc	1,800 rpm		cont	SM9D05009018G
		3,000 rpm		cont	SM9D05009030G

REMARKS 1. 상기 모델은 예시이며, 주문자의 요구에 따라서 세부 사양이 달라질 수 있습니다.
Detail specifications may be dependent on order.

GEARED MOTOR (기어 헤드 조립시) : 90N

1. OUTPUT SPEED (rpm) : Nout

$N_{out} = N_m / R$ (rpm)
Where = N_m : MOTOR SPEED (rpm)
R : GEAR RATIO (감속기)

2. OUTPUT TORQUE (kg-m) : Tout

$T_{out} = 0.974 \times \text{Watt} \times \eta / N_{out}$
Where = η : Efficiency (감기 전동 효율)
 $\eta = 0.90$ (R= 1/3 ~ 1/18)
 $\eta = 0.81$ (R= 1/20 ~ 1/40)
 $\eta = 0.73$ (R= 1/41 ~ 1/200)

3. MAXIMUM ALLOWABLE TORQUE (허용 최대 부하 토크)

Tallow = 100 kg-cm

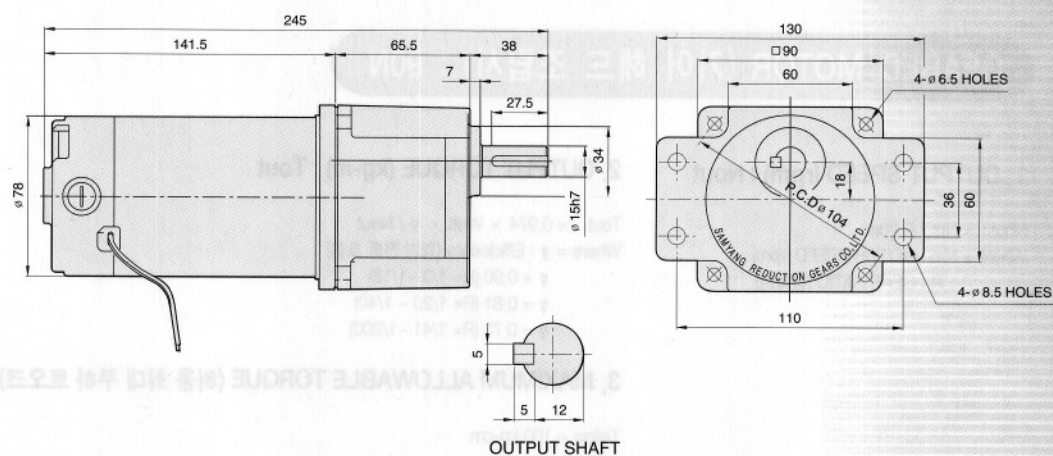
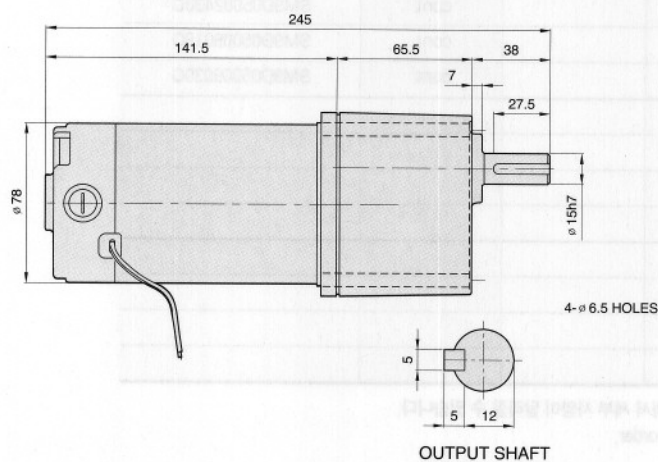
60W~120W

DC GEARED MOTOR
 □90mm MOTOR H/HF
 LEAD WIRE TYPE



● OUTLINE DRAWINGS

GEARED MOTOR



90mm SQUARE-H, HF

Power	Voltage	Speed	Current (amo)	Time Rate	CODE
60 Watt	24 Vdc	1,800 rpm	3.7	cont	SM9D06002418G
		3,000 rpm		cont	SM9D06002430G
	90 Vdc	1,800 rpm	1.0	cont	SM9D06009018G
		3,000 rpm		cont	SM9D06009030G
90 Watt	24 Vdc	1,800 rpm		cont	SM9D09002418G
		3,000 rpm		cont	SM9D09002430G
	90 Vdc	1,800 rpm	1.4	cont	SM9D09009018G
		3,000 rpm		cont	SM9D09009030G
120 Watt	24 Vdc	1,800 rpm		cont	SM9D12002418G
		3,000 rpm		cont	SM9D12002430G
	90 Vdc	1,800 rpm		cont	SM9D12009018G
		3,000 rpm		cont	SM9D12009030G

REMARKS 1. 상기 모델은 예시이며, 주문자의 요구에 따라서 세부 사양이 달라질 수 있습니다.
Detail specifications may be dependent on order.

GEARED MOTOR (기어 헤드 조립시) : 90H, 90HF

1. OUTPUT SPEED (rpm) : Nout

$N_{out} = N_m / R$ (rpm)
Where = N_m : MOTOR SPEED (rpm)
R : GEAR RATIO (감속기)

2. OUTPUT TORQUE (kg-m) : Tout

$T_{out} = 0.974 \times \text{Watt} \times \eta / N_{out}$
Where = η : Efficiency (감속기 전동 효율)
 $\eta = 0.90$ (R= 1/3 ~ 1/18)
 $\eta = 0.81$ (R= 1/20 ~ 1/40)
 $\eta = 0.73$ (R= 1/41 ~ 1/200)

3. MAXIMUM ALLOWABLE TORQUE (허용 최대 부하 토크)

$T_{allow} = 200 \text{ kg-cm}$

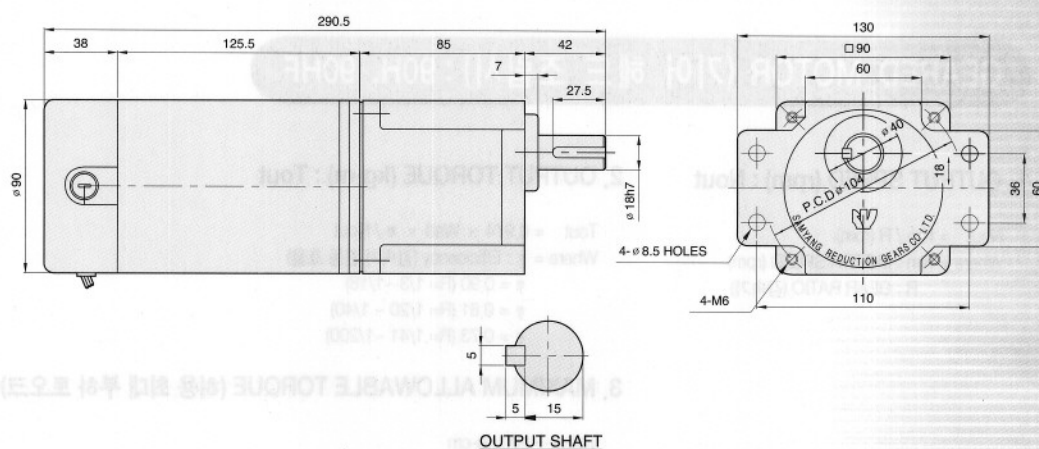
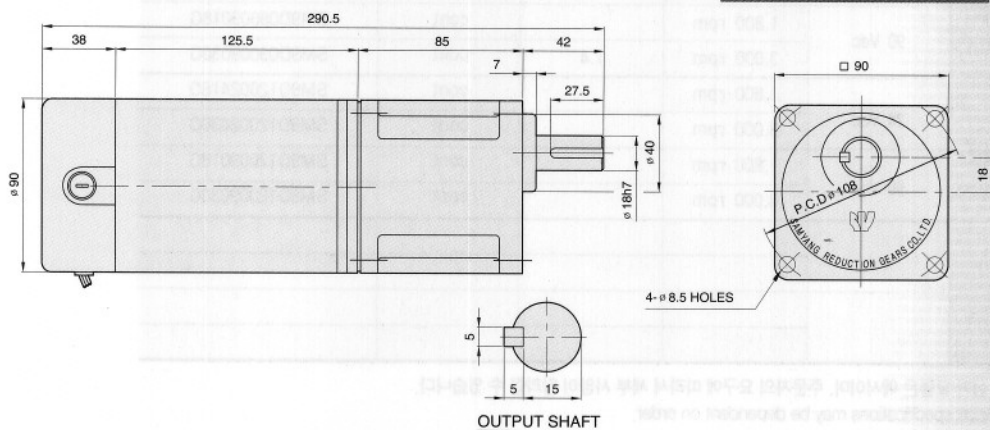
150W~200W

DC GEARED MOTOR
☐ 90mm MOTOR K/KF
 LEAD WIRE TYPE



● OUTLINE DRAWINGS

GEARED MOTOR



90mm SQUARE-K, KF

Power	Voltage	Speed	Current (amo)	Time Rate	CODE
150 Watt	24 Vdc	1,800 rpm		cont	SM9D15002418G
		3,000 rpm		cont	SM9D15002430G
	90 Vdc	1,800 rpm		cont	SM9D15009018G
		3,000 rpm		cont	SM9D15009030G
180 Watt	24 Vdc	1,800 rpm		cont	SM9D18002418G
		3,000 rpm		cont	SM9D18002430G
	90 Vdc	1,800 rpm		cont	SM9D18009018G
		3,000 rpm		cont	SM9D18009030G
200 Watt	24 Vdc	1,800 rpm		cont	SM9D20002418G
		3,000 rpm		cont	SM9D20002430G
	90 Vdc	1,800 rpm		cont	SM9D20009018G
		3,000 rpm		cont	SM9D20009030G

REMARKS 1. 상기 모델은 예시이며, 주문자의 요구에 따라서 세부 사양이 달라질 수 있습니다.
Detail specifications may be dependent on order.

GEARED MOTOR (기어 헤드 조립시) : 90H, 90HF

1. OUTPUT SPEED (rpm) : Nout

$N_{out} = N_m / R$ (rpm)
Where = N_m : MOTOR SPEED (rpm)
R : GEAR RATIO (감속기)

2. OUTPUT TORQUE (kg-m) : Tout

$T_{out} = 0.974 \times \text{Watt} \times \eta / N_{out}$
Where = η : Efficiency (감속기 전동 효율)
 $\eta = 0.90$ (R= 1/3 ~ 1/18)
 $\eta = 0.81$ (R= 1/20 ~ 1/40)
 $\eta = 0.73$ (R= 1/41 ~ 1/200)

3. MAXIMUM ALLOWABLE TORQUE (허용 최대 부하 토크)

$T_{allow} = 300 \text{ kg-cm}$

GEAR HEAD 및 MOTOR부착 Bracket



BRACKET CODE

MAKER

SB-BCKT

SAMYANG BRACKET

TYPE

00601

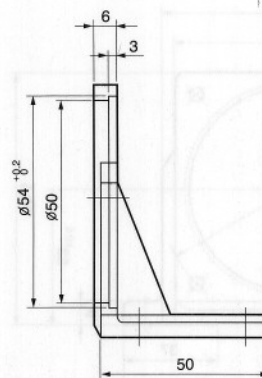
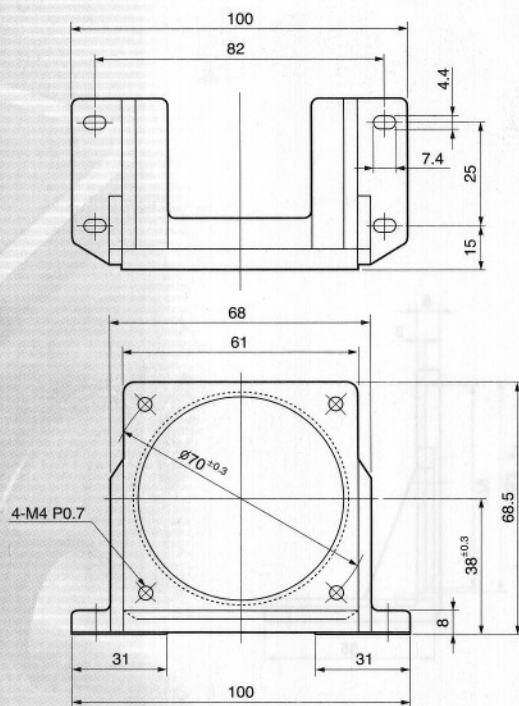
00601 : 60각

00801 : 80각

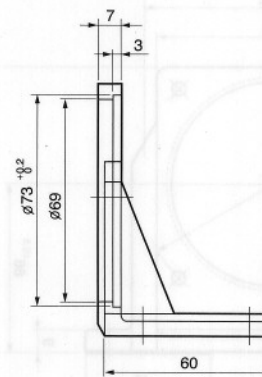
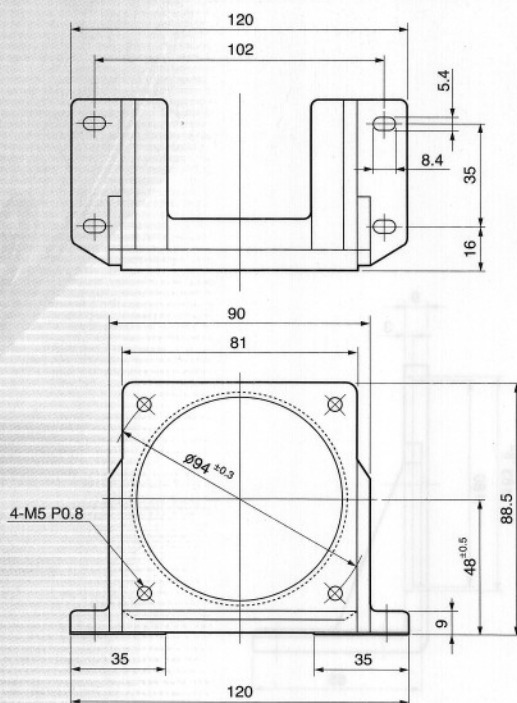
00901 : 90각 일반 Type

00902 : 90각 King Type

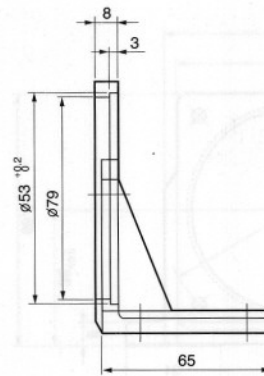
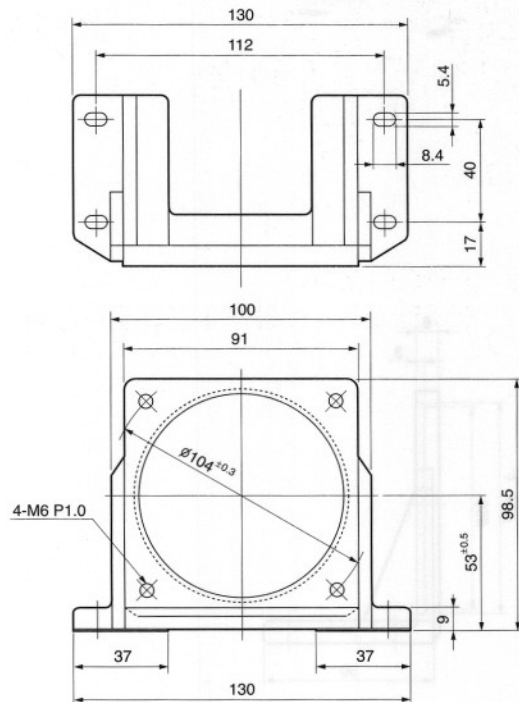
60mm용



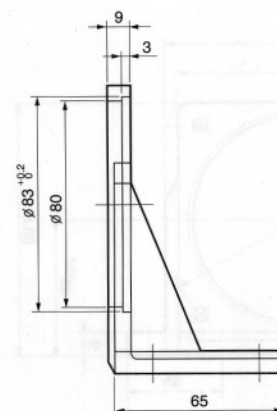
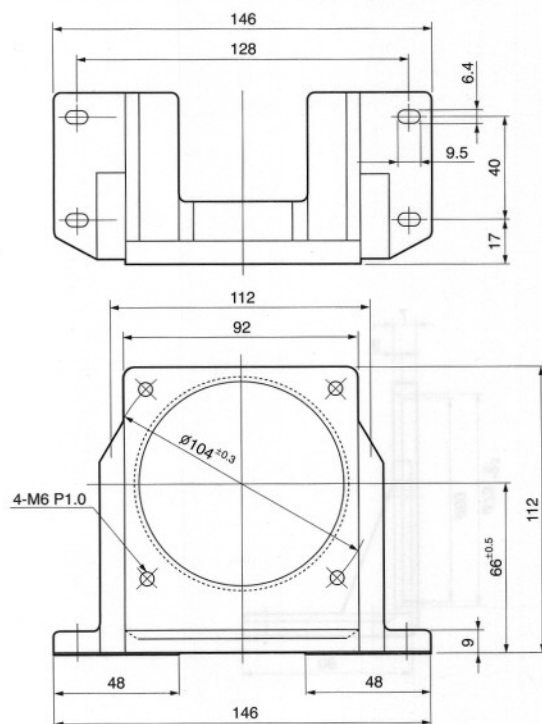
80mm용



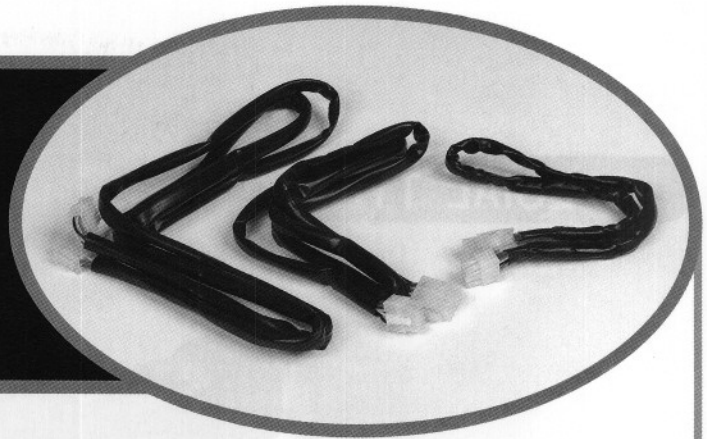
90mm용 "N", "H" TYPE



90mm용 "K" TYPE

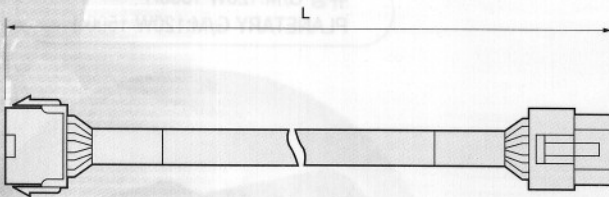


연장선



- ▶ SPEED CONTROL MOTOR UNIT CONTROLLER간에 사용되는 연장선입니다.
- ▶ UNIT CONTROLLER는 0.5m연장선은 기본이며 연장사용시 3m이하로 사용하며 아래와 같이 별매품 입니다.

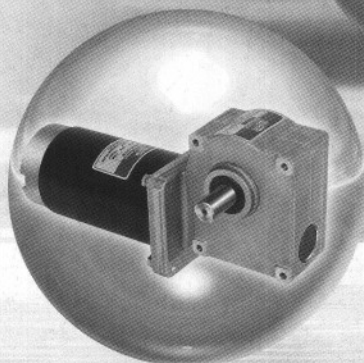
DIMENSION



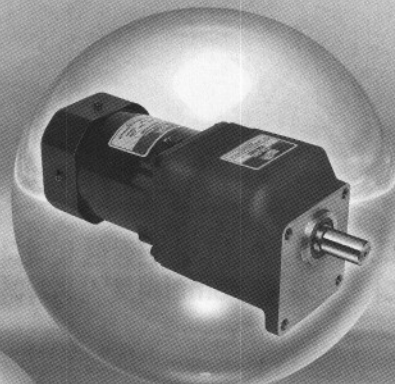
● MODEL

MODEL	L (연장선 길이)
10SE-0005	0.5m
10SE-0010	1.0m
10SE-0015	1.5m
10SE-0020	2m
10SE-0030	3m

SPECIAL TYPE



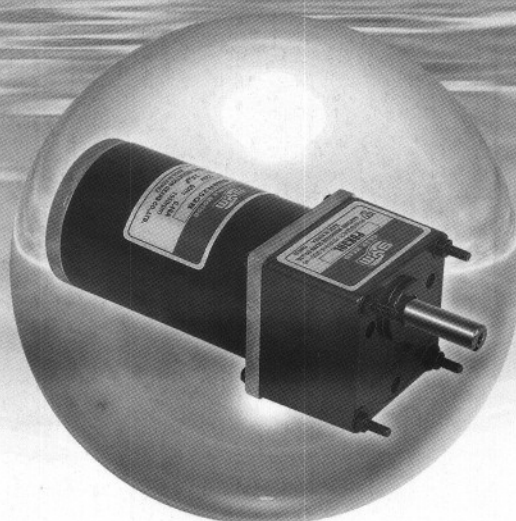
WORM GEARED MOTOR



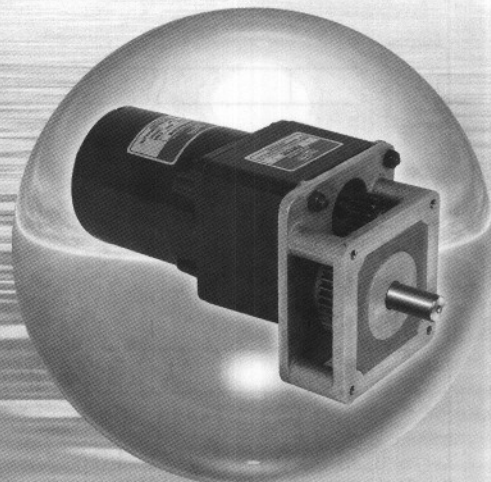
유성 G/M:60W 1500:1
PLANETARY G/M:60W 1500:1



유성 G/M:120W 1500:1
PLANETARY G/M:120W 1500:1



DC G/M



특수형케이스부착형
Special case extension type

